## Homogeneous Linear Systems of ODEs in Maple

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This worksheet illustrates how to analyze homogeneous linear systems of ODEs in Maple.
First, load in the "plots" and "LinearAlgebra" package
$>$ with(plots):
with(LinearAlgebra) :
Example System: Consider the homogeneous linear system of ODEs
$>d e 1:=x l^{\prime}(t)=x 1(t)+3 \cdot x 2(t)$;
$d e 2:=x 2^{\prime}(t)=3 \cdot x 1(t)+x 2(t)$
for functions $\mathrm{x} 1(\mathrm{t})$ and $\mathrm{x} 2(\mathrm{t})$, with initial data $\mathrm{x} 1(0)=2$, $\mathrm{x} 2(0)=6$.
SSolution via dsolve: The solution can be obtained with Maple's dsolve command:
$[>$ sol $:=\operatorname{dsolve}(\{d e 1, \operatorname{de2}, x 1(0)=2, x 2(0)=6\},\{x 1(t), x 2(t)\})$
Solution via Eigen-analysis: The system above is of the form $\mathbf{x}^{\prime}=\mathbf{A x}$ where $\mathbf{x}=<\mathrm{x} 1, \mathrm{x} 2>$ and [> $A:=\operatorname{Matrix}([[1,3],[3,1]])$
We solve using the eigenvector/value analysis of Section 6.2.2. The eigenvalues and vectors of A can be computed as
>> eigs $:=$ Eigenvectors $(A)$
The first part of "eigs" (the column vector $<4,-2>$ ) has as its components the eigenvalues of A , that is, the eigenvalues are
[> eigs[1][1], eigs[1][2]
The second part of "eigs" (the $2 \times 2$ matrix) has as its columns the corresponding eigenvectors of A .
Define a matrix $\mathbf{P}$
[> $P:=e i g s[2]$
Las was done in equation (6.18) in the text. Let
$[ \rangle x 0:=\langle 2,6\rangle$
denote the initial condition vector. As per the procedure in Section 6.2.2, we can construct the solution
to this ODE system by first solving $\mathbf{P c}=\mathbf{x} \mathbf{0}$ for $\mathbf{c}$, which in Maple takes the form
$>c:=\operatorname{LinearSolve}(P, x 0)$
[From (6.17) in the text the solution is then
$[>$ xsol $:=c[1] \cdot \exp (e i g s[1][1] \cdot t) \cdot \operatorname{Column}(P, 1)+c[2] \cdot \exp (e i g s[1][2] \cdot t) \cdot \operatorname{Column}(P, 2)$
The command "Column $(\mathrm{P}, \mathrm{j})$ " picks off the j th column of a matrix " P ".
The components $\mathrm{x} 1(\mathrm{t})$ and $\mathrm{x} 2(\mathrm{t})$ are given by
[> xsol[1]; $x \operatorname{sol}[2] ;$
Example 2: Consider the system
$>d e l:=x l^{\prime}(t)=-5 \cdot x 1(t)+6 \cdot x 2(t)$;
$d e 2:=x 2^{\prime}(t)=-3 \cdot x 1(t)+x 2(t) ;$
[with initial data $\mathrm{x} 1(0)=1, \mathrm{x} 2(0)=2$. This system is governed by the matrix
$A:=\operatorname{Matrix}([[-5,6],[-3,1]])$
[Compute the eigenvalues/vectors as
>> eigs $:=$ Eigenvectors $(A)$
Following the analysis in the previous example, pick off the eigenvectors and install them in a matrix
$\lfloor\mathbf{P}$ as
$\lceil>P:=e i g s[2]$
In the general solution (6.17) in the text, the desired initial conditions are obtained by taking the $\mathrm{c}[\mathrm{k}]$ as the components of the vector $\mathbf{c}$ that satisfies $\mathbf{P c}=\mathbf{x} \mathbf{0}$ where $\mathbf{x} \mathbf{0}=<1,2>$ (equation (6.18)). Compute
$[>c:=\operatorname{LinearSolve}(P,\langle 1,2\rangle)$
The solution (from (6.17)) is then
$[>x s o l:=c[1] \cdot \exp ($ eigs $[1][1] \cdot t) \cdot \operatorname{Column}(P, 1)+c[2] \cdot \exp (e i g s[1][2] \cdot t) \cdot \operatorname{Column}(P, 2)$
However, a real-valued version is obtained with
$\stackrel{\square}{>}$ evalc $(x s o l)$

