ROSE-HULMAN INSTITUTE OF TECHNOLOGY

Mechanical Systems

Review of Conservation of Energy

(by P. Cornwell)

From ES201 conservation of energy can be written as:

$$\frac{dE_{sys}}{dt} = \dot{Q} + \dot{W} + \sum_{in} \dot{m}_i \left(h + \frac{v^2}{2} + gz \right)_i - \sum_{out} \dot{m}_o \left(h + \frac{v^2}{2} + gz \right)_{in}$$

In contrast to conservation of linear and angular moment, which are vector equations, conservation of energy is a scalar equation. In this class we'll usually be using the finite time form for a closed system as shown below.

$$\Delta E_{sys} = W$$

where the energy of the system is

$$E_{sys} = E_K + E_G + E_S + U$$

where

Comments

$$E_K = \frac{1}{2}mv_G^2 + \frac{1}{2}I_G\mathbf{w}^2$$
 (you will always need to use kinematics to relate v_G and ω .)

$$E_G = mgz$$
 (z is the distance the center of mass is from the datum)

$$E_S = \frac{1}{2}kx^2$$
 (x is measured from the free length of the spring)

$$U = \text{internal energy}$$
 (this is usually zero in this class unless there is an impact)

and work is defined to be

$$W = \int_{1}^{2} \vec{F} d\vec{r} \qquad \text{or} \qquad W = \int_{1}^{2} M d\theta$$

Special Cases:

constant force:
$$W = \int_{1}^{2} \vec{F} d\vec{r} = \int_{1}^{2} F ds = F \int_{0}^{s} ds \implies W = Fs$$

constant moment:
$$W = \int_{1}^{2} M d\theta = M \int_{0}^{\theta} d\theta \implies W = M\theta$$

rolling friction (on a fixed surface):
$$W = \int_{1}^{2} \vec{F} \cdot d\vec{r} = \int_{1}^{2} F ds_{c} \left(\frac{dt}{dt}\right) = \int_{1}^{2} F v_{c} dt = 0 \implies W = 0$$
velocity of the point of contact

Conservation of Energy