Unless specified otherwise, r,s,t,u,v,w,x,y,z are strings over alphabet  $\Sigma$ ; while a, b, c, d are individual alphabet symbols.

## **DFSM notation:** $M = (K, \Sigma, \delta, s, A)$ , where:

K is a finite set of *states*,  $\Sigma$  is a finite *alphabet* 

 $s \in K$  is start state,  $A \subseteq K$  is set of *accepting states* 

 $\delta: (K \times \Sigma) \to K$  is the *transition function* 

Extend  $\delta$ 's definition to  $\delta$ :  $(K \times \Sigma^*) \to K$  by the recursive definition  $\delta(q, \varepsilon) = q$ ,  $\delta(q, xa) = \delta(\delta(q, x), a)$ 

M accepts w iff  $\delta(s, w) \in A$ .  $L(M) = \{w \in \Sigma^* : \delta(s, w) \in A\}$ 

## Alternate notation:

(q, w) is a *configuration* of M. (current state, remaining input)

The *yields-in-one-step* relation:  $|-_M$ :

 $(q, w) \mid_{-M} (q', w')$  iff w = a w' for some symbol  $a \in \Sigma$ , and  $\delta(q, a) = q'$ 

The yields-in-zero-or-more-steps relation:  $|-_M^*|$  is the reflexive, transitive closure of  $|-_M$ .

A *computation* by M is a finite sequence of configurations  $C_0, C_1, \ldots, C_n$  for some  $n \ge 0$  such that:

- $C_0$  is an initial configuration,
- $C_n$  is of the form  $(q, \varepsilon)$ , for some state  $q \in K_M$ ,
- $\forall i \in \{0, 1, ..., n-1\} (C_i \mid -_M C_{i+1})$

M accepts wiff the state that is part of the last step in w is in A.

A language L is **regular** if L=L(M) for some DFSM M.

In an **NDFSM**, the function  $\delta$  is replaced by the relation  $\Delta : \Delta \subseteq (K \times (\Sigma \cup \{\varepsilon\})) \times K$ 

```
ndfsmtodfsm(M: NDFSM) =
 1. For each state q in K_M do:
         1.1 Compute eps(q).
 2. s' = eps(s)

Compute δ':

         3.1 active-states = {s'}.
         3.2 δ' = Ø.
         3.3 While there exists some element Q of active-states for
             which \delta' has not yet been computed do:
                    For each character c in \Sigma_M do:
                          new-state = \emptyset.
                          For each state q in Q do:
                              For each state p such that (q, c, p) \in \Delta do:
                                   new-state = new-state \cup eps(p).
                          Add the transition (q, c, new-state) to \delta'.
                          If new-state ∉ active-states then insert it.
 4. K' = active-states.
 5. A' = \{Q \in \mathcal{K} : Q \cap A \neq \emptyset\}.
```

Some functions over languages: maxstring(L) = $\{w \in L: \forall z \in \Sigma^* (z \neq \varepsilon \rightarrow wz \notin L)\}.$ chop(L) = $\{w: \exists x \in L \ (x = x_1 c x_2, x_1 \in \Sigma_L^*, x_2 \in \Sigma_L^*, c \in \Sigma_L\}$  $|x_1| = |x_2|$ , and  $w = x_1x_2$ . firstchars(L) =  $\{w: \exists y \in L \ (y = cx \land c \in \Sigma_L \land x \in \Sigma_L^* \land w \in \{c\}^*)\}.$ 

Equivalent strings relative to a language: Given a language L, two strings w and x in  $\Sigma_{L}^{*}$  are *indistinguishable* with respect to L, written  $w \approx_L x$ , iff  $\forall z \in \Sigma^*$  ( $xz \in L$  iff  $yz \in L$ ). [x] is a notation for "the equivalence class that contains the string x".

## The construction of a minimal-state DSFM based on $\approx_L$ :

 $M = (K, \Sigma, \delta, s, A)$ , where K contains n states, one for each equivalence class of  $\approx_L$ .

 $s = [\varepsilon]$ , the equivalence class containing  $\varepsilon$  under  $\approx_L$ ,

 $A = \{ [x] : x \in L \},\$ 

 $\delta([x], a) = [xa].$ 

**Enumerator** (generator) for a language: When it is asked, enumerator gives us the next element of the language. Any given element of the language will appear within a finite amount of time. It is allowed that some may appear multiple times.

**Recognizer:** Given a string s, recognizer halts and accepts s if s is in the language. If not, recognizer either halts and rejects s or keeps running forever. This is a semidecision procedure. If recognizer is guaranteed to always halt and (accept or reject) no matter what string it is given as input, it is a **decision procedure**.