



Recap: Optimal Binary Search Trees

- Suppose we have n distinct data keys K₁, K₂, ..., K_n (in increasing order) that we wish to arrange into a Binary Search Tree
- This time the expected number of probes for a successful or unsuccessful search depends on the shape of the tree and where the search ends up
- Guiding principle for optimization?
- This discussion follows Reingold and Hansen, Data Structures. An excerpt on optimal static BSTS is posted on Moodle. I use a_i and b_i where Reingold and Hansen use α_i and β_i

What contributes to the expected number of probes?

- Frequencies, depth of node
- For successful search, number of probes is
 one more than
 the depth of the
 corresponding internal node
- For unsuccessful, number of probes is
 equal to
 the depth of the corresponding



Optimal BST Notation

- Keys are K₁, K₂, ..., K_n, in internal nodes x₁, x₂, ..., x_n
- Let v be the value we are searching for
- For i= 1, ..., n, let a, be the probability that v is key K,
- For i= 1, ..., n-1, let b_i be the probability that $K_i < v < K_{i+1}$
 - Similarly, let b_0 be the probability that $v < K_1$, and b_n the probability that $v > K_n$
 - Each b_i is associated with external node y_i
- Note that $\sum_{i=1}^{n} a_i + \sum_{i=0}^{n} b_i = 1$
- We can also just use frequencies instead of probabilities when finding the optimal tree (and divide by their sum to get the probabilities if we ever need them). That is what we will do in an example.
- Should we try exhaustive search of all possible BSTs

What not to measure

- What about external path length and internal path length?
- These are too simple, because they do not take into account the frequencies.
- We need weighted path lengths.



Weighted Path Length

$$C(T) = \sum_{i=1}^{n} a_i [1 + depth(x_i)] + \sum_{i=0}^{n} b_i [depth(y_i)]$$
Note: y_0, ..., y_n are the external nodes of the tree

- If we divide this by $\Sigma a_i + \Sigma b_i$, we get the expected number of probes.
- We can also define C recursively:

• C(□) = 0. If T = , then

 $C(T) = C(T_L) + C(T_R) + \Sigma a_i + \Sigma b_i$, where the summations are over all a_i and b_i for nodes in T

 It can be shown by induction that these two definitions are equivalent (a homework problem).

Example

- Frequencies of vowel occurrence in English
- : A, E, I, O, U
- a's: 32, 42, 26, 32,
- b's: 0, 34, 38, 58, 95, 21
- Draw a tree (with E as root), and see which is best. (sum of a's and b's is 390).



Strategy

- We want to minimize the weighted path length
- Once we have chosen the root, the left and right subtrees must themselves be optimal **EBSTs**
- We can build the tree from the bottom up, keeping track of previously-computed values



Intermediate Quantities

- Cost: Let C_{ij} (for $0 \le i \le j \le n$) be the cost of an optimal tree (not necessarily unique) over the frequencies b_i , a_{i+1} , b_{i+1} , ... a_j , b_j . Then
- $C_{ii} = 0$, and $C_{ij} = \min_{i < k \le j} (C_{i,k-1} + C_{kj}) + \sum_{t=i}^{J} b_t + \sum_{t=i+1}^{J} a_t$
- This is true since the subtrees of an optimal tree must be optimal
- To simplify the computation, we define
- W_{ii} = b_i, and W_{ij} = W_{i,j-1} + a_j + b_j for i<j.
 Note that W_{ij} = b_i + a_{i+1} + ... + a_j + b_j, and so
- $C_{ii} = 0$, and $C_{ij} = W_{ij} + \min_{i \neq k \leq i} (C_{i,k-1} + C_{kj})$
- Let R_{ij} (root of best tree from i to j) be a value of k that minimizes $C_{i,k-1} + C_{ki}$ in the above formula

```
Code
# initialize the main diagonal
for i in range (n + 1):
     R[i][i] = i
     W[i][i] = b[i]
     # Draw this cell of the table in the given window.
     \label{eq:continuous} drawSquare(i, i, W[i][i], C[i][i], R[i][i], win, indent, squareSize)
# Now populate each of the n upper diagonals:
for d in range(1, n+1): # fill in this diagonal
     # The previous diagonals are already filled in.
     for i in range (n - d + 1):
          j = i + d; # on the dth diagonal, j - i = d
opt = i + 1 # until we find a better one
for k in range(i+2, j+1):
                if C[i][k-1]+C[k][j] < C[i][opt-1]+C[opt][j]:
                    opt = k
          R[i][j] = opt
          W[i][j] = W[i][j-1] + a[j] + b[j]
          C[i][j] = C[i][opt-1] + C[opt][j] + W[i][j]
# Draw this cell of the table in the given window.
          drawSquare(i, j, W[i][j], C[i][j], R[i][j], win, indent, squareSize)
```

	Results												
R00: W00: C00:	0	R01: W01: C01:	1 66 66	R02: W02: C02:		R03: W03: C03:		R04: W04: C04:			05: 390	 Constructed by diagonals, 	
		R11: W11: C11:	1 34 0	R12: W12: C12:		R13: W13: C13:	3 198 312	R14: W14: C14:	3 325 624	R15: W15: C15:		from main diagonal	
				R22: W22: C22:	2 38 0	R23: W23: C23:			4 249 371			upward	
	How to construct the optimal tree? Analysis of the algorithm?						58	R34: W34: C34:	4 185 185	R35: W35: C35:		What is the optimal	
ор								R44: W44: C44:	4 95 0		tree? 45: 128 45: 128		
										R55: W55: C55:	5 21 0		

Running time

- Most frequent statement is the comparison if C[i][k-1]+C[k][j] < C[i][opt-1]+C[opt][j]:
- How many times does it execute: $\sum_{d=1}^{n} \sum_{i=0}^{n-d} \sum_{k=i+2}^{i+d} 1$

```
 \begin{aligned} \text{simplify(sum(sum(1,k=i+2..i+d),i=0..n-d),d=1..n));} \\ & -\frac{1}{6}n + \frac{1}{6}n^3 \end{aligned}
```

