

# MA/CSSE 473 Day 29

- Student Questions?
- Expected Lookup time in a Binary Search Tree
- Optimal static Binary Search Tree

## Recap: Optimal linked list order

- Suppose we have n distinct data items x<sub>1</sub>, x<sub>2</sub>, ..., x<sub>n</sub> in a linked list.
- Also suppose that we know the probabilities p<sub>1</sub>, p<sub>2</sub>, ..., p<sub>n</sub> that each of the items is the one we'll be searching for.
- What is the expected number of probes before a successful search completes?
  - $-\sum_{i=1}^{n} i p_i$
- How can we minimize this number?
  - Place the elements in the list in decreasing order of probability.
- What about an unsuccessful search?

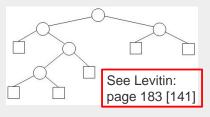


# **Optimal Binary Search Trees**

- Suppose we have n distinct data keys K<sub>1</sub>, K<sub>2</sub>, ...,
   K<sub>n</sub> (in increasing order) that we wish to arrange into a Binary Search Tree
- This time the expected number of probes for a successful or unsuccessful search depends on the shape of the tree and where the search ends up
- This discussion follows Reingold and Hansen, Data Structures. An excerpt on optimal static BSTS is posted on Moodle. I use  $a_i$  and  $b_i$  where Reingold and Hansen use  $\alpha_i$  and  $\beta_i$

## Recap: Extended binary search tree

 It's simplest to describe this problem in terms of an extended binary search tree (EBST): a BST enhanced by drawing "external nodes" in place of all of the null pointers in the original tree



- Formally, an Extended Binary Tree (EBT) is either
  - an external node, or
  - an (internal) root node and two EBTs T<sub>1</sub> and T<sub>R</sub>
- In diagram, Circles = internal nodes, Squares = external nodes
- It's an alternative way of viewing a binary tree
- The external nodes stand for places where an unsuccessful search can end or where an element can be inserted
- An EBT with n internal nodes has \_\_\_\_ external nodes (We proved this by induction earlier in the term)

# What contributes to the expected number of probes?

- Frequencies, depth of node
- For successful search, number of probes is
   one more than
   the depth of the
   corresponding internal node
- For unsuccessful, number of probes is
   equal to
   the depth of the corresponding



# **Optimal BST Notation**

- Keys are K<sub>1</sub>, K<sub>2</sub>, ..., K<sub>n</sub>
- Let v be the value we are searching for
- For i= 1, ...,n, let a, be the probability that v is key K,
- For i= 1, ..., n-1, let  $b_i$  be the probability that  $K_i < v < K_{i+1}$ 
  - Similarly, let  $b_0$  be the probability that  $v < K_1$ , and  $b_n$  the probability that  $v > K_n$
- Note that  $\sum_{i=1}^{n} a_i + \sum_{i=0}^{n} b_i = 1$
- We can also just use frequencies instead of probabilities when finding the optimal tree (and divide by their sum to get the probabilities if we ever need them). That is what we will do.
- Should we try exhaustive search of all possible BSTs? Answer on next slide

# Aside: How many possible BST's

- Given distinct keys K<sub>1</sub> < K<sub>2</sub> < ... < K<sub>n</sub>, how many different Binary Search Trees can be constructed from these values?
   When n=20,
- Figure it out for n=2, 3, 4, 5 **c(n) is**
- Write the recurrence relation almost 10<sup>10</sup>
- Solution is the **Catalan number** c(n)

$$c(n) = {2n \choose n} \frac{1}{n+1} = \frac{(2n)!}{n!(n+1)!} = \prod_{k=2}^{n} \frac{n+k}{k} \approx \frac{4^{n}}{n^{3/2} \sqrt{\pi}}$$

• Verify for n = 2, 3, 4, 5.

Wikipedia Catalan article has  $c(n) = \binom{2n}{n} \frac{1}{n+1}$ 



## Recap: Optimal Binary Search Trees

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- Let v be the value we are searching for
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but we can also just use frequencies when finding the optimal tree (and divide by their sum to get the probabilities if needed)



#### What not to measure

- Earlier, we introduced the notions of external path length and internal path length
- These are too simple, because they do not take into account the frequencies.
- We need weighted path lengths.



# Weighted Path Length

$$C(T) = \sum_{i=1}^{n} a_{i} [1 + depth(x_{i})] + \sum_{i=0}^{n} b_{i} [depth(y_{i})]$$

- If we divide this by  $\Sigma a_i + \Sigma b_i$  we get the average search time.
- We can also define it recursively:

**Note**:  $y_0, ..., y_n$  are the external nodes of the tree

•  $C(\Box) = 0$ . If T =



 $C(T) = C(T_L) + C(T_R) + \Sigma a_i + \Sigma b_i$ , where the summations are over all  $a_i$  and  $b_i$  for nodes in T

 It can be shown by induction that these two definitions are equivalent (good practice problem).

# Example

- Frequencies of vowel occurrence in English
- : A, E, I, O, U
- a's: 32, 42, 26, 32, 12
- b's: 0, 34, 38, 58, 95, 21
- Draw a couple of trees (with E and I as roots), and see which is best. (sum of a's and b's is 390).

#### Strategy

- We want to minimize the weighted path length
- · Once we have chosen the root, the left and right subtrees must themselves be optimal **EBSTs**
- We can build the tree from the bottom up, keeping track of previously-computed values



#### Intermediate Quantities

- Cost: Let  $C_{ij}$  (for  $0 \le i \le j \le n$ ) be the cost of an optimal tree (not necessarily unique) over the frequencies  $\dot{b}_i$ ,  $a_{i+1}$ ,  $b_{i+1}$ , ... $a_j$ ,  $b_j$ . Then
- $C_{ii} = 0$ , and  $C_{ij} = \min_{i < k \le j} (C_{i,k-1} + C_{kj}) + \sum_{t=i}^{j} b_t + \sum_{t=i+1}^{j} a_t$
- This is true since the subtrees of an optimal tree must be optimal
- To simplify the computation, we define
- $W_{ii} = b_i$ , and  $W_{ij} = W_{i,j-1} + a_j + b_j$  for i<j. Note that  $W_{ij} = b_i + a_{i+1} + ... + a_j + b_j$ , and so  $C_{ii} = 0$ , and  $C_{ij} = W_{ij} + \min_{i < k \le j} (C_{i,k-1} + C_{kj})$
- Let R<sub>ii</sub> (root of best tree from i to j) be a value of k that minimizes
  - $C_{i,k-1} + C_{ki}$  in the above formula

```
Code
# initialize the main diagonal
for i in range(n + 1):
    R[i][i] = i
    W[i][i] = b[i]
    # Draw this cell of the table in the given window.
    \label{eq:continuous} drawSquare(i, i, W[i][i], C[i][i], R[i][i], win, indent, squareSize)
# Now populate each of the n upper diagonals:
for d in range(1, n+1): # fill in this diagonal
    # The previous diagonals are already filled in.
    for i in range (n - d + 1):
        j = i + d; # on the dth diagonal, j - i = d
        opt = i + 1 # until we find a better one for k in range(i+2, j+1):
             if C[i][k-1]+C[k][j] < C[i][opt-1]+C[opt][j]:
                 opt = k
        R[i][j] = opt
        W[i][j] = W[i][j-1] + a[j] + b[j]
        C[i][j] = C[i][opt-1] + C[opt][j] + W[i][j]
         # Draw this cell of the table in the given window.
        \label{eq:continuous} drawSquare(i, j, W[i][j], C[i][j], R[i][j], win, indent, squareSize)
```

	Results										
woo: 0 wc	)1: 1 )1: 66 )1: 66	R02: W02: C02:		R03: W03: C03:		R04: W04: C04:		R05: W05: C05:		<ul> <li>Constructed by diagonals,</li> </ul>	
w1	L1: 1 L1: 34 L1: 0	R12: W12: C12:		R13: W13: C13:		R14: W14: C14:		R15: W15: C15:		from main diagonal	
		R22: W22: C22:	2 38 0	R23: W23: C23:			4 249 371			upward	
How to					3 58 0	R34: W34: C34:		R35: W35: C35:		What is the optimal	
optimal tree?					R44: W44: C44:	4 95 0	R45: W45: C45:		tree?		
Analysis of the algorithm?								R55: W55: C55:	5 21 0		

# Running time

- Most frequent statement is the comparison if C[i][k-1]+C[k][j] < C[i][opt-1]+C[opt][j]:</li>
- How many times does it execute:  $\sum_{d=1}^{n} \sum_{i=0}^{n-d} \sum_{k=i+2}^{i+d} 1$

```
 \begin{aligned} \text{simplify(sum(sum(1,k=i+2..i+d),i=0..n-d),d=1..n));} \\ & -\frac{1}{6}n + \frac{1}{6}n^3 \end{aligned}
```



Do what seems best at the moment ...

GREEDY ALGORITHMS

## **Greedy algorithms**

- Whenever a choice is to be made, pick the one that seems optimal for the moment, without taking future choices into consideration
  - Once each choice is made, it is irrevocable
- For example, a greedy Scrabble player will simply maximize her score for each turn, never saving any "good" letters for possible better plays later
  - Doesn't necessarily optimize score for entire game
- Greedy works well for the "optimal linked list with known search probabilities" problem, and reasonably well for the "optimal BST" problem
  - But does not necessarily produce an optimal tree

# **Greedy Chess**

- Take a piece or pawn whenever you will not lose a piece or pawn (or will lose one of lesser value) on the next turn
- Not a good strategy for this game either



## **Greedy Map Coloring**

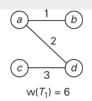
- On a planar (i.e., 2D Euclidean) connected map, choose a region and pick a color for that region
- Repeat until all regions are colored:
  - Choose an uncolored region R that is adjacent<sup>1</sup> to at least one colored region
    - If there are no such regions, let R be any uncolored region
  - Choose a color that is different than the colors of the regions that are adjacent to R
  - Use a color that has already been used if possible
- The result is a valid map coloring, not necessarily with the minimum possible number of colors

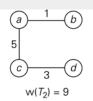
<sup>1</sup> Two regions are adjacent if they have a common edge

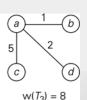


# Spanning Trees for a Graph







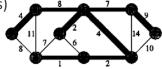


**FIGURE 9.1** Graph and its spanning trees;  $T_1$  is the minimum spanning tree



#### Minimal Spanning Tree (MST)

- Suppose that we have a connected network G
   (a graph whose edges are labeled by numbers, which we call weights)
- We want to find a tree T that
  - spans the graph (i.e. contains all nodes of G).
  - minimizes (among all spanning trees) the sum of the weights of its edges.
- Is this MST unique?



- One approach: Generate all spanning trees and determine which is minimum
- Problems:
  - The number of trees grows exponentially with N
  - Not easy to generate
  - Finding a MST directly is simpler and faster

More details soon



## Huffman's algorithm

- Goal: We have a message that co9ntains n different alphabet symbols. Devise an encoding for the symbols that minimizes the total length of the message.
- Principles: More frequent characters have shorter codes. No code can be a prefix of another.
- Algorithm: Build a tree form which the codes are derived. Repeatedly join the two lowestfrequency trees into a new tree.

