

## Higher Order Bases

The accuracy of a finite element solution can be improved by either increasing the mesh ( $h$ -refinement) or by increasing the degree of the basis function ( $p$ -refinement). While this course will focus primarily on  $h$ -refinement, considerable insight can be gained by briefly investigating  $p$ -refinement.

For our study problem of one-dimensional, steady-state heat conduction with variable conductivity and source, the recipe lead to

$$GWS^h = S_e GWS_e^h = S_e \left( \int_{\Omega_e} \frac{d\{N_k\}}{dx} k(x) \frac{d\{N_k\}^T}{dx} d\bar{x} \{Q\}_e - \int_{\Omega_e} \{N_k\} s(x) d\bar{x} - k(x) \frac{dT^N}{dx} \begin{Bmatrix} \mathbf{d}_{e1} \\ \mathbf{d}_{eM} \end{Bmatrix} = \{0\}_e \right) \quad (1a)$$

which was expressed compactly as

$$GWS^h = S_e GWS_e^h = S_e ([\text{DIFF}]_e \{Q\}_e = \{\text{SRC}\}_e + \{\text{BFLX}\}_e) \quad (1b)$$

We must now evaluate the matrix integrals leading to  $[\text{DIFF}]_e$  and  $\{\text{SRC}\}_e$ . Let us handle the conductivity as an element averaged term and the source as an element interpolated term. Hence

$$\begin{aligned} [\text{DIFF}]_e \{Q\}_e &= \int_{\Omega_e} \frac{d\{N_k\}}{dx} k(x) \frac{d\{N_k\}^T}{dx} d\bar{x} \{Q\}_e \\ &\approx \bar{k}_e \int_{\Omega_e} \frac{d\{N_k\}}{dx} \frac{d\{N_k\}^T}{dx} d\bar{x} \{Q\}_e \\ &= ( ) (\bar{k})_e \{ \}_e^T (-1) [\text{A211k}] \{Q\}_e \end{aligned} \quad (2a)$$

$$\begin{aligned} \{\text{SRC}\}_e &= \int_{\Omega_e} \{N_k\} s(x) d\bar{x} \\ &\approx \int_{\Omega_e} \{N_k\} \{N_k\}^T d\bar{x} \{S\}_e \\ &= ( ) ( )_e \{ \}_e^T (1) [\text{A200k}] \{S\}_e \end{aligned} \quad (2b)$$

Our earlier discussion on interpolation theory revealed the linear, quadratic, and cubic basis functions to take the form of

$$\textbf{Linear:} \quad \{N_1(\mathbf{z}_i)\} = \begin{Bmatrix} \mathbf{z}_1 \\ \mathbf{z}_2 \end{Bmatrix} \quad (3a)$$

$$\textbf{Quadratic:} \quad \{N_2(\mathbf{z}_i)\} \equiv \begin{Bmatrix} \mathbf{z}_1(2\mathbf{z}_1 - 1) \\ 4\mathbf{z}_1\mathbf{z}_2 \\ \mathbf{z}_2(2\mathbf{z}_2 - 1) \end{Bmatrix} \quad (3b)$$

**Cubic:**

$$\{N_3(\mathbf{z}_i)\} \equiv \frac{9}{2} \begin{Bmatrix} \mathbf{z}_1 \left( \mathbf{z}_2^2 - \mathbf{z}_2 + \frac{2}{9} \right) \\ \mathbf{z}_1 \mathbf{z}_2 (2 - 3\mathbf{z}_2) \\ \mathbf{z}_1 \mathbf{z}_2 (3\mathbf{z}_2 - 1) \\ \mathbf{z}_2 \left( \mathbf{z}_2^2 - \mathbf{z}_2 + \frac{2}{9} \right) \end{Bmatrix} \quad (3c)$$

where

$$\mathbf{z}_1(\bar{x}) \equiv 1 - \frac{\bar{x}}{l_e} \quad \mathbf{z}_2(\bar{x}) \equiv \frac{\bar{x}}{l_e} \quad \bar{x} = x - X_L \quad (3d)$$

Let us begin with the linear basis function. Carefully applying the chain rule

$$\frac{d\{N_1(\mathbf{z}_i)\}}{dx} = \frac{d\{N_1(\mathbf{z}_i)\}}{d\mathbf{z}_i} \frac{d\mathbf{z}_i}{d\bar{x}} \frac{d\bar{x}}{dx} \quad \text{for } 1 \leq i \leq 2 \quad (4)$$

to the first entry

$$\begin{aligned} \frac{d\{N_1(1,1)\}}{dx} &= \frac{d\mathbf{z}_1}{d\mathbf{z}_1} \frac{d\mathbf{z}_1}{d\bar{x}} \frac{d\bar{x}}{dx} + \frac{d\mathbf{z}_1}{d\mathbf{z}_2} \frac{d\mathbf{z}_2}{d\bar{x}} \frac{d\bar{x}}{dx} \\ &= 1 \left( -\frac{1}{l_e} \right) + 0 \\ &= -\frac{1}{l_e} \end{aligned} \quad (5a)$$

and to the second entry

$$\begin{aligned} \frac{d\{N_1(2,1)\}}{dx} &= \frac{d\mathbf{z}_2}{d\mathbf{z}_1} \frac{d\mathbf{z}_1}{d\bar{x}} \frac{d\bar{x}}{dx} + \frac{d\mathbf{z}_2}{d\mathbf{z}_2} \frac{d\mathbf{z}_2}{d\bar{x}} \frac{d\bar{x}}{dx} \\ &= 0 + 1 \left( \frac{1}{l_e} \right) \\ &= \frac{1}{l_e} \end{aligned} \quad (5b)$$

Thus

$$\boxed{\frac{d\{N_1(\mathbf{z}_i)\}}{dx} = \frac{1}{l_e} \begin{Bmatrix} -1 \\ 1 \end{Bmatrix}} \quad (6)$$

Differentiating the quadratic basis function

$$\frac{d\{N_2(\mathbf{z}_i)\}}{dx} = \frac{d\{N_2(\mathbf{z}_i)\}}{d\mathbf{z}_i} \frac{d\mathbf{z}_i}{d\bar{x}} \frac{d\bar{x}}{dx} \quad \text{for } 1 \leq i \leq 2 \quad (7)$$

First entry

$$\begin{aligned} \frac{d\{N_2(1,1)\}}{dx} &= \frac{d}{d\mathbf{z}_1} (\mathbf{z}_1 (2\mathbf{z}_1 - 1)) \frac{d\mathbf{z}_1}{d\bar{x}} \frac{d\bar{x}}{dx} + \frac{d}{d\mathbf{z}_2} (\mathbf{z}_1 (2\mathbf{z}_1 - 1)) \frac{d\mathbf{z}_2}{d\bar{x}} \frac{d\bar{x}}{dx} \\ &= ((2\mathbf{z}_1 - 1) + 2\mathbf{z}_1) \left( -\frac{1}{l_e} \right) + 0 \\ &= \frac{1}{l_e} (\mathbf{z}_2 - 3\mathbf{z}_1) \end{aligned} \quad (8a)$$

Second entry

$$\begin{aligned} \frac{d\{N_2(2,1)\}}{dx} &= \frac{d}{d\mathbf{z}_1} (4\mathbf{z}_1 \mathbf{z}_2) \frac{d\mathbf{z}_1}{d\bar{x}} \frac{d\bar{x}}{dx} + \frac{d}{d\mathbf{z}_2} (4\mathbf{z}_1 \mathbf{z}_2) \frac{d\mathbf{z}_2}{d\bar{x}} \frac{d\bar{x}}{dx} \\ &= (4\mathbf{z}_2) \left( -\frac{1}{l_e} \right) + (4\mathbf{z}_1) \left( \frac{1}{l_e} \right) \\ &= \frac{1}{l_e} 4(\mathbf{z}_1 - \mathbf{z}_2) \end{aligned} \quad (8b)$$

Third entry

$$\begin{aligned} \frac{d\{N_2(3,1)\}}{dx} &= \frac{d}{d\mathbf{z}_1} (\mathbf{z}_2 (2\mathbf{z}_2 - 1)) \frac{d\mathbf{z}_1}{d\bar{x}} \frac{d\bar{x}}{dx} + \frac{d}{d\mathbf{z}_2} (\mathbf{z}_2 (2\mathbf{z}_2 - 1)) \frac{d\mathbf{z}_2}{d\bar{x}} \frac{d\bar{x}}{dx} \\ &= 0 + ((2\mathbf{z}_2 - 1) + 2\mathbf{z}_2) \left( \frac{1}{l_e} \right) + 0 \\ &= \frac{1}{l_e} (3\mathbf{z}_2 - \mathbf{z}_1) \end{aligned} \quad (9)$$

Thus

$$\boxed{\frac{d\{N_2(\mathbf{z}_i)\}}{dx} = \frac{1}{l_e} \begin{bmatrix} \mathbf{z}_2 - 3\mathbf{z}_1 \\ 4(\mathbf{z}_1 - \mathbf{z}_2) \\ 3\mathbf{z}_2 - \mathbf{z}_1 \end{bmatrix}} \quad (10)$$

It is left as a homework exercise that

$$\frac{d\{N_3(\mathbf{z}_i)\}}{dx} = \frac{9}{2l_e} \begin{Bmatrix} -3\mathbf{z}_2^2 + 4\mathbf{z}_2 - 11/9 \\ 9\mathbf{z}_2^2 - 10\mathbf{z}_2 + 2 \\ -9\mathbf{z}_2^2 + 8\mathbf{z}_2 - 1 \\ 3\mathbf{z}_2^2 - 2\mathbf{z}_2 + 2/9 \end{Bmatrix} \quad (11)$$

Having evaluated the basis derivatives, let us proceed to the element integrals. Starting with the [A211k] master matrix within [DIFF]<sub>e</sub>

$$\int_{\Omega_e} \frac{d\{N_k\}}{dx} \frac{d\{N_k\}^T}{dx} d\bar{x}$$

we have, for the linear basis

$$\int_{\Omega_e} \frac{d\{N_1\}}{dx} \frac{d\{N_1\}^T}{dx} d\bar{x} = \int_{\Omega_e} \frac{1}{l_e} \begin{Bmatrix} -1 \\ 1 \end{Bmatrix} \frac{1}{l_e} \begin{Bmatrix} -1 & 1 \end{Bmatrix} d\bar{x} = \int_{\Omega_e} \frac{1}{l_e^2} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} d\bar{x} \quad (12)$$

It is of considerable convenience that the vector product is constant, yielding immediate evaluation

$$\int_{\Omega_e} \frac{d\{N_1\}}{dx} \frac{d\{N_1\}^T}{dx} d\bar{x} = \frac{1}{l_e} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} \quad (13)$$

The quadratic basis is a bit more difficult

$$\int_{\Omega_e} \frac{d\{N_2\}}{dx} \frac{d\{N_2\}^T}{dx} d\bar{x} = \int_{\Omega_e} \frac{1}{l_e^2} \begin{bmatrix} (\mathbf{z}_2 - 3\mathbf{z}_1)^2 & (\mathbf{z}_2 - 3\mathbf{z}_1)4(\mathbf{z}_1 - \mathbf{z}_2) & (\mathbf{z}_2 - 3\mathbf{z}_1)(3\mathbf{z}_2 - \mathbf{z}_1) \\ 4(\mathbf{z}_1 - \mathbf{z}_2)(\mathbf{z}_2 - 3\mathbf{z}_1) & 16(\mathbf{z}_1 - \mathbf{z}_2)^2 & 4(\mathbf{z}_1 - \mathbf{z}_2)(3\mathbf{z}_2 - \mathbf{z}_1) \\ (3\mathbf{z}_2 - \mathbf{z}_1)(\mathbf{z}_2 - 3\mathbf{z}_1) & (3\mathbf{z}_2 - \mathbf{z}_1)4(\mathbf{z}_1 - \mathbf{z}_2) & (3\mathbf{z}_2 - \mathbf{z}_1)^2 \end{bmatrix} d\bar{x} \quad (14)$$

The required integrals are readily evaluated by substituting the definitions of  $\mathbf{z}_1(\bar{x})$  and  $\mathbf{z}_2(\bar{x})$  into (13) and letting a symbolic package such as Maple do the gruntwork. However, Maple has not always existed and, as an historical note, the following analytical solution is presented. Integrals over  $\Omega_e$  of *all* polynomials in the  $\mathbf{z}_i$  can be evaluated as

$$\int_{\Omega_e} \mathbf{z}_1^p \mathbf{z}_2^q d\bar{x} = l_e \frac{p!q!}{(1+p+q)!} \quad (15)$$

Irrespective of method, (14) integrates out to

$$\int_{\Omega_e} \frac{d\{N_2\}}{dx} \frac{d\{N_2\}^T}{dx} d\bar{x} = \frac{1}{3l_e} \begin{bmatrix} 7 & -8 & 1 \\ -8 & 16 & -8 \\ 1 & -8 & 7 \end{bmatrix} \quad (16)$$

Completing the analysis with the cubic basis, it is left as a homework exercise to verify that

$$\int_{\Omega_e} \frac{d\{N_3\}}{dx} \frac{d\{N_3\}^T}{dx} d\bar{x} = \frac{1}{40l_e} \begin{bmatrix} 148 & -189 & 54 & -13 \\ & 432 & -297 & 54 \\ & & 432 & -189 \\ (\text{sym}) & & & 148 \end{bmatrix} \quad (17)$$

In conclusion, we have evaluated the matrix form of the [A211k] master matrix for linear, quadratic, and cubic basis functions. Heed that the metric for each basis remains -1.

Turning our attention to the master matrix [A200k] within {SRC}<sub>e</sub>

$$\int_{\Omega_e} \{N_k\} \{N_k\}^T d\bar{x}$$

we have, for the linear basis

$$\int_{\Omega_e} \{N_1\} \{N_1\}^T d\bar{x} = \int_{\Omega_e} \begin{Bmatrix} z_1 \\ z_2 \end{Bmatrix} \begin{Bmatrix} z_1 & z_2 \end{Bmatrix} d\bar{x} = \int_{\Omega_e} \begin{bmatrix} z_1^2 & z_1 z_2 \\ z_2 z_1 & z_2^2 \end{bmatrix} d\bar{x} \quad (18)$$

which is readily evaluated via Maple or (15) to give

$$\int_{\Omega_e} \{N_1\} \{N_1\}^T d\bar{x} = \frac{l_e}{6} \begin{bmatrix} 2 & 1 \\ 1 & 2 \end{bmatrix} \quad (19)$$

Likewise, the quadratic and cubic bases yield

$$\int_{\Omega_e} \{N_2\} \{N_2\}^T d\bar{x} = \frac{l_e}{30} \begin{bmatrix} 4 & 2 & -1 \\ 2 & 16 & 2 \\ -1 & 2 & 4 \end{bmatrix} \quad (20)$$

$$\int_{\Omega_e} \{N_3\} \{N_3\}^T d\bar{x} = \begin{bmatrix} & & & \\ & & & \\ & & & \\ & & & \end{bmatrix} \quad (21)$$

Heed that the metric for each basis remains 1.

### Homework:

1. Verify equation (11), the derivative of {N<sub>3</sub>}.
2. Verify equation (17), the element master matrix [A211C].
3. Figure out equation (21), the element master matrix [A200C].