

HOMEWORK ASSIGNED 3/14/02

PROBLEM 1

Verify that obtained nodal temperature solutions agree with

$$(9) \quad Q_1 = \frac{SL^2}{2k} + \frac{qL}{k} + T_b$$

$$Q_2 = \frac{3SL^2}{8k} + \frac{qL}{2k} + T_b$$

$$Q_3 = T_b$$

and that boundary heat fluxes agree with

$$(11) \quad -k \frac{dT^N}{dx} \Big|_{x=L} = SL + q_{in}$$

Reorder

$$(3b) \quad \frac{k}{4a} Q_2 - \frac{k}{4a} Q_3 = \frac{SL/2}{2}$$

$$-\frac{k}{4a} Q_2 + \frac{k}{4a} Q_3 = \frac{SL/2}{2} + k \frac{dT^N}{dx} \quad \checkmark$$

to move Q_3 to the right side, $k \frac{dT^N}{dx}$ to the left side, then continue through to obtain a global matrix statement similar to

$$\begin{bmatrix} 1 & -1 & 0 \\ -1 & 2 & -1 \\ 0 & -1 & 1 \end{bmatrix} \begin{bmatrix} Q_1 \\ Q_2 \\ Q_3 \end{bmatrix} = \frac{L}{2k} \begin{bmatrix} \frac{SL}{4} + q \\ 2SL/4 \\ \frac{SL}{4} + k \frac{dT^N}{dx} \end{bmatrix}$$

where the column of unknowns has $k \frac{dT^N}{dx}$ as the bottom entry.

STARTING WITH

$$(3b) \quad \frac{k}{4a} Q_2 = \frac{SL/2}{2} + \frac{k}{4a} Q_3$$

$$-\frac{k}{4a} Q_2 - \frac{k \frac{dT^N}{dx}}{4a} = \frac{SL/2}{2} - \frac{k}{4a} Q_3 \quad \checkmark$$

$$(3a) \quad \checkmark \quad \frac{k}{4a} Q_1 - \frac{k}{4a} Q_2 = \frac{SL/2}{2} + q_{in}$$

$$-\frac{k}{4a} Q_1 + \frac{k}{4a} Q_2 = \frac{SL/2}{2}$$

$$\checkmark \frac{2k}{L} Q_1 - \frac{2k}{L} Q_2 + 0 \frac{k dT^N}{dx} = \frac{SL}{4} + q$$

$$\checkmark -\frac{2k}{L} Q_1 + \frac{2k}{L} Q_2 + 0 \frac{k dT^N}{dx} = \frac{SL}{4} \quad \checkmark$$

$$\checkmark 0 Q_1 + 0 Q_2 + 0 \frac{k dT^N}{dx} = 0$$

$$\checkmark 0 Q_1 + 0 Q_2 + 0 \frac{k dT^N}{dx} = 0$$

$$\checkmark 0 Q_1 + \frac{2k}{L} Q_2 + 0 \frac{k dT^N}{dx} = \frac{SL}{4} + \frac{2k}{L} Q_3 \quad \checkmark$$

$$0 Q_1 - \frac{2k}{L} Q_2 - 1 \frac{k dT^N}{dx} = \frac{SL}{4} - \frac{2k}{L} Q_3$$

$$\frac{2k}{L} Q_1 - \frac{2k}{L} Q_2 + 0 \frac{k dT^N}{dx} = \frac{SL}{4} + q$$

$$-\frac{2k}{L} Q_1 + \frac{4k}{L} Q_2 + 0 \frac{k dT^N}{dx} = \frac{SL}{2} + \frac{2k}{L} Q_3$$

$$0 Q_1 - \frac{2k}{L} Q_2 - 1 \frac{k dT^N}{dx} = \frac{SL}{4} - \frac{2k}{L} Q_3$$

$$\frac{2k}{L} \begin{bmatrix} 1 & -1 & 0 \\ -1 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix} \left\{ \right\} = \frac{SL}{4} \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} + \begin{bmatrix} q_{in} \\ 0 \\ 0 \end{bmatrix} \quad \checkmark \quad \left\{ \right\} = \begin{bmatrix} Q_1 \\ Q_2 \\ \frac{k dT^N}{dx} \end{bmatrix}$$

$$\frac{2k}{L} \begin{bmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & -1 & -\frac{L}{2k} \end{bmatrix} \left\{ \right\} = \frac{SL}{4} \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} + \frac{2k}{L} \begin{bmatrix} 0 \\ Q_3 \\ -Q_3 \end{bmatrix}$$

$$\frac{2k}{L} \begin{bmatrix} 1 & -1 & 0 \\ -1 & 2 & 0 \\ 0 & -1 & -\frac{L}{2k} \end{bmatrix} \left\{ \right\} = \frac{SL^2}{kL} \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix} + \frac{2k}{L} \begin{bmatrix} \frac{L}{2k} q_{in} \\ Q_3 \\ -Q_3 \end{bmatrix}$$

$$\begin{bmatrix} 1 & -1 & 0 \\ -1 & 2 & 0 \\ 0 & -1 & -\frac{1}{2k} \end{bmatrix} \begin{bmatrix} Q_1 \\ Q_2 \\ \frac{k dT^v}{dx} \end{bmatrix} = \frac{SL^2}{8k} \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix} + \begin{bmatrix} \frac{L}{2k} q \\ T_b \\ -T_b \end{bmatrix}$$

Solve 3eqn for 3 unknowns
 $Q_1, Q_2, (k dT^v/dx)$

$$\checkmark Q_1 = \frac{1}{2k} [SL^2 + 2Lq + 2T_b k] = \left(\frac{SL^2}{2k} + \frac{Lq}{k} + T_b \right)$$

$$\checkmark Q_2 = \frac{1}{8k} [3SL^2 + 4Lq + 8T_b k] = \left(\frac{3SL^2}{8k} + \frac{Lq}{2k} + T_b \right)$$

$$\checkmark \frac{k dT^v}{dx} = -SL - q$$

VERIFIED ☺

Woo-hoo!

Assigned 3/14/02

PROBLEM 2

Starting with

$$GWS^A = \sum_{e=1}^M GWS_e^A = \sum_{e=1}^M \left(\frac{k}{L_e} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} \{Q_e\} - \frac{sL_e}{2} \begin{Bmatrix} 1 \\ 1 \end{Bmatrix} - k \frac{dT^N}{dx} \begin{Bmatrix} \delta_{e1} \\ \delta_{eM} \end{Bmatrix} = \begin{Bmatrix} 0 \\ 0 \end{Bmatrix} \right)$$

linear interpolation basis

repeat the assembly and solution process for a 3 element (4 node) uniform discretization of the domain (0, L). Include a plot of the exact solution and the $M=2$ and $M=3$ finite element results for problem data specified in the text, p 32, problem 1.

Be sure that nodes are connected by linear functions. Comment on solution accuracy and effort required.

APPLYING 3-elements:

$$GWS_1^A = \frac{k}{L/3} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} \begin{Bmatrix} Q_1 \\ Q_2 \end{Bmatrix} - \frac{sL/3}{2} \begin{Bmatrix} 1 \\ 1 \end{Bmatrix} - q \begin{Bmatrix} 1 \\ 0 \end{Bmatrix} = \begin{Bmatrix} 0 \\ 0 \end{Bmatrix}$$

$$GWS_2^A = \frac{k}{L/3} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} \begin{Bmatrix} Q_2 \\ Q_3 \end{Bmatrix} - \frac{sL/3}{2} \begin{Bmatrix} 1 \\ 1 \end{Bmatrix} - k \frac{dT^N}{dx} \begin{Bmatrix} 0 \\ 0 \end{Bmatrix} = \begin{Bmatrix} 0 \\ 0 \end{Bmatrix}$$

$$GWS_3^A = \frac{k}{L/3} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} \begin{Bmatrix} Q_3 \\ Q_4 \end{Bmatrix} - \frac{sL/3}{2} \begin{Bmatrix} 1 \\ 1 \end{Bmatrix} - k \frac{dT^N}{dx} \begin{Bmatrix} 0 \\ 1 \end{Bmatrix} = \begin{Bmatrix} 0 \\ 0 \end{Bmatrix}$$

LINEAR ALGEBRAIC:

$$e=1 \quad \frac{k}{L/3} (Q_1 - Q_2) = \frac{sL/3}{2} + q$$

$$\frac{k}{L/3} (-Q_1 + Q_2) = \frac{sL/3}{2}$$

$$e=2 \quad \frac{k}{L/3} (Q_2 - Q_3) = \frac{sL/3}{2}$$

$$\frac{k}{L/3} (-Q_2 + Q_3) = \frac{sL/3}{2}$$

$$e=3 \quad \frac{k}{L/3} (Q_3 - Q_4) = \frac{sL/3}{2}$$

$$\frac{k}{L/3} (-Q_3 + Q_4) = \frac{sL/3}{2} + k \frac{dT^N}{dx}$$



PADDING THE EQUATIONS:

$$e=1 \quad \frac{k}{L/3} \begin{pmatrix} Q_1 - Q_2 + 0Q_3 + 0Q_4 \\ (-Q_1 + Q_2 + 0Q_3 + 0Q_4) \\ (0Q_1 + 0Q_2 + 0Q_3 + 0Q_4) \\ (0Q_1 + 0Q_2 + 0Q_3 + 0Q_4) \end{pmatrix} \Rightarrow \frac{3k}{L} \begin{bmatrix} 1 & -1 & 0 & 0 \\ -1 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} Q_1 \\ Q_2 \\ Q_3 \\ Q_4 \end{bmatrix}$$

$$e=2 \quad \begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & 1 & -1 & 0 \\ 0 & -1 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \quad e=3 \quad \begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & -1 \\ 0 & 0 & -1 & 1 \end{bmatrix}$$

ASSEMBLY:

$$\therefore \frac{3k}{L} \begin{bmatrix} 1 & -1 & 0 & 0 \\ -1 & 1 & -1 & 0 \\ 0 & -1 & 1 & -1 \\ 0 & 0 & -1 & 1 \end{bmatrix} \begin{bmatrix} Q_1 \\ Q_2 \\ Q_3 \\ Q_4 \end{bmatrix} = \frac{SL}{6} \begin{bmatrix} 1 \\ 1+1 \\ 1+1 \\ 1 \end{bmatrix} + \begin{bmatrix} q \\ 0 \\ 0 \\ kdT^N/dx \end{bmatrix}$$

$$\begin{bmatrix} 1 & -1 & 0 & 0 \\ -1 & 2 & -1 & 0 \\ 0 & -1 & 2 & -1 \\ 0 & 0 & -1 & 1 \end{bmatrix} \begin{bmatrix} Q_1 \\ Q_2 \\ Q_3 \\ Q_4 \end{bmatrix} = \frac{L}{3k} \begin{bmatrix} SL/6 + q \\ SL/3 \\ SL/3 \\ SL/6 + kdT^N/dx \end{bmatrix}$$

IMPOSING DIRICHLET:

$$\begin{bmatrix} 1 & -1 & 0 & 0 \\ -1 & 2 & -1 & 0 \\ 0 & -1 & 2 & -1 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} Q_1 \\ Q_2 \\ Q_3 \\ Q_4 \end{bmatrix} = \begin{bmatrix} 4/3k (SL/6 + q) \\ SL^2/9k \\ SL^2/9k \\ T_b \end{bmatrix}$$

SOLVE FOR NODAL VALUES:

$$Q_1 = \frac{1}{2k} [SL^2 + 2Lq + 2T_b k] = \frac{SL^2}{2k} + \frac{Lq}{k} + T_b$$

$$Q_2 = \frac{1}{9k} [4SL^2 + 6Lq + 9T_b k] = \frac{4SL^2}{9k} + \frac{2Lq}{3k} + T_b$$

$$Q_3 = \frac{1}{18k} [5SL^2 + 6Lq + 18T_b k] = \frac{5SL^2}{18k} + \frac{Lq}{3k} + T_b$$

$$Q_4 = T_b$$

p.32 data

Determine actual nodal temperatures for

$$q(0) = 1500 \text{ Btu/h} \cdot \text{ft}^2$$

$$S = -1400 \text{ Btu/ft}^3 \cdot \text{h}$$

$$K = 4 \text{ Btu/h} \cdot ^\circ\text{F} \cdot \text{ft}$$

$$T_b(L) = 0^\circ\text{F}$$

SOLVE FOR $\frac{k dT^N}{dx}$:

$$-Q_3 + Q_4 = \frac{L}{3k} (SL/6 + k dT^N/dx)$$

$$k \frac{dT^N}{dx} = -SL - q$$

w/ given data

$$Q_1 = 200^\circ\text{F}$$

$$Q_2 = 94.4^\circ\text{F}$$

$$Q_3 = 27.8^\circ\text{F}$$

$$Q_4 = 0^\circ\text{F}$$

Plot needed

w/ comparison to 3 node solution

Comments: When doing so much by hand it's easy to miss a sign or write/type something incorrectly & much more difficult to find the ~~error~~ mistake. Imagine doing a 20 element grid!

In other news, for this function, increasing the number of nodes decreases the error by a noticeable (see plot) amount, while doubling the effort required to obtain it. Makes me think that there must be another way to do it.

Excellent Job!

[>

3/14/02 Problem 1 (Done)

```
[ > restart;
> e1:=Q1-Q2=s*L^2/8/k+L/2/k*q;
e2:=-Q1+2*Q2=2*s*L^2/8/k+Tb;
e3:=-Q2-L/2/k*k_dTN_dx=s*L^2/8/k-Tb;

e1:=Q1-Q2= $\frac{1}{8} \frac{s L^2}{k} + \frac{1}{2} \frac{L q}{k}$ 

e2:=-Q1+2 Q2= $\frac{1}{4} \frac{s L^2}{k} + Tb$ 

e3:=-Q2- $\frac{1}{2} \frac{L k \text{ dTN\_dx}}{k} = \frac{1}{8} \frac{s L^2}{k} - Tb$ 

> solve({e1,e2,e3},{Q1,Q2,k_dTN_dx});

{Q2= $\frac{1}{8} \frac{3 s L^2 + 4 L q + 8 T b k}{k}$ , Q1= $\frac{1}{2} \frac{s L^2 + 2 L q + 2 T b k}{k}$ , k_dTN_dx=-s L - q}
```

[>

3/14/02 Problem 2 (Done)

```
[ > restart;
> e1:=Q1-Q2=L/3/k*(s*L/6+q);
e2:=-Q1+2*Q2-Q3=s*L^2/9/k;
e3:=-Q2+2*Q3-Q4=s*L^2/9/k;
e4:=Q4=Tb;

e1:=Q1-Q2= $\frac{1}{3} \frac{L \left( \frac{1}{6} s L + q \right)}{k}$ 

e2:=-Q1+2 Q2-Q3= $\frac{1}{9} \frac{s L^2}{k}$ 

e3:=-Q2+2 Q3-Q4= $\frac{1}{9} \frac{s L^2}{k}$ 

e4:=Q4=Tb

> soll:=solve({e1,e2,e3,e4},{Q1,Q2,Q3,Q4});

soll:={Q4=Tb, Q3= $\frac{1}{18} \frac{5 s L^2 + 6 L q + 18 T b k}{k}$ , Q2= $\frac{1}{9} \frac{4 s L^2 + 6 L q + 9 T b k}{k}$ ,

Q1= $\frac{1}{2} \frac{s L^2 + 2 L q + 2 T b k}{k}$ }

> assign(soll);
```

```

> e5:=-Q3+Q4=L/3/k*(s*L/6+k_dTN_dx);

$$e5 := -\frac{1}{18} \frac{5sL^2 + 6Lq + 18Tbk}{k} + Tb = \frac{1}{3} \frac{L \left( \frac{1}{6} sL + k_dTN_{dx} \right)}{k}$$

> sol2:=solve(e5,k_dTN_dx);

$$sol2 := -sL - q$$

> q:=1500;s:=-1400;k:=4;Tb:=0;L:=1;

$$q := 1500$$


$$s := -1400$$


$$k := 4$$


$$Tb := 0$$


$$L := 1$$

> Q1;

$$200$$

> evalf(Q2);

$$94.44444444$$

> evalf(Q3);

$$27.77777778$$

> Q4;

$$0$$

> eq1:=s*L^2/2/k*(1-(x/L)^2)+q*L/k*(1-(x/L))+Tb;

$$eq1 := 200 + 175x^2 - 375x$$

> with(plots):
> p0:=plot(eq1,x=0..1,color=black):
> p1:=pointplot({[0,Q1],[L/3,Q2],[2*L/3,Q3],[L,Q4]},color=blue,symbol=box):p2:=pointplot({[0,s*L^2/2/k+q*L/k+Tb],[L/2,3*s*L^2/8/k+q*L/2/k+Tb],[L,Tb]},color=red,symbol=circle):
y = mx + b
m = (y1-y2)/(x1-x2)
y - y2 = (y1-y2)x2/(x1-x2) + b
b = y2 - x2(y1-y2)/(x1-x2)
y = (y1-y2)/(x1-x2) x + y2 - x2(y1-y2)/(x1-x2)
y (x1-x2) - y2 (x1-x2) = x (y1-y2) - x2 (y1-y2)
y (x1-x2) - y2 (x1-x2) = (x - x2) (y1-y2)
y - y2 = (x-x2) (y1-y2)/(x1-x2)
y = (x-x2) * (y1-y2)/(x1-x2) + y2
> piece1:=plot(piecewise(x<1/3,
(x-1/3)*
(Q1-Q2)/(0-1/3)
+Q2,x<2/3,
(x-2/3)*

```

```

(Q2-Q3)/(1/3-2/3)
+Q3,x<1,
(x-1)*
(Q3-Q4)/(2/3-1)
+Q4),x=0..1
,color=blue):
piece2:=plot(piecewise(x<1/2,
(x-1/2)*
(s*L^2/2/k+q*L/k+Tb-(3*s*L^2/8/k+q*L/2/k+Tb))/(0-1/2)
+(3*s*L^2/8/k+q*L/2/k+Tb),x<1,
(x-1)*
(3*s*L^2/8/k+q*L/2/k+Tb-Tb)/(1/2-1)
+Tb),x=0..1):

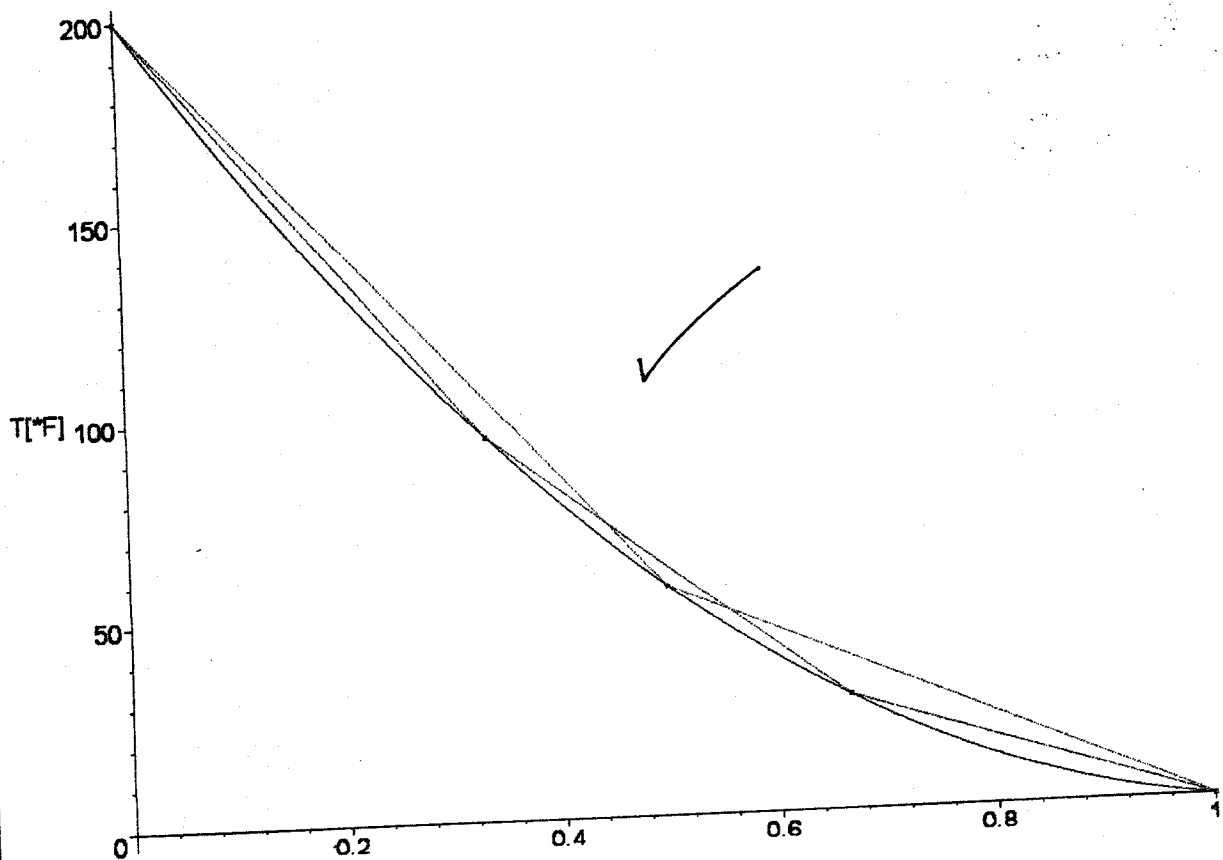
```

provide plot of points for M=2 and M=3 with eq1

```

> display({p0,p1,p2,piece1,piece2},labels=["x[ft]","T[*F]"],title
="Temperature Approximations");

```



```

[ >
3/15/02 Problem 1 is done, by hand.
3/15/02 Problem 2 is done, but not fully understood, by hand.
[ >

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PROBLEM 1

DETERMINE MASTER MATRICES [A200L] AND [A211L]

A200L: 1-dimensional matrix
 2-bases in integral
 (neither is differentiated) ✓
 L - linear basis function

$$\int_{\Omega_e} \{N_1\} \{N_1\}^T d\bar{x}$$

$$\{N_1\}_{2 \times 1} = \begin{Bmatrix} \delta_1 \\ \delta_2 \end{Bmatrix} = \begin{Bmatrix} 1 - \bar{x}/l_e \\ \bar{x}/l_e \end{Bmatrix} \quad \{N_1\}_{1 \times 2}^T = \{\delta_1, \delta_2\} = \{1 - \bar{x}/l_e, \bar{x}/l_e\} \quad \checkmark$$

$$\int_{\Omega_e} \begin{bmatrix} (1 - \bar{x}/l_e)^2 & \bar{x}/l_e (1 - \bar{x}/l_e) \\ \bar{x}/l_e (1 - \bar{x}/l_e) & (\bar{x}/l_e)^2 \end{bmatrix} d\bar{x} \quad \checkmark$$

$$\int \begin{bmatrix} 1 - 2\bar{x}/l_e + (\bar{x}/l_e)^2 & \bar{x}/l_e - (\bar{x}/l_e)^2 \\ \bar{x}/l_e - (\bar{x}/l_e)^2 & (\bar{x}/l_e)^2 \end{bmatrix} d\bar{x}$$

$$\left[\begin{array}{cc} \bar{x} - \bar{x}^2/l_e + \bar{x}^3/3l_e^2 & \bar{x}^2/2l_e - \bar{x}^3/3l_e^2 \\ \bar{x}^2/2l_e - \bar{x}^3/3l_e^2 & \bar{x}^3/3l_e^2 \end{array} \right] \bigg|_{\Omega_e=0, l_e}$$

$$\left[\begin{array}{cc} \bar{x} (1 - \bar{x}/l_e + \frac{1}{3}(\bar{x}/l_e)^2) & \bar{x} (\frac{1}{2}(\bar{x}/l_e) - \frac{1}{3}(\bar{x}^2/l_e^2)) \\ \bar{x} (\frac{1}{2}(\bar{x}/l_e) - \frac{1}{3}(\bar{x}/l_e)^2) & \bar{x} (\frac{1}{3}(\bar{x}/l_e)^2) \end{array} \right]$$

$$l_e \begin{bmatrix} 1 - 1 + \frac{1}{3}(1) & \frac{1}{2}(1) - \frac{1}{3}(1) \\ \frac{1}{2}(1) - \frac{1}{3}(1) & \frac{1}{3}(1) \end{bmatrix}$$

$$l_e \begin{bmatrix} \frac{1}{3} & \frac{1}{6} \\ \frac{1}{6} & \frac{1}{3} \end{bmatrix}$$

$\Rightarrow$ A200L

Read!

AZ11L:

- 1- dimensional matrix ($k=1$)
- 2- basis in integral
(both differentiated)
- 2- linear basis functions

$$\int_{\Omega_e} \frac{d\{N_i\}}{dx} \frac{d\{N_i\}^T}{dx} d\bar{x} \quad \checkmark$$

$$\{N_i\} = \begin{matrix} \delta_1 \\ \delta_2 \end{matrix} = \begin{matrix} 1 - \bar{x}/l_e \\ \bar{x}/l_e \end{matrix} \quad \frac{d}{dx} = \begin{matrix} -1/l_e \\ 1/l_e \end{matrix}$$

$$\begin{pmatrix} -1/l_e \\ 1/l_e \end{pmatrix} \begin{pmatrix} -1/l_e & 1/l_e \end{pmatrix} = \begin{matrix} 1/l_e^2 & -1/l_e^2 \\ -1/l_e^2 & 1/l_e^2 \end{matrix}$$

$$\frac{1}{l_e^2} \int_{\Omega_e} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} d\bar{x} \quad \checkmark \quad \frac{1}{l_e^2} \begin{bmatrix} \bar{x} & -\bar{x} \\ -\bar{x} & \bar{x} \end{bmatrix} \Big|_{l_e} = \frac{1}{l_e^2} \begin{bmatrix} l_e & -l_e \\ -l_e & l_e \end{bmatrix} \quad \checkmark$$

$$AZ11L \Rightarrow \frac{1}{l_e} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix}$$

✓
Gmaly!

ASSIGNED 3/15/02

PROBLEM 2:

Apply recipe steps 1-6, i.e. eg (12)

$$\begin{aligned} GWS^* &= \sum_e GWS_e^* \\ &= \sum_e \left(\int_{\Omega_e} \frac{d\{N_k\}}{dx} k(x) \frac{d\{N_k\}^T}{dx} d\bar{x} \{Q\}_e \right. \\ &\quad \left. - \int_{\Omega_e} \{N_k\} s(x) d\bar{x} - k(x) \frac{dT^N}{dx} \begin{Bmatrix} \delta_{el} \\ \delta_{em} \end{Bmatrix} = \{0\} \right) \end{aligned}$$

for the following ODE + BC set

(a) $\mathcal{L}(h) = \frac{d}{dx} \left(\frac{1}{Pa} \frac{dh(x)}{dx} \right) - u h(x) = 0 \quad \Omega \in (0, L)$

(b) $\mathcal{L}(h) = \frac{dh(x)}{dx} = 0 \quad \checkmark \quad \partial\Omega \in L$

(c) $h = h_0 \quad \partial\Omega \in 0$

(1) $h(x) \approx h^N(x) = \sum_{\alpha=1}^N \Psi_{\alpha}(x) Q_{\alpha} \quad \checkmark \quad \int_0^L u dv = - \int_0^L v du + uv \Big|_0^L$

(2) $e^N(x) = h(x) - h^N(x) \quad \checkmark$

$\mathcal{L}\{e^N\} = \mathcal{L}\{h\} - \mathcal{L}\{h^N\} = -\mathcal{L}\{h^N\} \quad \checkmark$

$WS^N = \int_{\Omega} \Phi_{\beta} \mathcal{L}(h^N) dx \quad \checkmark \quad GWS^N = \int_{\Omega} \Psi_{\beta} \mathcal{L}(h^N) dx \quad \checkmark$

$GWS^N = \int_{\Omega} \Psi_{\beta} \left[\frac{d}{dx} \left(\frac{1}{Pa} \frac{dh(x)}{dx} \right) - u h(x) \right] dx = 0 \quad \checkmark$

$= \int_{\Omega} \Psi_{\beta} \left[\frac{d}{dx} \left(\frac{1}{Pa} \frac{d\Psi_{\alpha} Q_{\alpha}}{dx} \right) - u \Psi_{\alpha} Q_{\alpha} \right] dx = 0 \quad \checkmark$
 Substitution from (1)
 Integrate by parts

$u = \Psi_{\beta} \quad dv = \frac{1}{Pa} \frac{d\Psi_{\alpha} Q_{\alpha}}{dx} \quad \checkmark$

$du = \frac{d\Psi_{\beta}}{dx} \quad v = \frac{1}{Pa} \left(\frac{d\Psi_{\alpha} Q_{\alpha}}{dx} \right)$

$= \int_{\Omega} \left[-\frac{1}{Pa} \left(\frac{d\Psi_{\alpha} Q_{\alpha}}{dx} \right) \frac{d\Psi_{\beta}}{dx} - \Psi_{\alpha} Q_{\alpha} \right] dx + \Psi_{\beta} \frac{1}{Pa} \left(\frac{d\Psi_{\alpha} Q_{\alpha}}{dx} \right) \Big|_{\partial\Omega} = 0 \quad \checkmark$

PREVIOUSLY

$$\int_{\Omega} \left[-\frac{d\psi_{\beta}}{dx} \left(\frac{1}{Pa} \frac{d\psi_{\alpha}}{dx} \right) - u \psi_{\alpha} \right] dx Q_{\alpha} + \psi_{\beta} \frac{1}{Pa} \left(\frac{d\psi_{\alpha} Q_{\alpha}}{dx} \right) \bigg|_0^L$$

DESCRIPTION $\Rightarrow (\psi_{\alpha} Q_{\alpha})_e = \{N_k(\xi_i)\}^T \{Q\}_e$

$(\psi_{\beta})_e = \{N_k(\xi_i)\}$ ✓

FOR ASSEMBLY $\Rightarrow \psi_{\alpha} Q_{\alpha} = S_e (\{N_k(\xi_i)\}^T \{Q\}_e)$

$\int_{\Omega} GWS^h = S_e GWS_e^h$

$$GWS_e^h = \int_{\Omega_e} \left[-\frac{d\{N_k\}}{dx} \left(\frac{1}{Pa} \frac{d\{N_k\}^T}{dx} \right) \right] d\bar{x} \{Q\}_e + \int_{\Omega_e} [-u \{N_k\}^T] d\bar{x} \{Q\}_e$$

THIS I CAN'T UNDERSTAND $\left\{ \frac{1}{Pa} \frac{dh^N}{dx} \begin{Bmatrix} \delta_{el} \\ \delta_{em} \end{Bmatrix} = \begin{Bmatrix} 0 \\ 0 \end{Bmatrix} \right.$

$\therefore GWS^h = \int_{\Omega_e} \left[-\int_{\Omega_e} \frac{d\{N_k\}}{dx} \frac{1}{Pa} \frac{d\{N_k\}^T}{dx} d\bar{x} \{Q\}_e - \int_{\Omega_e} u \{N_k\}^T d\bar{x} \{Q\}_e + \frac{1}{Pa} \frac{dh^N}{dx} \begin{Bmatrix} \delta_{el} \\ \delta_{em} \end{Bmatrix} = \begin{Bmatrix} 0 \\ 0 \end{Bmatrix} \right]$ ✓

do you see it now?

Awesome!