

ECE-320 Quiz #4

For problems 1-3 , consider a closed loop system with transfer function

$$G_0(s) = \frac{s+a}{s^2+bs+k}$$

1) The sensitivity to variations in k , $S_k^{G_0}(s)$, is

- a) $\frac{k}{s^2+bs+k}$ b) $\frac{-k}{s^2+bs+k}$ c) 1 d) $\frac{k}{s+a} - \frac{k}{s^2+bs+k}$ e) none of these

2) The sensitivity to variations in b , $S_b^{G_0}(s)$, is

- a) $\frac{-b}{s^2+bs+k}$ b) $\frac{-bs}{s^2+bs+k}$ c) 1 d) $\frac{b}{s+a} - \frac{bs}{s^2+bs+k}$ e) none of these

3) The sensitivity to variations in a , $S_a^{G_0}(s)$, is

- a) $\frac{a}{s^2+bs+k}$ b) $\frac{-a}{s^2+bs+k}$ c) 1 d) $\frac{a}{s+a}$ e) none of these

4) Assume we compute the sensitivity of a system with nominal value $a = 4$ to be

$$S_a^{G_0}(s) = \frac{1}{s+a}$$

For what frequencies will the sensitivity function be less than $\frac{1}{\sqrt{32}}$?

- a) $\omega < 4$ rad/sec b) $\omega > 4$ rad/sec c) $\omega > 16$ rad/sec d) $\omega < 16$ rad/sec e) none of these

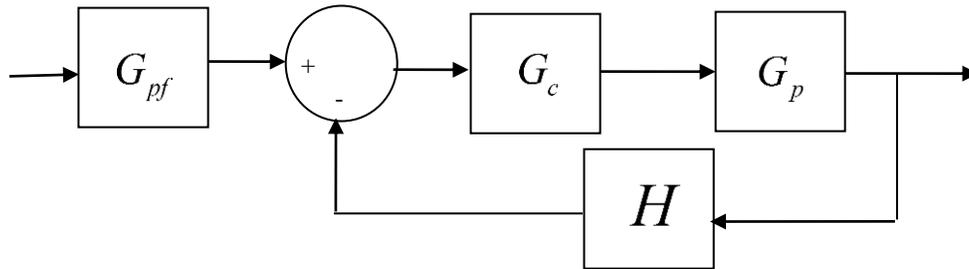
5) Assume we compute the sensitivity of a system with nominal value $a = 3$ to be

$$S_a^{G_0}(s) = \frac{s+2}{s+1+a}$$

For what frequencies will the sensitivity function be greater than $\sqrt{\frac{10}{16}}$?

- a) $\omega < 4$ rad/sec b) $\omega > 4$ rad/sec c) $\omega > 16$ rad/sec d) $\omega < 16$ rad/sec e) none of these

Problems 6-9 refer to the following system



6) To reduce the sensitivity of the closed loop transfer function variations in the plant G_p , we should

- a) make $|G_c(j\omega)G_p(j\omega)H(j\omega)|$ large b) make $|G_c(j\omega)G_p(j\omega)H(j\omega)|$ small
 c) make G_{pf} large d) do nothing, we cannot change the sensitivity

7) To reduce the sensitivity of the closed loop transfer function to variations in the prefilter G_{pf} , we should

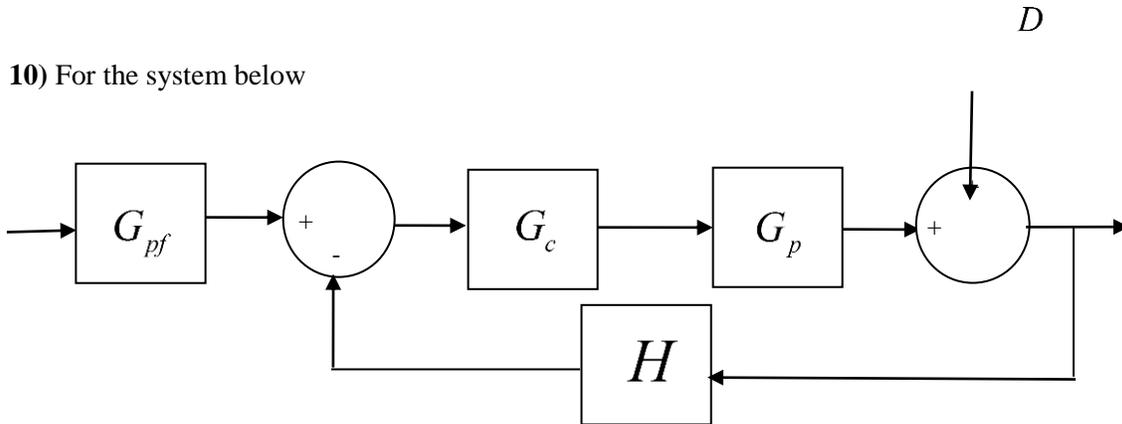
- a) make $|G_c(j\omega)G_p(j\omega)H(j\omega)|$ large b) make $|G_c(j\omega)G_p(j\omega)H(j\omega)|$ small
 c) make G_{pf} small d) do nothing, we cannot change the sensitivity

8) To reduce the sensitivity of the closed loop transfer function to variations in the controller G_c , we should

- a) make $|G_c(j\omega)G_p(j\omega)H(j\omega)|$ large b) make $|G_c(j\omega)G_p(j\omega)H(j\omega)|$ small
 c) make $|H(j\omega)|$ large d) do nothing, we cannot change the sensitivity

9) To reduce the sensitivity of the closed loop transfer function to variations in the sensor H , we should

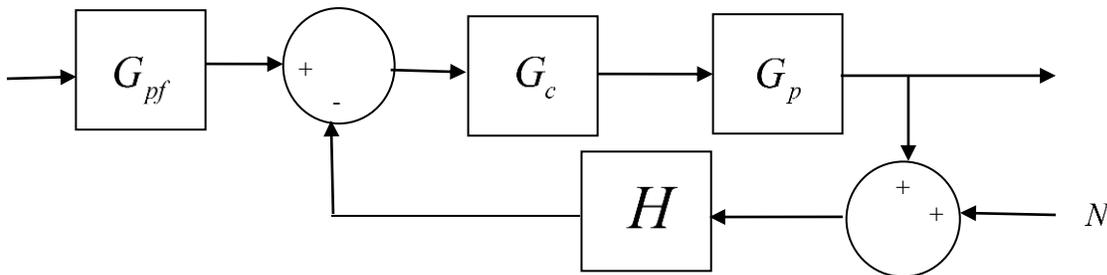
- a) make $|G_c(j\omega)G_p(j\omega)H(j\omega)|$ large b) make $|G_c(j\omega)G_p(j\omega)H(j\omega)|$ small
 c) make G_{pf} large d) do nothing, we cannot change the sensitivity



to reduce the effects of the external disturbance D on the system output, we should

- a) make $|G_c(j\omega)G_p(j\omega)H(j\omega)|$ large b) make $|G_c(j\omega)G_p(j\omega)H(j\omega)|$ small
 c) make G_{pf} large d) do nothing, we cannot change the sensitivity

11) For the system below



to reduce the effects of sensor noise N on the closed loop system, we should

- a) make $|G_c(j\omega)G_p(j\omega)H(j\omega)|$ large b) make $|G_c(j\omega)G_p(j\omega)H(j\omega)|$ small
 c) make $|H(j\omega)|$ large d) do nothing, we cannot change the sensitivity