

## Practice Quiz 5

(no calculators allowed)

For problems 1 and 2, assume  $z = \frac{e^{-j\omega_0 t}}{3+2j}$ ,

**1) The magnitude of  $z$ ,  $|z|$ , is equal to**

- a)  $\frac{1}{\sqrt{5}}$
- b)  $\frac{1}{\sqrt{13}}$
- c)  $\frac{e^{-j\omega_0 t}}{\sqrt{5}}$
- d)  $\frac{e^{-j\omega_0 t}}{\sqrt{13}}$
- e) none of these

**2) The complex conjugate of  $z$ ,  $z^*$ , is equal to**

- a)  $z^* = \frac{e^{-j\omega_0 t}}{3-2j}$
- b)  $z^* = \frac{e^{+j\omega_0 t}}{3+2j}$
- c)  $z^* = \frac{e^{+j\omega_0 t}}{3-2j}$
- d) none of these

For problems 3 and 4, assume we know  $z = 10\angle 45^\circ$

**3) The magnitude of the conjugate of  $z$ ,  $|z^*|$ , is equal to**

- a) 10
- b) -10
- c) 5
- d) -5
- e) none of these

**4) The phase of the conjugate of  $z$ ,  $\angle z^*$ , is equal to**

- a)  $45^\circ$
- b)  $-45^\circ$
- c)  $0^\circ$
- d) none of these

**5) Using Euler's identity, we can write  $\cos(\omega t)$  as**

- a)  $\frac{e^{j\omega t} + e^{-j\omega t}}{2}$
- b)  $\frac{e^{j\omega t} - e^{-j\omega t}}{2}$
- c)  $\frac{e^{j\omega t} + e^{-j\omega t}}{2j}$
- d)  $\frac{e^{j\omega t} - e^{-j\omega t}}{2j}$

**6) Using Euler's identity, we can write  $\sin(\omega t)$  as**

- a)  $\frac{e^{j\omega t} + e^{-j\omega t}}{2}$
- b)  $\frac{e^{j\omega t} - e^{-j\omega t}}{2}$
- c)  $\frac{e^{j\omega t} + e^{-j\omega t}}{2j}$
- d)  $\frac{e^{j\omega t} - e^{-j\omega t}}{2j}$

For problems 7 and 8, assume we have an LTI system with impulse response  $h(t) = e^{-t}u(t+1)$

7) Is the system **causal**?      a) yes    b) no

8) Is the system **BIBO** stable? a) yes    b) no

9) Assume  $x(t) = 2\cos(3t)$  is the input to an LTI system with transfer function  $H(j\omega) = 2e^{-j\omega}$ . In steady state the output of this system will be

- a)  $y(t) = 4\cos(3t)e^{-j3}$     b)  $y(t) = 4\cos(3t - 3)$     c)  $y(t) = 4\cos(3t - 1)$     d) none of these

Problems 10-12 refer to a system with transfer function  $H(s) = \frac{10}{s+3}$ . Assume the input to this system is  $x(t) = 2\cos(3t + 30^\circ)$

10) In steady state, the **magnitude** of the output will be

- a)  $\frac{20}{3}$     b)  $\frac{20}{\sqrt{18}}$     c)  $\frac{20}{\sqrt{8}}$     d)  $\frac{20}{6}$

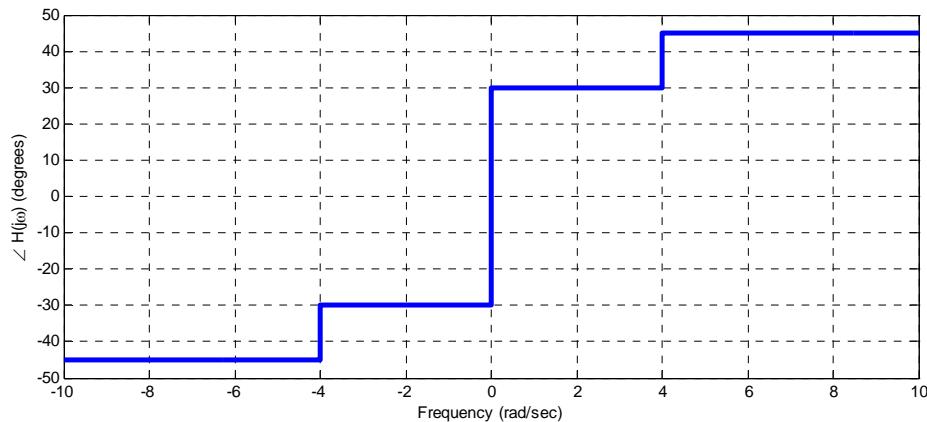
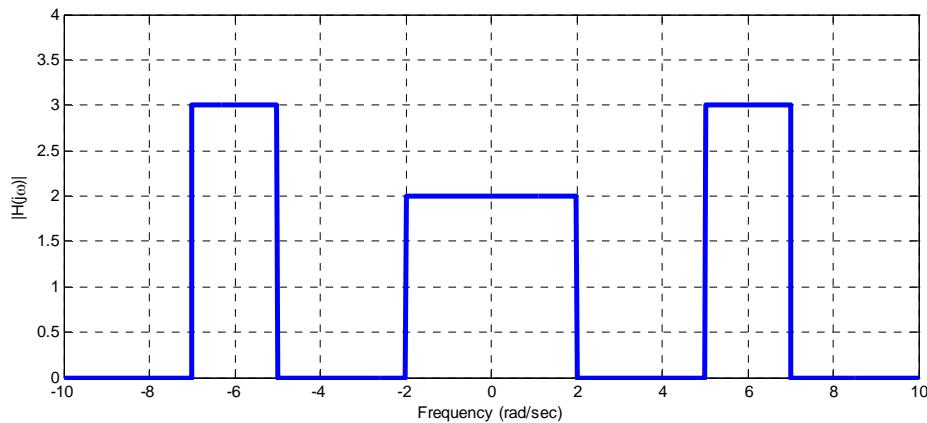
11) In steady state, the **phase** of the output will be

- a)  $30^\circ$     b)  $45^\circ$     c)  $-15^\circ$     d)  $-45^\circ$

12) The **bandwidth** (-3 dB point) of the system is

- a) 10 Hz    b) 10 radians/sec    c) 3 radians/sec    d) 3 Hz

13) Assume  $x(t) = 2 + 3\cos(t) + 3\cos(4t) + 2\cos(6t)$  is the input to an LTI system with the transfer function shown graphically (magnitude and phase) below:



The steady state output of the system will be

- a) 0
- b)  $y(t) = 2 + 3\cos(t) + 3\cos(4t) + 2\cos(6t)$
- c)  $y(t) = 4 + 6\cos(t) + 6\cos(6t)$
- d)  $y(t) = 4 + 6\cos(t + 30^\circ) + 6\cos(6t + 45^\circ)$
- e)  $y(t) = 2 + 6\cos(t + 30^\circ) + 6\cos(6t + 45^\circ)$
- f)  $y(t) = 4 + 3\cos(t + 30^\circ) + 2\cos(6t + 45^\circ) + 3\cos(t - 30^\circ) + 2\cos(6t - 45^\circ)$
- g)  $y(t) = 4 + 6\cos(t + 30^\circ) + 6\cos(6t + 45^\circ) + 6\cos(t - 30^\circ) + 6\cos(6t - 45^\circ)$
- h) none of these

**14)** Assume  $x(t) = 3\cos(2t - 5)$  is the input to a system with transfer function

$$H(j\omega) = \begin{cases} 3e^{-j2\omega} & |\omega| < 3 \\ 2 & \text{else} \end{cases}$$

the output  $y(t)$  in steady state will be

- a)  $y(t) = 6\cos(2t - 5)$
- b)  $y(t) = 9\cos(2t - 5)$
- c)  $y(t) = 9\cos(2t - 5)e^{-j4}$
- d)  $y(t) = 9\cos(2t - 9)$

**15)** Assume  $x(t) = 2\cos(3t)$  is the input to system with transfer function  $H(j\omega) = 2e^{-j\omega}$ . In steady state the output of the system will be

- a)  $y(t) = 4\cos(3t)e^{-j\omega}$
- b)  $y(t) = 4\cos(3t)e^{-j3}$
- c)  $y(t) = 4\cos(3t - 3)$
- d)  $y(t) = 4\cos(3t + 3)$
- e) none of these

**16)** Assume  $x(t) = 2\cos(t) + 5\sin(2t) + 6\sin(3t)$  is the input to a system with transfer

function  $H(j\omega) = 3\Pi\left(\frac{\omega}{5}\right)$ . In steady state the output of the system will be

- a)  $y(t) = [2\cos(t) + 5\sin(2t) + 6\sin(3t)] \left[ 3\text{rect}\left(\frac{\omega}{5}\right) \right]$
- b)  $y(t) = 6\cos(t) + 15\sin(2t) + 18\sin(3t)$
- c)  $y(t) = 6\cos(t) + 15\sin(2t)$
- d) none of these

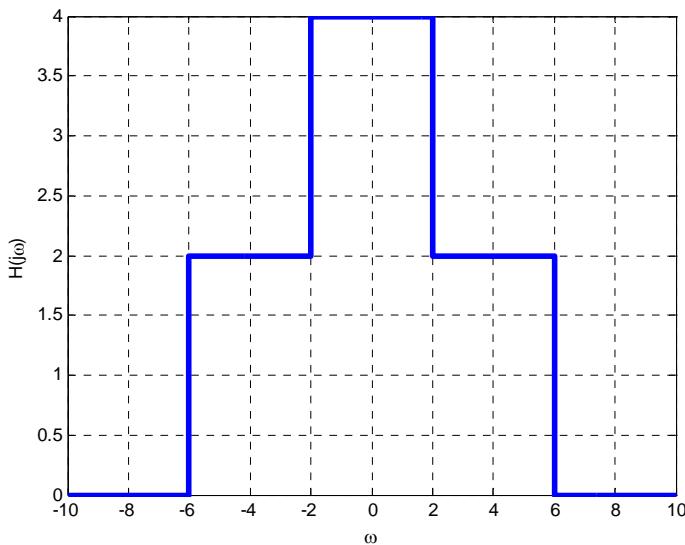
**17)** Assume  $x(t) = 2\cos(3t) + 4\cos(5t)$  is the input to a system with transfer function given by

$$H(j\omega) = \begin{cases} 2 & 4 < |\omega| < 6 \\ 0 & \text{else} \end{cases}$$

The output of the system in steady state will be

- a)  $y(t) = 4\cos(3t) + 8\cos(5t)$
- b)  $y(t) = 8\cos(5t)$
- c)  $y(t) = 4\cos(3t)$
- d) none of these

**18)** Assume  $x(t) = \cos(t) + \cos(5t) + \cos(9t)$  is the input to a system with transfer function given below:



The output of this system in steady state will be

- a)  $y(t) = 4\cos(t) + 4\cos(5t)$
- b)  $y(t) = 4\cos(t) + 2\cos(5t) + \cos(9t)$
- c)  $y(t) = 4\cos(t) + 2\cos(5t)$
- d) none of these

**Answers:** 1-b, 2-c, 3-a, 4-b, 5-a, 6-d, 7-b, 8-a, 9-b, 10-b, 11-c, 12-c, 13-d, 14-d, 15-c, 16-c, 17-b, 18-c