

Share The Future - II

A Working Conference

*Sophomore Engineering Curricula -
A Proven, Innovative Approach to
Engineering Science Education*

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Foundation Coalition

Objectives of Workshop

- Revisit the idea of a *core* curricula.
- Discuss a proven approach to integrate the engineering science core.
- Discuss ways to apply this framework to develop courses and curricula.

Workshop Overview

- Introductions
- Systems, Conservation & Accounting, and Modeling Paradigm
 - Concepts & Definitions
 - Conservation & Accounting Principles
 - Common Problem Solving Format
 - Example Solutions
- Curricula -- TAMU & RH
- Questions

What's a Sophomore Engineering Curricula?

An integrated engineering science
(and mathematics) curricula
taught at the sophomore level.

Advantages of the Systems, Accounting & Modeling Approach

- provides a conceptual framework.
- unifies the presentation of physical laws.
- helps students see links between apparently unrelated topics.
- promotes transfer of learning.
- allows a common problem solving strategy that helps students tackle new problems and apply new concepts.

Group Activity 1

Assuming that there is an engineering science and mathematics core that should be common for all engineering students,

- what would you place in the core in terms of courses or topics, and
- what, if any, common concepts or topics run through all of the core courses?

Is there a core?



What's Core Material?



*What are the themes or
threads of the core?*



What's the Sophomore Engineering Curriculum approach?

A curriculum built on the belief that

- There is a common engineering science and mathematics core for *all* engineers.
- This core should serve as a foundation for discipline specific education.
- Both vertical and horizontal integration of course material are important.
- Learning can be improved if the core is built around a few key concepts.

What's Core Material?

Diff. Equations I	Dynamics	Circuits
Fluid Mechanics	Linear Algebra	Statistics
Statics	Thermodynamics	Diff. Equations II
Heat Transfer	System Dynamics	Mechanics of Materials
	Materials	

Sophomore Engineering Curriculum
Content



Sophomore Engineering Curriculum

Contents

Free-Body Diagram

Ideal Spring

Dry Friction

Force

$$F = ma$$

Ideal Gas Law

Steam Tables

Closed System

Open System

Work & Heat Transfer

Ohm's Law

Node

Current

Voltage

KCL & KVL

Mass Flow

Control Volume

Friction Factor

Newtonian Fluid

Pressure

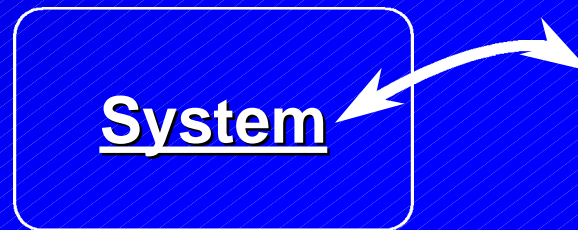
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Common Threads

Constitutive Relations

Ohm's Law
Ideal Spring
Dry Friction
Ideal Gas Law
Steam Tables
Friction Factor
Newtonian Fluid

Modeling Assumptions



System

Node

Free-Body Diagram

Closed System

Open system

Control Volume

Interactions with Surroundings

Current
Force
Work
Heat Transfer
Mass Flow

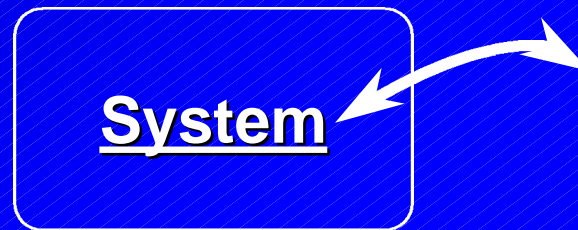
Physical Constraints

Accounting Equations

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Common Threads

Constitutive
Relations



Interactions
with
Surroundings

Modeling Assumptions

Physical Constraints

Accounting Equations

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Common Themes

- Conservation and accounting framework for physical laws
- Problem solving with a common strategy
 - Systems
 - Conservation and accounting concept
 - Modeling

*Where did this
approach come from?*

Where did it come from?

- 1987 - Unified Engineering Science Curriculum Project
 - NSF-funded project at Texas A&M
 - Developed a four-course sequence of sophomore engineering courses (the “20X sequence”):
 - Conservation Principles in Engineering
 - Properties of Matter
 - Modeling/Behavior of Engineering Systems
 - Conservation Principles of Continuous Media
 - <http://www-chen.tamu.edu/uesc/>

Where did it come from?

- L. Prandtl's fluid mechanics work in the early 1900's.
- Discipline of system dynamics
- Recent calls from physics
 - H. Burkhardt, "System physics: A uniform approach to the branches of classical physics." *Am. J. Phys.* 55, 344-350, 1987.
 - Chapter 1 in H. Fuchs, *The Dynamics of Heat*. Springer-Verlag, 1996.

W. G. Vincenti, *What Engineers Know and How They Know It*, Johns Hopkins Press, 1990.

- “Engineers, unlike physicists, are after useful artifacts and must predict the performance of the objects they design.”
- **“Organization according to control-volume ideas is thus not only simpler but brings clearer understanding of the physical principles common to otherwise disparate situations.”**
- “By organizing knowledge according to physical laws rather than known problems, it aids in recognizing a control-volume problem when met in an unfamiliar disguise.”

- “Control-volume analysis, by setting up an explicit method of bookkeeping for the various flow quantities, provides such a procedure for the many engineers who must deal with fluid-mechanical devices.”
- **“Control-volume analysis is useful precisely because it provides a framework and method for thinking clearly about a large class of the often confusing problems that arise in engineering design.”**

From Chpt 4, “A Theoretical Tool for Design: Control-Volume Analysis, 1912-1953.”

Concepts & Definitions

- Model
- System
 - Open system
 - Closed system
- Property
 - Intensive property
 - Extensive property
- State of a system
- Process
 - Steady state
 - Finite time
 - Transient
- Interaction
- Accounting Principle
- Conserved Property
- Constitutive Relation

Group Activity 2

- Match the name with the appropriate definition.
- Compare your answers with your team members

Some Concepts Defined

System - any region of space or quantity of matter set aside for analysis

Open system vs. Closed system

Isolated system

Property - any characteristic of a system that can be assigned a numerical value at a specified time without considering the history of the system.

Extensive property vs. Intensive property

Some Concepts Defined

State of a system - complete description of the system in terms of its properties

Process - the means by which a system changes its state.

Steady-state system

Interaction - the transport of an extensive property across a system's boundary.

Conserved property - a property that cannot be generated or consumed.

Accounting Equation for Extensive Property B

$$\frac{dB_{sys}}{dt} = \left[\dot{B}_{in} - \dot{B}_{out} \right] + \left[\dot{B}_{gen} - \dot{B}_{cons} \right]$$

Rate of Accumulation
of B
inside the system
at time t

Net Transport Rate
of B
into the system
at time t .

Net Generation Rate
of B
inside the system
at time t

Accounting Equation for Extensive Property B

$$\begin{aligned}
 \frac{d}{dt} B_{\text{sys}} &= \underbrace{\left[\dot{B}_{in} - \dot{B}_{out} \right]}_{\substack{\text{net rate transported} \\ \text{across the boundary} \\ \text{into the system}}} + \underbrace{\left[\dot{B}_{generated} - \dot{B}_{consumed} \right]}_{\substack{\text{net rate generated} \\ \text{within the system}}} \\
 &= \left[\dot{B}_{net,in} \Big|_{\substack{\text{without} \\ \text{mass flow}}} + \dot{B}_{net,in} \Big|_{\substack{\text{with} \\ \text{mass flow}}} \right] + \left[\dot{B}_{generated} - \dot{B}_{consumed} \right] \\
 &= \left[\dot{B}_{net,in} \Big|_{\substack{\text{without} \\ \text{mass flow}}} + \sum_{in} \dot{m}_i b_i - \sum_{out} \dot{m}_e b_e \right] + \left[\dot{B}_{generated} - \dot{B}_{consumed} \right]
 \end{aligned}$$

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Systems & Accounting

Framework for Physical Laws

- What's the extensive property?
- How can it be counted?
- How can it be stored in the system?
- How can it be transported?
- How can it be generated or consumed?

$$\begin{array}{c} \text{Rate} \\ \text{of} \\ \text{Storage} \end{array} = \begin{array}{c} \text{Net} \\ \text{Transport} \\ \text{Rate In} \end{array} + \begin{array}{c} \text{Net} \\ \text{Generation} \\ \text{Rate} \end{array}$$

Example

Conservation of
Linear Momentum

Conservation of Linear Momentum

What is linear momentum?

The linear momentum of a particle is the product of the mass of the particle m and its velocity \mathbf{V} . Students already know this definition from physics.

$$\vec{P} = m\vec{V}$$

Conservation of Linear Momentum

How can it be stored in and quantified for a system?

$$\vec{P}_{\text{sys}} = \int_{V_{\text{sys}}} \vec{V} \rho \, dV$$

$$\vec{P}_{\text{sys}} = \sum \vec{P}_j = \sum m_j \vec{V}_j$$

Conservation of Linear Momentum

How can it be transported across the system boundaries?

- External Forces
 - Contact Forces
 - Body Forces
- Mass transport

$$\vec{F}_{\text{external}}$$

$$\dot{m}\vec{V}$$

Conservation of Linear Momentum

How can linear momentum be generated or consumed within the system?

Experience has shown that it is impossible to create or destroy linear momentum; hence, we say that ***linear momentum is conserved.***

$$\dot{\vec{P}}_{gen} = \dot{\vec{P}}_{con} = 0$$

Conservation of Linear Momentum (Rate form)

$$\frac{dB_{\text{sys}}}{dt} = \left[\dot{B}_{in} - \dot{B}_{out} \right] + \left[\sum_{in} \dot{m}_i b_i - \sum_{out} \dot{m}_e b_e \right] + \left[\dot{B}_{gen} - \dot{B}_{cons} \right]$$

$$\frac{d\vec{P}_{\text{sys}}}{dt} = \left[\dot{\vec{P}}_{in} - \dot{\vec{P}}_{out} \right] + \left[\sum_{in} \dot{m}_i \vec{V}_i - \sum_{out} \dot{m}_e \vec{V}_e \right] + \left[\dot{\vec{P}}_{gen} - \dot{\vec{P}}_{cons} \right]$$

Note: A red arrow points from the third term to a red '0', indicating it is zero. A green arrow points from the first term to the external force equation below.

$$\sum \vec{F}_{\text{external}}$$

Conservation of Linear Momentum

$$\vec{P}_{\text{sys}} = \int_{V_{\text{sys}}} \vec{V} \rho dV$$

$$\frac{d\vec{P}_{\text{sys}}}{dt} = \sum \vec{F}_{\text{ext}} + \left[\sum_{\text{in}} \dot{m}_i \vec{V}_i - \sum_{\text{out}} \dot{m}_e \vec{V}_e \right]$$

where \dot{m} is the mass flow rate.

Recovering $F = ma$

$$\frac{d\vec{P}_{\text{sys}}}{dt} = \sum \vec{F}_{\text{ext}} + \left[\sum_{\text{in}} \dot{m}_i \vec{V}_i - \sum_{\text{out}} \dot{m}_e \vec{V}_e \right]$$

Closed System

$$\vec{P}_{\text{sys}} = m_G \vec{V}_G$$

$$\dot{m} = 0$$

$$\frac{d}{dt} \left(m_G \vec{V}_G \right) = \sum \vec{F}_{\text{ext}} \quad \rightarrow \quad m_G \frac{d}{dt} \left(\vec{V}_G \right) = m_G \vec{a}_G = \vec{F}_{\text{net}}$$

Group Activity 3

- Match the *extensive property* with its corresponding accounting (or conservation) equation.

Rate Form of Basic Laws

$$\underline{\frac{dm_{\text{sys}}}{dt}} = \underline{\sum_{\text{in}} \dot{m}_i} - \underline{\sum_{\text{out}} \dot{m}_e} \qquad \underline{\frac{dq_{\text{sys}}}{dt}} = \underline{\sum_{\text{in}} \dot{q}_i} - \underline{\sum_{\text{out}} \dot{q}_e}$$

$$\underline{\frac{d\bar{P}_{\text{sys}}}{dt}} = \underline{\sum_j \vec{F}_{\text{ext},j}} + \left[\underline{\sum_{\text{in}} \dot{m}_i \vec{V}_i} - \underline{\sum_{\text{out}} \dot{m}_e \vec{V}_e} \right]$$


$$\underline{\frac{d\vec{L}_{o,\text{sys}}}{dt}} = \underline{\sum_j \vec{M}_{o,j}} + \left[\underline{\sum_{\text{in}} \dot{m}_i (\vec{r}_i \times \vec{V}_i)} - \underline{\sum_{\text{out}} \dot{m}_e (\vec{r}_e \times \vec{V}_e)} \right]$$

$$\underline{\frac{dE_{\text{sys}}}{dt}} = \underline{\dot{Q}_{\text{net},in}} + \underline{\dot{W}_{\text{net},in}} + \left[\underline{\sum_{\text{in}} \dot{m}_i \left(h_i + \frac{V_i^2}{2} + gz_i \right)} - \underline{\sum_{\text{out}} \dot{m}_e \left(h_e + \frac{V_e^2}{2} + gz_e \right)} \right]$$

$$\underline{\frac{dS_{\text{sys}}}{dt}} = \underline{\sum_j \frac{\dot{Q}_j}{T_j}} + \left[\underline{\sum_{\text{in}} \dot{m}_i s_i} - \underline{\sum_{\text{out}} \dot{m}_e s_e} \right] + \underline{\dot{S}_{\text{gen}}}$$

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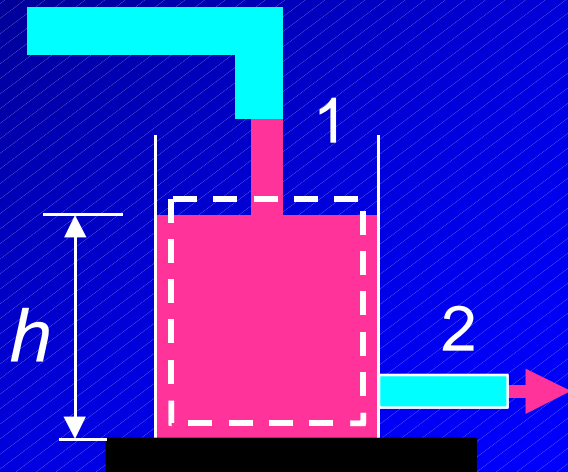
Problem Solving Format

- Known
- Find
- Given
- Analysis 
 - Strategy
 - Constructing model
 - Solution
- Comments

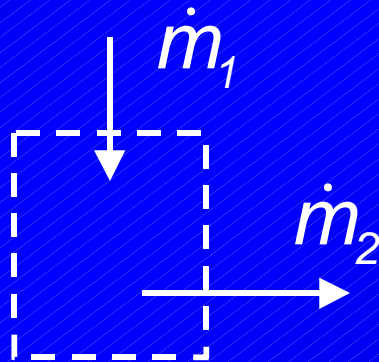
Typical Questions

- What's the system?
- What properties should we count?
- What's the time interval?
- What are the important interactions?
- What are the important constitutive relations?
- How do the basic equations simplify?
- What are the unknowns?
- How many equations do I need?

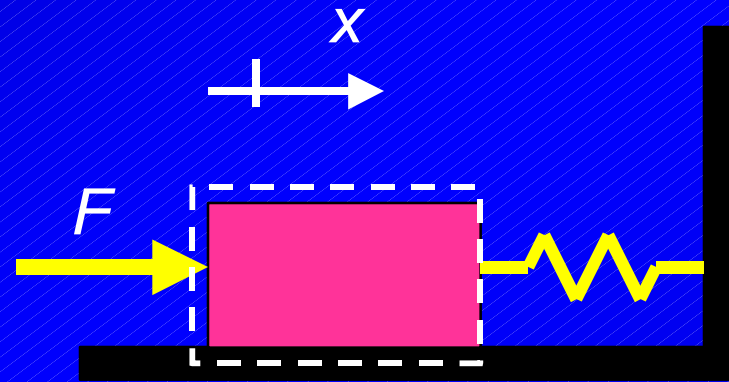
Find $h(t)$.



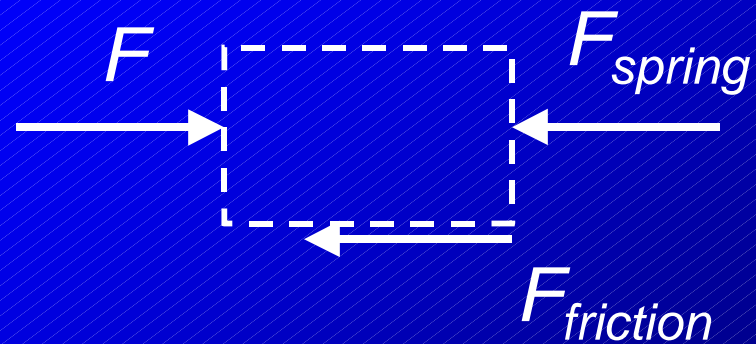
Mass



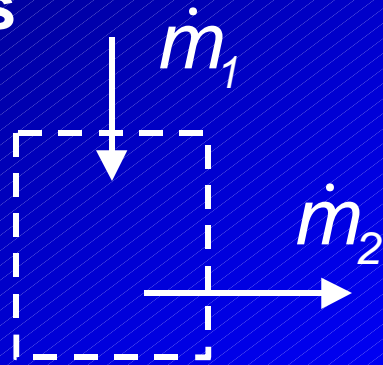
Find $V_x(t)$.



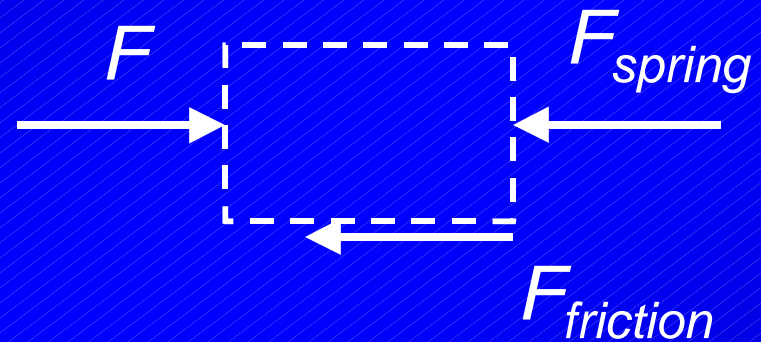
Linear Momentum



Mass



Linear Momentum



$$\frac{dm_{sys}}{dt} = \dot{m}_1 - \dot{m}_2$$

$$\frac{d}{dt}(rA_{tank}h) = \dot{m}_1 - C\sqrt{gh}$$

$$\frac{dh}{dt} = \frac{\dot{m}_1}{rA_{tank}} - \frac{C\sqrt{gh}}{rA_{tank}}$$

$$\frac{dP_{x,sys}}{dt} = F - F_{friction} - F_{spring}$$

$$\frac{d}{dt}(mV_x) = F - m_k mg - kx$$

$$\frac{dV_x}{dt} = \frac{F}{m} - m_k g - \frac{kx}{m}$$

Examples of how students are taught to solve problems

Heat Engine Performance



Monkeys on a Rope

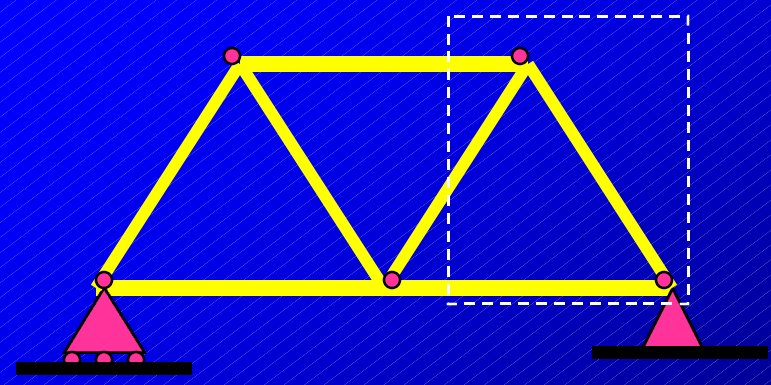
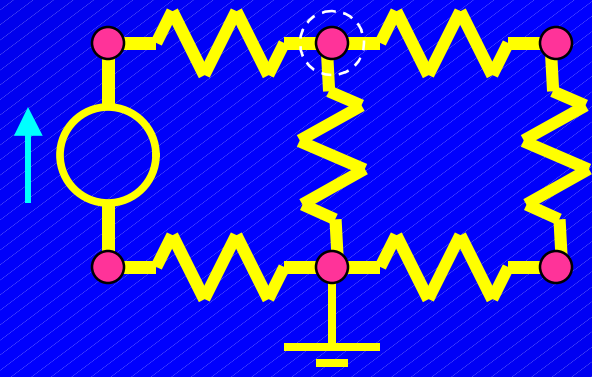
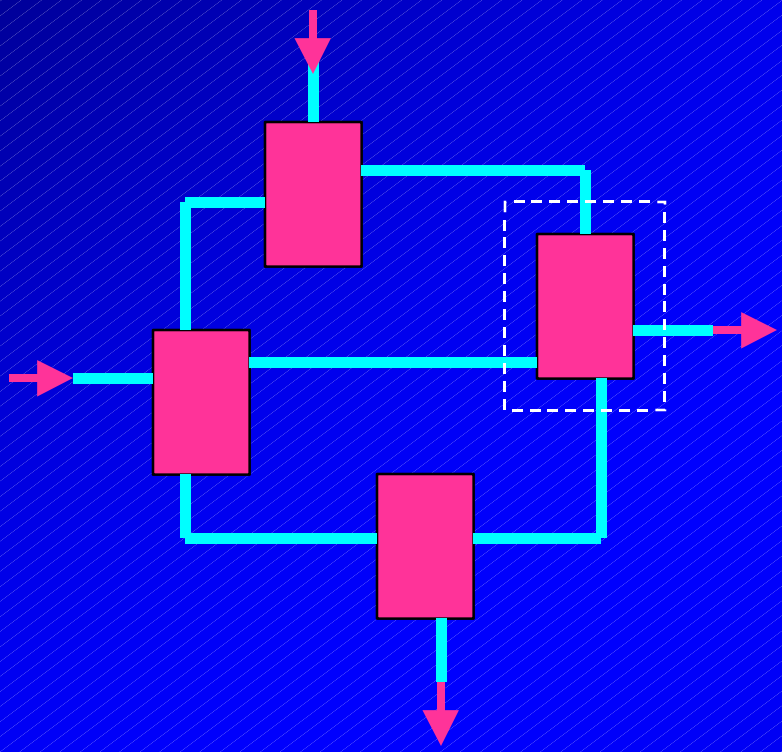


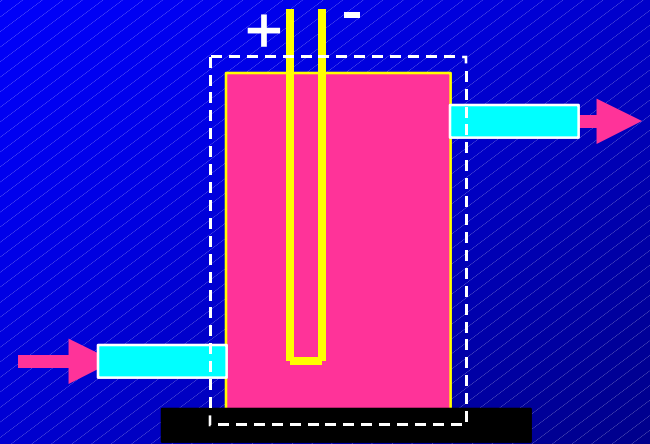
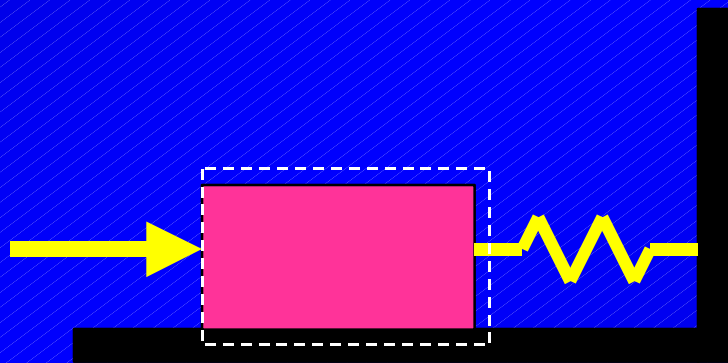
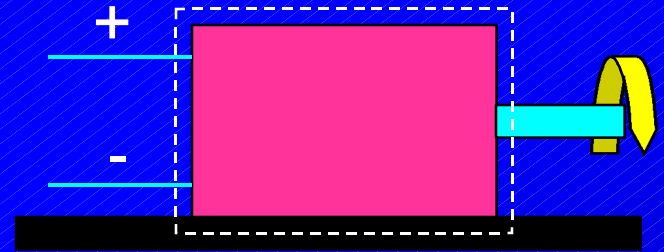
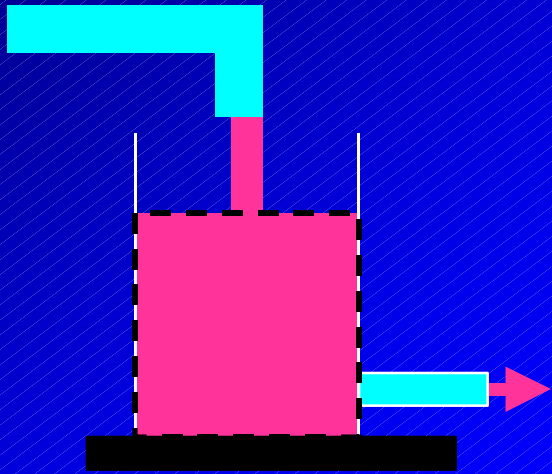
Colliding Train Cars

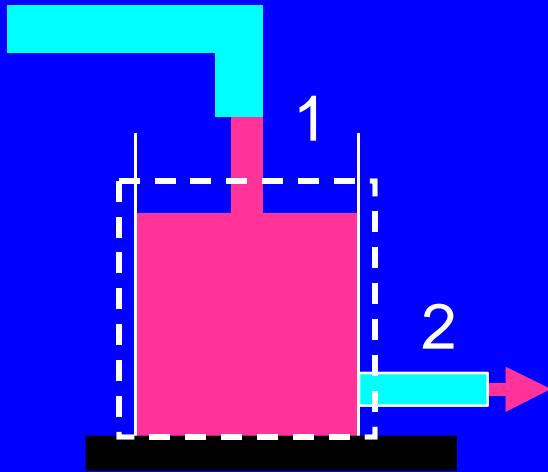


Grain Conveyor Belt





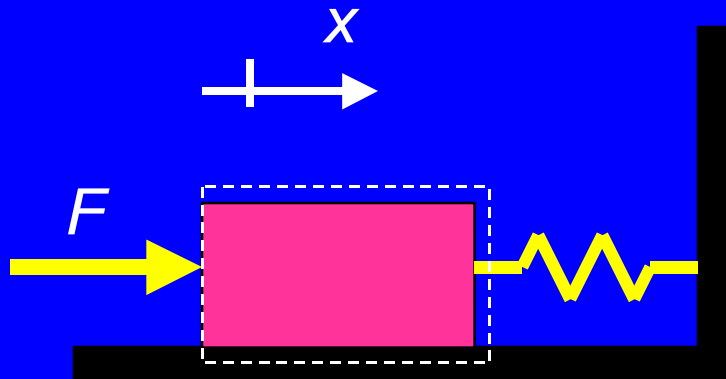




$$\frac{dm_{sys}}{dt} = \dot{m}_1 - \dot{m}_2$$

$$\frac{d}{dt} \left[r A_{\text{tank}} h \right] = \dot{m}_1 - C \sqrt{gh}$$

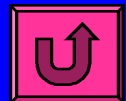
$$\frac{dh}{dt} = \frac{\dot{m}_1}{r A_{\text{tank}}} - \frac{C \sqrt{gh}}{r A_{\text{tank}}}$$



$$\frac{dP_{x,sys}}{dt} = F - \mathbf{m}_k mg - kx$$

$$\frac{d}{dt} \left[m V_x \right] = F - \mathbf{m}_k mg - kx$$

$$m \frac{dV_x}{dt} = \frac{F - \mathbf{m}_k mg - kx}{m}$$



Example - Carnot Cycle Revisited

What is the maximum thermal efficiency of a steady-state heat engine that receives energy by heat transfer at a surface temperature T_H and rejects energy by heat transfer at a surface temperature T_L ?

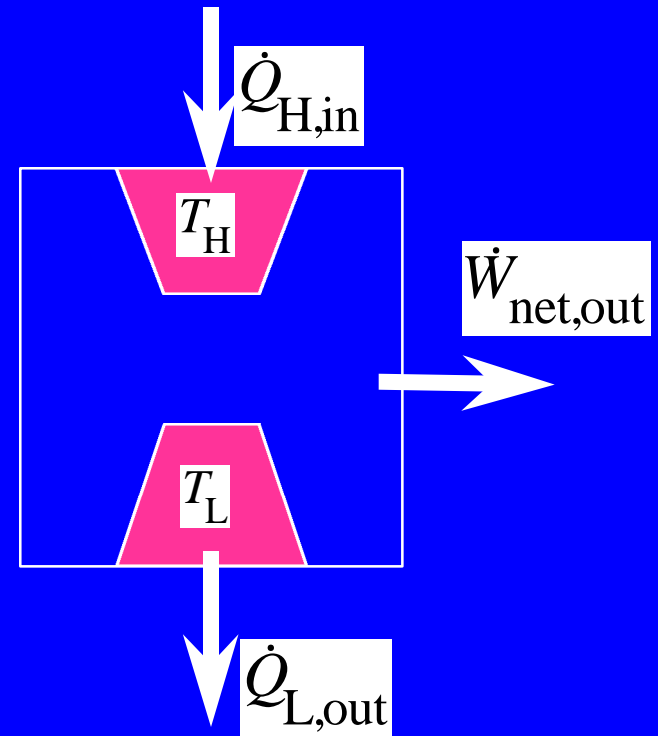
Analysis

What's the system?

What properties should we count?

What is the time interval?

What are the important interactions?



$$\frac{dE_{sys}}{dt} = \overset{0,SS}{\dot{Q}_{net,in}} + \dot{W}_{net,in}$$

$$0 = \left[\dot{Q}_{H,in} - \dot{Q}_{L,out} \right] - \dot{W}_{net,out}$$

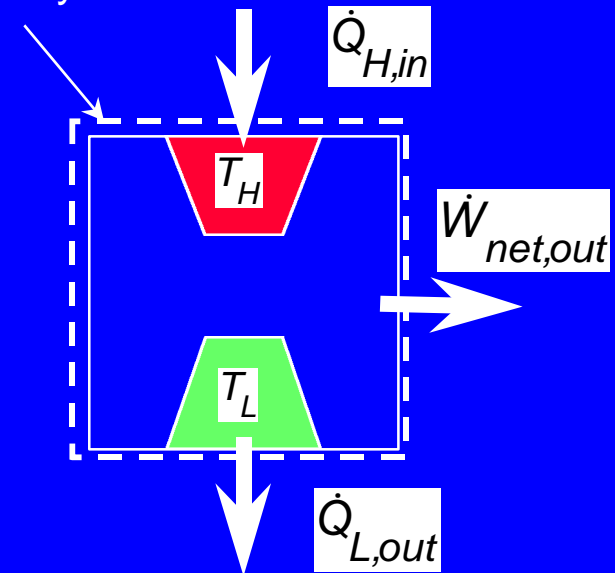
$$\dot{W}_{net,out} = \dot{Q}_{H,in} - \dot{Q}_{L,out}$$

$$\frac{dS_{sys}}{dt} = \overset{0,SS}{\sum_j \frac{\dot{Q}_j}{T_j}} + \dot{S}_{gen}$$

$$0 = \left[\frac{\dot{Q}_{H,in}}{T_H} - \frac{\dot{Q}_{L,out}}{T_L} \right] + \dot{S}_{gen}$$

$$\dot{Q}_{L,out} = \dot{Q}_{H,in} \left(\frac{T_L}{T_H} \right) + T_L \dot{S}_{gen}$$

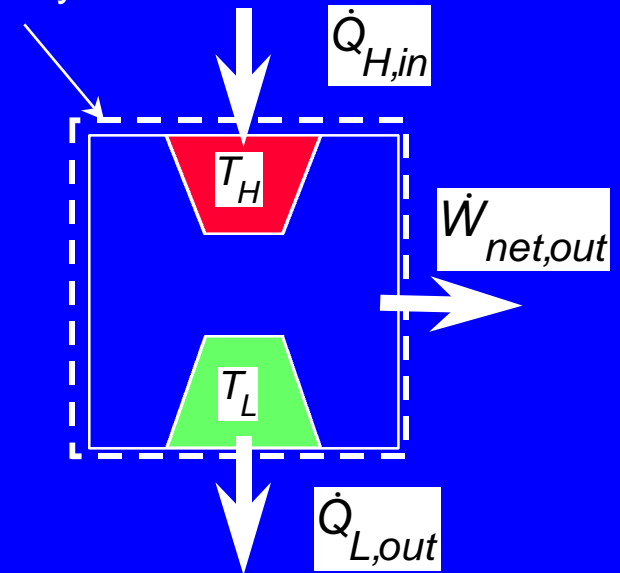
Closed System



$$\dot{W}_{net,out} = \dot{Q}_{H,in} - \left[\dot{Q}_{H,in} \frac{T_L}{T_H} + T_L \dot{S}_{gen} \right]$$

$$h = \frac{\dot{W}_{net,out}}{\dot{Q}_{H,in}} = \left[1 - \frac{T_L}{T_H} \right] - \frac{T_L \dot{S}_{gen}}{\dot{Q}_{H,in}}$$

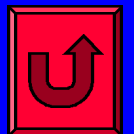
Closed System



$$h = \frac{\dot{W}_{net,out}}{\dot{Q}_{H,in}} = \left[1 - \frac{T_L}{T_H} \right] - \frac{T_L \dot{S}_{gen}}{\dot{Q}_{H,in}}$$

$$h_{max} = \left[1 - \frac{T_L}{T_H} \right]$$

$$\frac{T_L \dot{S}_{gen}}{\dot{Q}_{H,in}} \geq 0$$



Example - Monkeys on a Rope

Three monkeys *A*, *B*, and *C* with masses of 10, 12, and 8 kg, respectively, are climbing up and down the rope suspended from point *D*. At the instant shown in the figure, *A* is descending the rope with an acceleration of 1.6 m/s^2 , and *C* is pulling himself up with an acceleration of 0.9 m/s^2 . Monkey *B* is climbing up with a constant speed of 0.6 m/s .

Determine the tension T in the rope at *D*, in newtons.

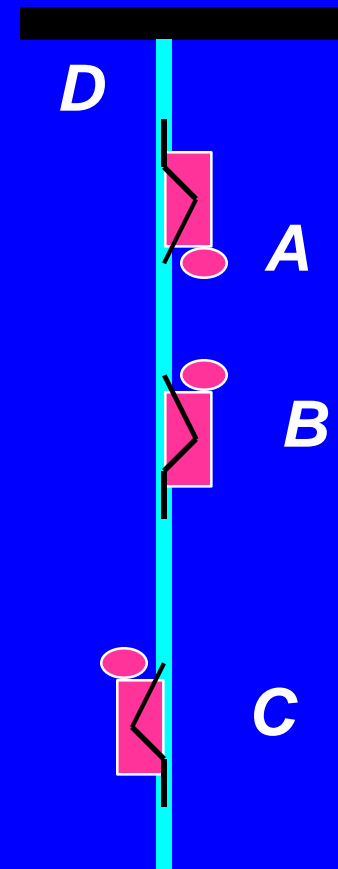
Analysis

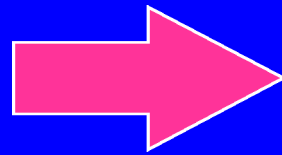
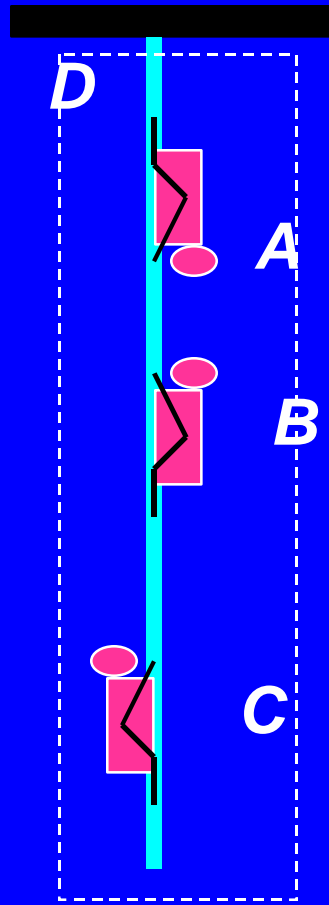
What's the system?

What properties should we count?

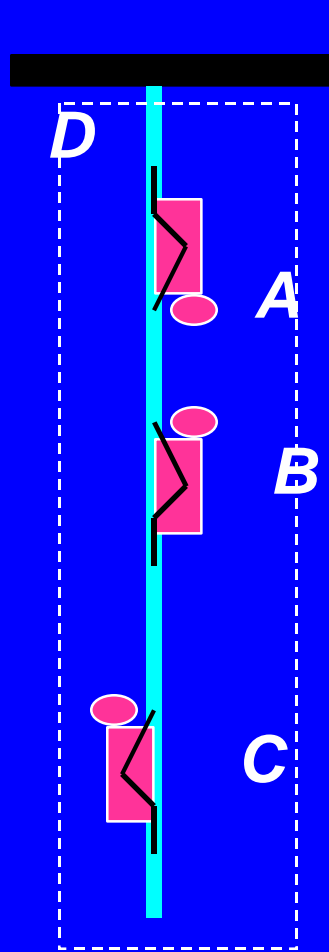
What is the time interval?

What are the important interactions?

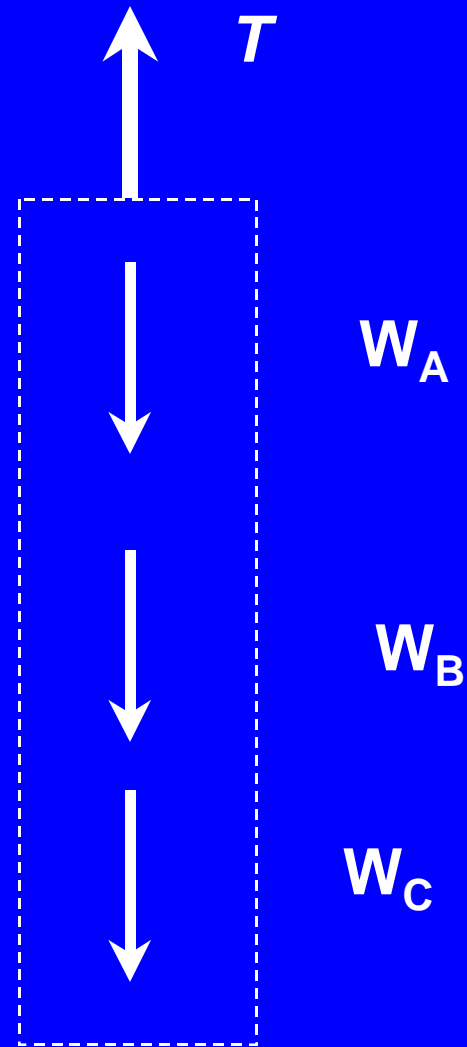
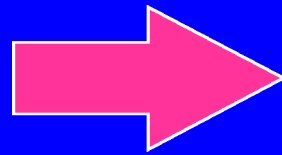




Physical System



Physical System



Free-body Diagram

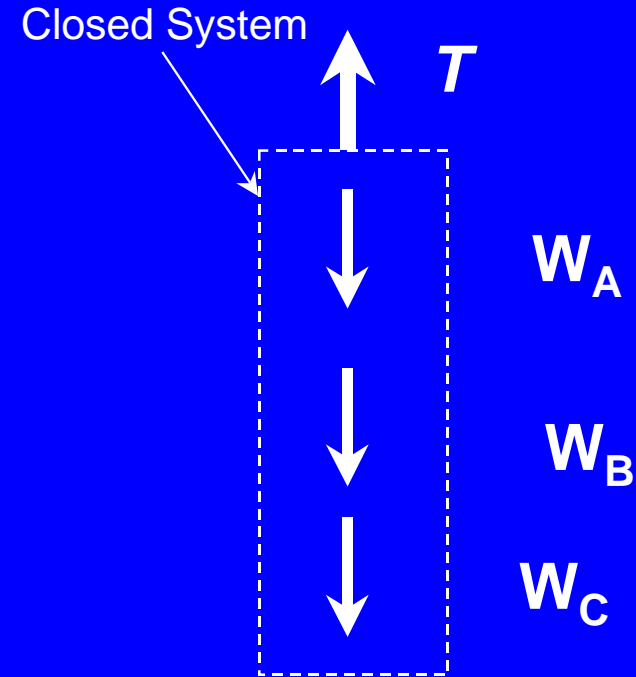
$$\frac{d\vec{P}_{\text{sys}}}{dt} = \sum_j \vec{F}_{\text{ext},j}$$

$$\sum_j \vec{F}_{\text{ext},j} = \vec{W}_A + \vec{W}_B + \vec{W}_C + \vec{T}$$

$$\vec{P}_{\text{sys}} = m_A \vec{V}_A + m_B \vec{V}_B + m_C \vec{V}_C$$

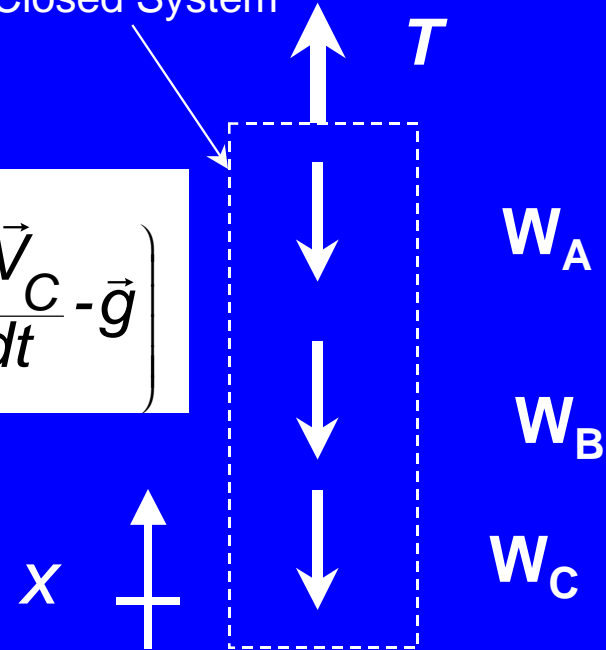
$$\frac{d}{dt} (m_A \vec{V}_A + m_B \vec{V}_B + m_C \vec{V}_C) = \vec{W}_A + \vec{W}_B + \vec{W}_C + \vec{T}$$

$$m_A \left(\frac{d\vec{V}_A}{dt} \right) + m_B \left(\frac{d\vec{V}_B}{dt} \right) + m_C \left(\frac{d\vec{V}_C}{dt} \right) = m_A \vec{g} + m_B \vec{g} + m_C \vec{g} + \vec{T}$$



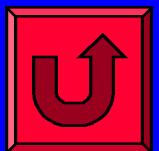
Closed System

$$\vec{T} = m_A \left(\frac{d\vec{V}_A}{dt} - \vec{g} \right) + m_B \left(\frac{d\vec{V}_B}{dt} - \vec{g} \right) + m_C \left(\frac{d\vec{V}_C}{dt} - \vec{g} \right)$$



$$\begin{aligned} T &= (10 \text{ kg}) \left[-1.6 + 9.81 \right] \left(\frac{\text{m}}{\text{s}^2} \right) + (12 \text{ kg}) \left[0 + 9.81 \right] \left(\frac{\text{m}}{\text{s}^2} \right) + (8 \text{ kg}) \left[0.9 + 9.81 \right] \left(\frac{\text{m}}{\text{s}^2} \right) \\ &= 82.1 \text{ N} \quad + \quad 117.7 \text{ N} \quad + \quad 85.6 \text{ N} \end{aligned}$$

$$T = 285.4 \text{ N}$$

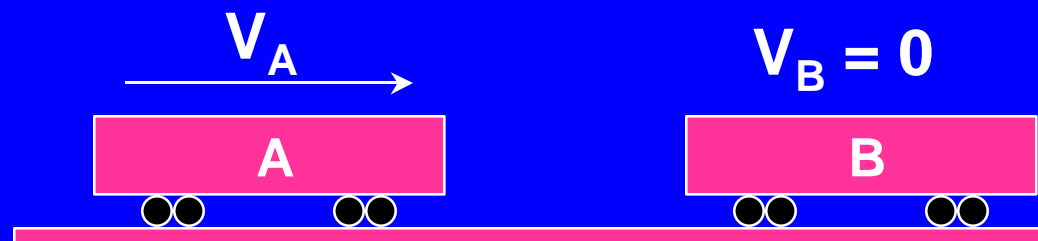


Examples - Rail Cars on the Move

A 45-Mg railroad car moving with a velocity of 3 km/h is to be coupled to a 25-Mg car which is at rest.

Determine

- (a) the final velocity of the coupled cars
- (b) the average impulsive force acting on each car if the coupling is completed in 0.3 s.



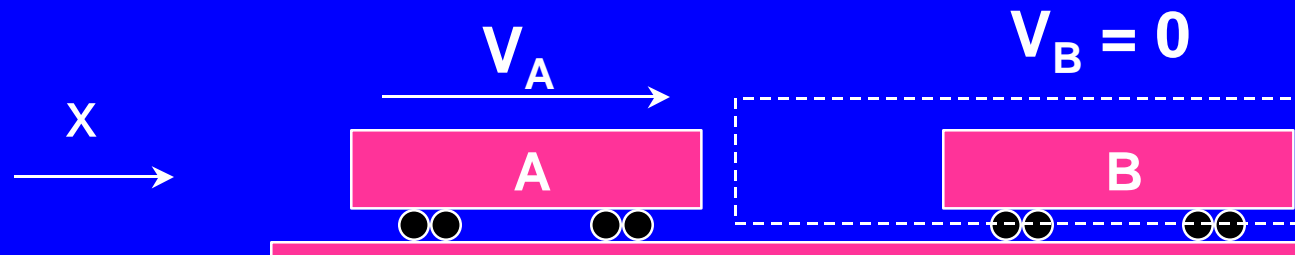
Part (a) - Final velocity after coupling

System: Assume an **open, moving system**.

Initially it contains car *B* only and finally it contains both cars.

Property:

$$\frac{d\vec{P}_{\text{sys}}}{dt} = \sum_j \vec{F}_{\text{ext},j} + \sum_{\text{in}} \dot{m}_i \vec{V}_i - \sum_{\text{out}} \dot{m}_e \vec{V}_e$$



Conservation of
Linear Momentum
(x-direction)

Integrate over time
interval t_1 to t_2 .

- 1 - Initial state
- 2 - Final state

$$V_{B,1} = 0$$

$$\frac{dP_{sys,x}}{dt} = \dot{m}_i V_{x,i}$$

$$\int_{t_1}^{t_2} \left(\frac{dP_{sys,x}}{dt} \right) dt = \int_{t_1}^{t_2} \left(\dot{m}_i V_{x,i} \right) dt$$

$$P_{sys,x,2} - P_{sys,x,1} = m_A V_{A,1}$$

$$(m_A + m_B) V_{AB,2} - \cancel{m_B V_{B,1}}^0 = m_A V_{A,1}$$

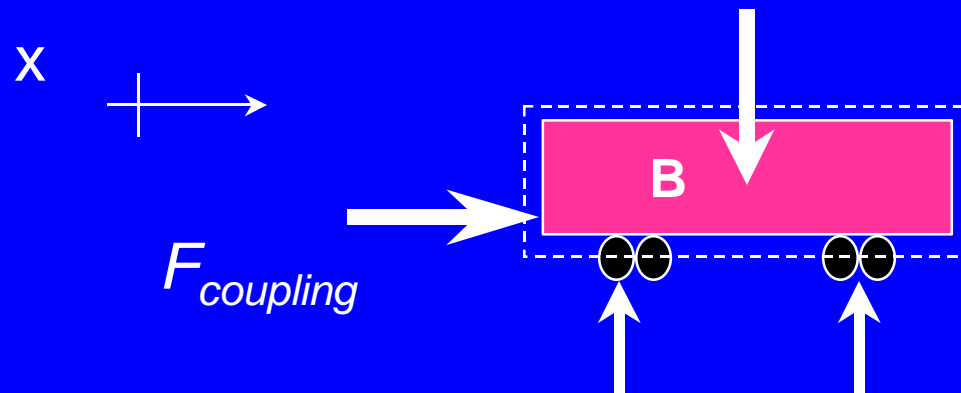
$$V_{AB,2} = \frac{m_A V_{A,1}}{m_A + m_B}$$

Part (b) Coupling Force

System: Assume a **closed system** that only contains car *B* throughout the process. This system moves with car *B*.

Property:

$$\frac{d\vec{P}_{\text{sys}}}{dt} = \sum_j \vec{F}_{\text{ext},j} + \sum_{\text{in}} \dot{m}_i \vec{V}_i - \sum_{\text{out}} \dot{m}_e \vec{V}_e$$



Conservation of Linear Momentum (x-direction)

Integrate over time interval t_1 to t_2 .

1 - Initial state

2 - Final state

$$V_{B,1} = 0$$

$$V_{B,2} = V_{AB,2}$$

from part (a)

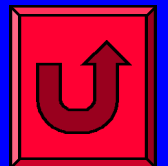
$$\frac{dP_{sys,x}}{dt} = F_x$$

$$\int_{t_1}^{t_2} \left(\frac{dP_{sys,x}}{dt} \right) dt = \int_{t_1}^{t_2} F_x dt$$

$$P_{sys,x,2} - P_{sys,x,1} = F_{x,avg} \Delta t$$

$$m_B V_{B,2} - m_B V_{B,1} = F_{x,avg} \Delta t$$

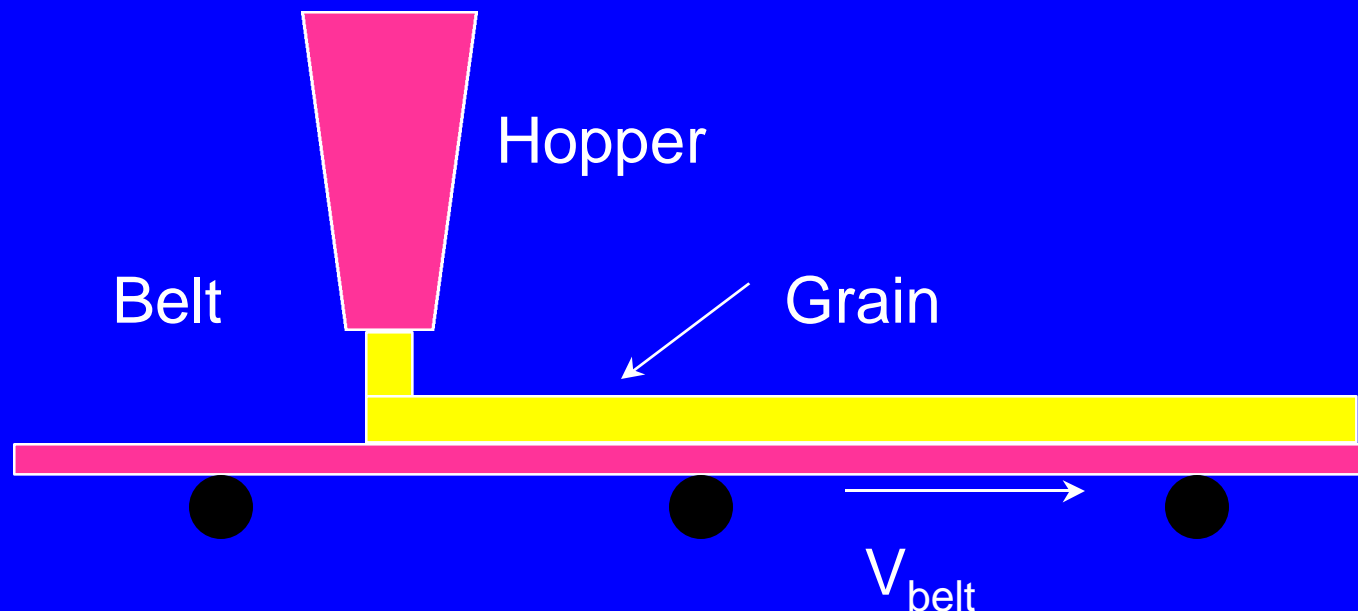
$$F_{x,avg} = \frac{m_B V_{B,2}}{\Delta t}$$

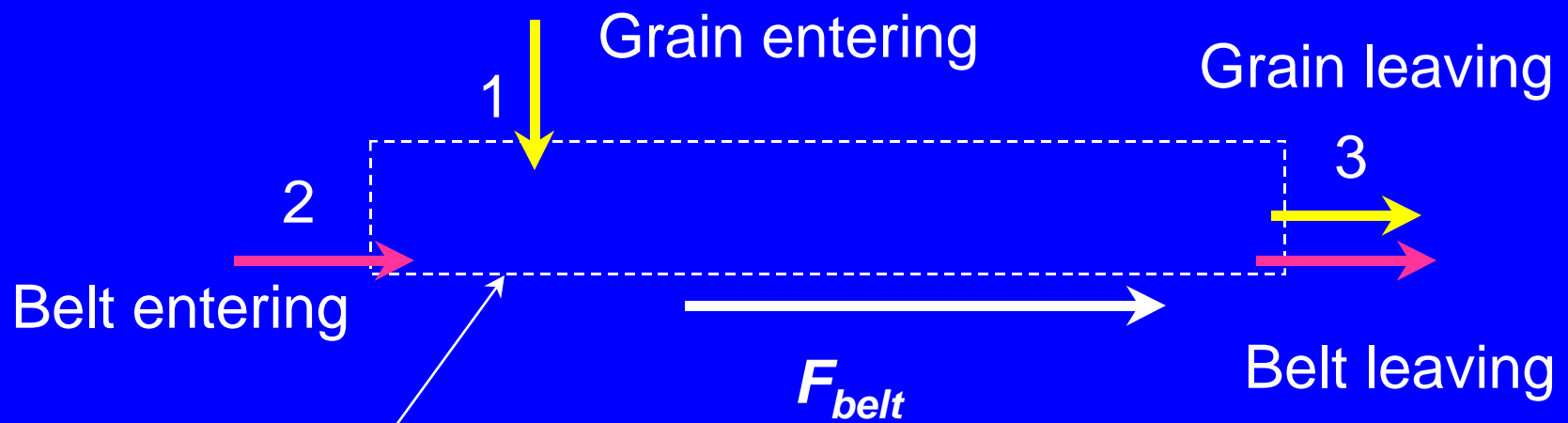
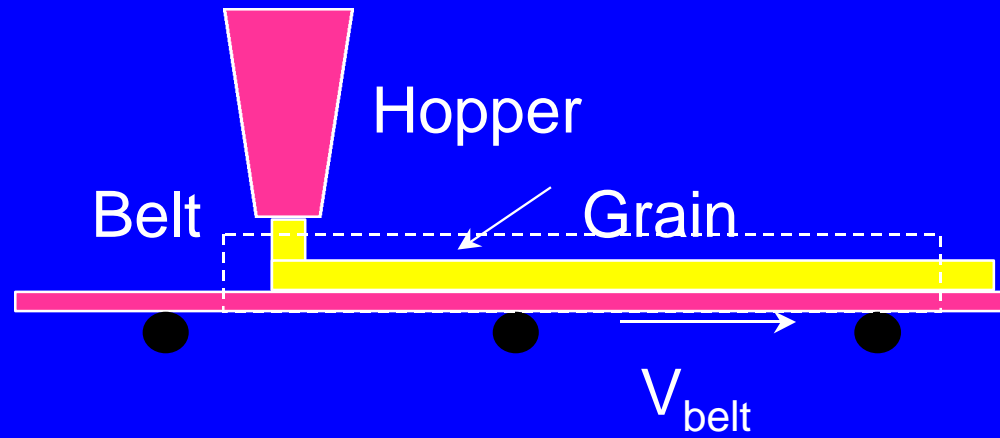


Example - Conveyor Belt

Grain falls from a hopper onto a conveyor belt at the rate of 200 kg/min. The conveyor belt carries the grain away at a constant velocity of 2 m/s.

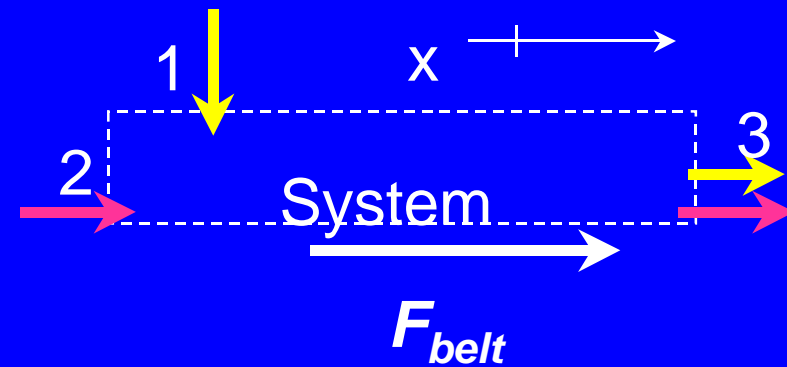
Determine the force on the belt required to keep the belt moving at a constant speed.





Steady-state open system

Conservation of mass
for this system.



$$\frac{dm_{sys}}{dt} = \dot{m}_{grain,1} + \dot{m}_{belt,2} - \dot{m}_{belt,3} - \dot{m}_{grain,3}$$

$$m_{sys} = m_{belt,sys} + m_{grain,sys}$$

0, SS

$$\frac{dm_{belt,sys}}{dt} = \dot{m}_{belt,2} - \dot{m}_{belt,3}$$

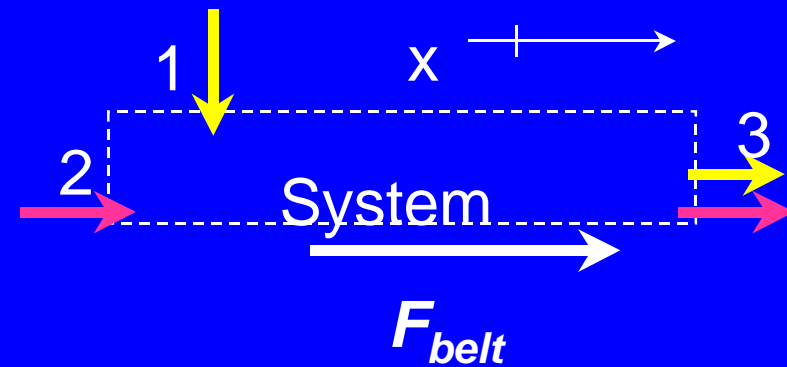
0, SS

$$\frac{dm_{grain,sys}}{dt} = \dot{m}_{grain,1} - \dot{m}_{grain,3}$$

$$\dot{m}_{belt,2} = \dot{m}_{belt,3}$$

$$\dot{m}_{grain,1} = \dot{m}_{grain,3}$$

Conservation of Linear Momentum for this system. (X-direction)



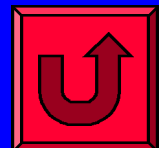
0, SS

$$\frac{dP_{x,sys}}{dt} = \sum_j F_{x,ext,j} + \sum_{in} \dot{m}_i V_{x,i} - \sum_{out} \dot{m}_e V_{x,e}$$

$$0 = F_{belt} + \dot{m}_{grain,1} V_{x,grain,1} + \dot{m}_{belt,2} V_{x,belt,2} - \dot{m}_{belt,3} V_{x,belt,3} - \dot{m}_{grain,3} V_{x,grain,3}$$

$$0 = F_{belt} + \dot{m}_{grain} \left(\cancel{V_{x,grain,1}}^0 - V_{x,grain,3} \right) + \dot{m}_{belt} \left(\cancel{V_{x,belt,2}}^0 - V_{x,belt,3} \right)$$

$$F_{belt} = \dot{m}_{grain} V_{x,grain,3} = \dot{m}_{grain} V_{belt}$$



End of Examples

Implications for curricula and courses

- Can be used as a way to integrate existing courses if instructors work together.
- Can be used as basis for *new* curricula based on *system, conservation and accounting, and modeling paradigm.*

Texas A&M - College Station

Sophomore Curriculum

History of Conservation Principles at TAMU

- 1987 NSF funded a program to unify the Undergraduate Engineering Sciences
- Developed the four sophomore courses (the 20X sequence) comprising “all” the engineering science needed by “all” majors.
- The FC, in response to feedback, modified the material to form 5 courses

Current TAMU Structure

- ENGR 211(3) - Conservation Principles and the Structure of Engineering - Statics and Dynamics
- ENGR 212 (3) - Conservation Principles and the Structure of Engineering - Thermo/Fluid Dynamics
- ENGR 213 (3) - Properties of Materials
- ENGR 214(3) - Conservation Principles of Continuous Media
- ENGR 215 (3) - Principles and Application of Electrical Engineering

Rose-Hulman

Sophomore Engineering Curricula

What is the Rose-Hulman Sophomore Engineering Curriculum?

An eight-course sequence that integrates core material in engineering science and mathematics.

- Designed for all engineering majors.
- Developed by a multi-disciplinary faculty team.
- Taught since 1995-1996.
- Required of all electrical, computer, and mechanical engineering students.

What's our Core?

Diff. Equations I	Dynamics
Fluid Mechanics	Circuits
Thermodynamics	Diff. Equations II
Statistics	System Dynamics

Matrix Algebra

32 Qtr. Credit Hours

Sophomore Engineering Curriculum

Our New Approach

Fall

Diff. Equations &
Matrix Algebra I (4)

Conservation &
Accounting
Principles (4)

Winter

Diff. Equations &
Matrix Algebra II (4)

Fluid & Thermal
Systems (3)

Electrical
Systems (3)

Mechanical
Systems (3)

Spring

Statistics for
Engineers (4)

Analysis & Design
of Engineering
Systems (5)

30 Qtr. Credit Hours

Sophomore Engineering Curriculum

Advantages for Students

- Participate in a coordinated curriculum that consciously stresses the links between engineering science and mathematics.
- Provide a common foundation of engineering science and mathematics knowledge for future learning.
- Learn to apply a common framework for problem solving based upon an understanding of the conservation and accounting principles.
- Learn to handle open-ended problems.
- Work with multi-discipline problems.
- Learn cooperatively and work in teams.
- Use computer technology across the curriculum.

Sophomore Engineering Curriculum

A Brief History

Fall 1993

- Foundation Coalition funded by NSF.

1993-1994

- Institute considered various ideas for Sophomore Curriculum (Friday afternoon meetings)

Summer 1994

- Workshops on teaming, active learning, curriculum design. (Approximately 4 days total)
- Multidisciplinary faculty team developed overall framework for SEC. (12 faculty)

Sophomore Engineering Curriculum

A Brief History

1994-1995

- Met with departments and finalized proposal.
- Proposal for pilot approved by Institute.
- Required by electrical and computer engineering department.

Summer 1995

- Team of 12 faculty and 3 students developed detailed curriculum material for eight courses.

Sophomore Engineering Curriculum

A Brief History

1995-1996

- Offered RH/FC SEC for first time to 90 students
- Rose-Hulman required students to purchase a laptop computer.

1996-1997

- Adopted by mechanical engineering department for Fall 1998.

2000-2001

- Currently taken by 220-230 mechanical, electrical, and computer engineering students.

Sophomore Engineering Curriculum

Curriculum Structure

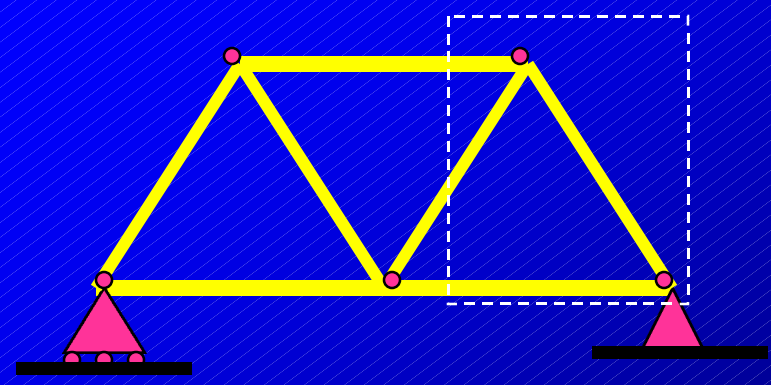
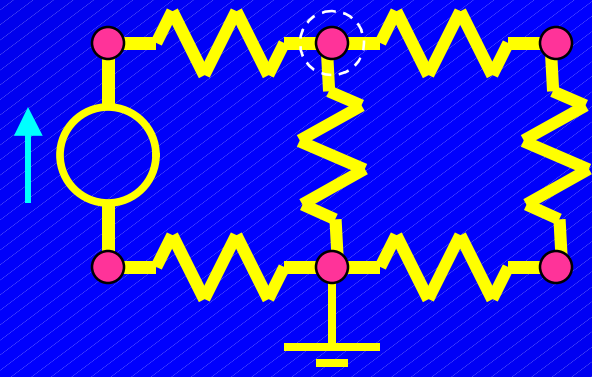
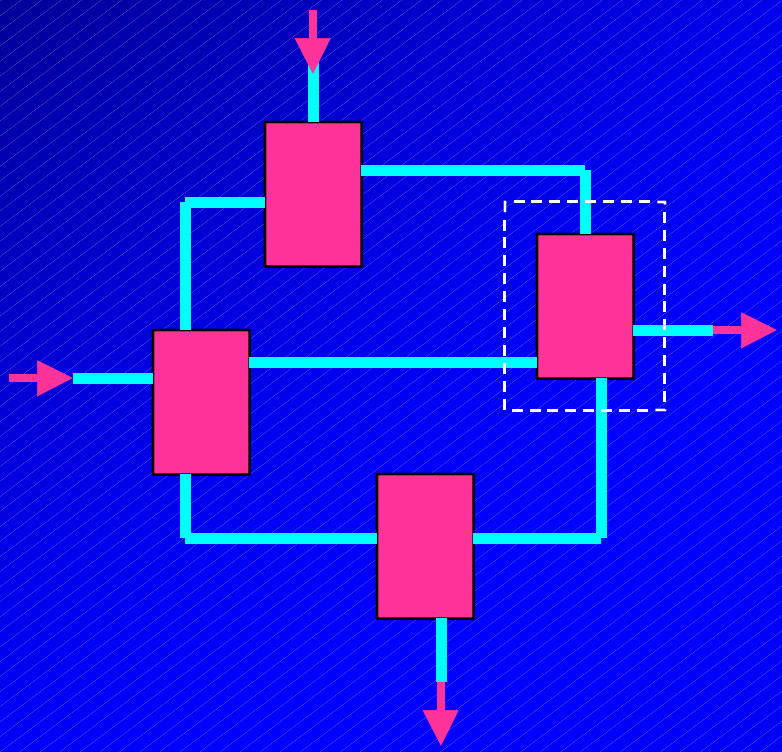
FALL Quarter	8 Credit Hours
MA 211 - Applied Mathematics I (4)	
ES 201 - Conservation & Accounting Principles (4)	
WINTER Quarter	13 Credit Hours
MA 213 - Applied Mathematics III (4)	
ES 202 - Fluid & Thermal Systems (3)	
ES 203 - Electrical Systems (3)	
ES 204 - Mechanical Systems (3)	
SPRING Quarter.	9 Credit Hours
MA 223 - Engineering Statistics (4)	
ES 205 - Analysis & Design of Engineering Systems (5)	
TOTAL CREDITS	30 Credit Hours

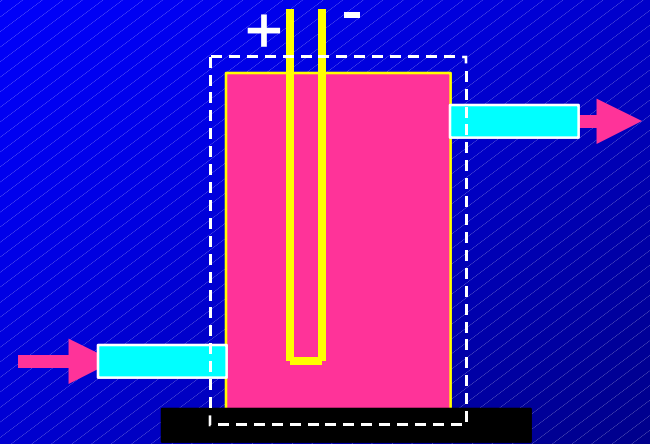
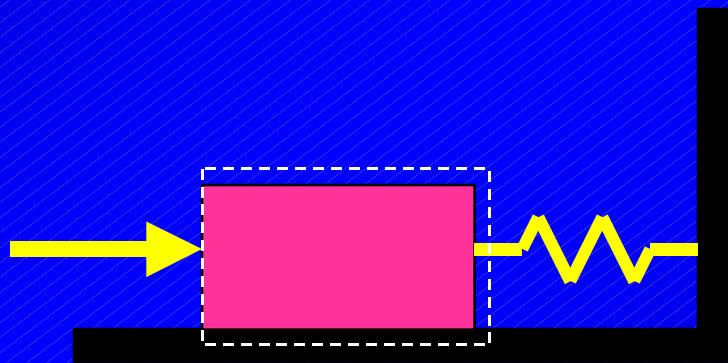
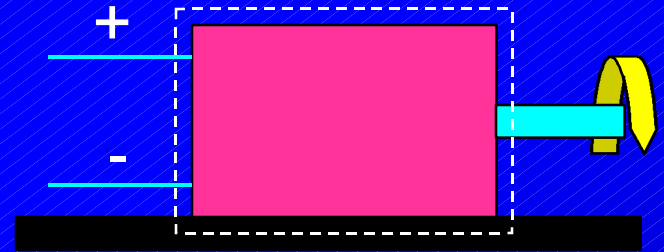
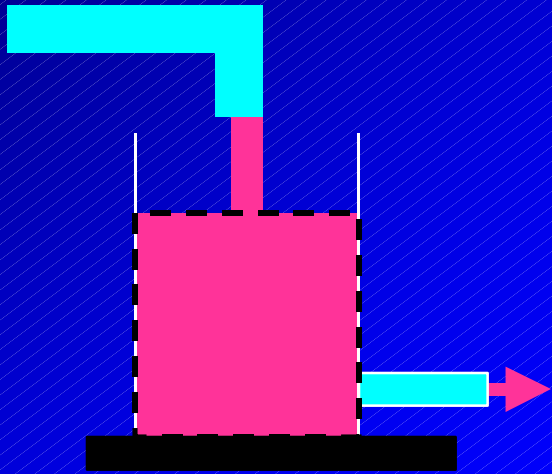
ES 201
*Conservation & Accounting
Principles*

Fall Quarter - 4 credits

Conservation & Accounting Principles

- Basic Systems, Accounting, and Modeling Concepts
- Laws
 - Conservation Laws: Mass, Charge, Energy, Linear & Angular Momentum
 - Accounting Principle: Entropy
- Simple open and closed systems





ES 202
Fluid & Thermal Systems

Winter Quarter - 3 credits
Shared 3-hr Laboratory

Fluid & Thermal Systems

- Thermodynamic Properties
 - Pure simple compressible substances
 - Gases: ideal gas & Z-Chart
 - Solids/Liquids: incompressible substance
- Applications to Open and Closed Systems
- Simple Cycles

Fluid & Thermal Systems

- Dimensional Analysis
- Mechanical Energy Equation
 - Bernoulli Equation
 - Pipe Flow of Incompressible Fluids
 - Pump/Turbine Efficiencies
- Lift and Drag
- Hydrostatics

Fluid & Thermal Systems

Laboratory Experiences

Lab 1 - Dimensional Analysis

Lab 2 - Torricelli's Principle, Friction Factors, Water-Wall Exhibit

Lab 3 - Back-pressure steam turbine

ES 203
Electrical Systems

Winter Quarter - 3 credits

Shared 3-hr Laboratory

Electrical Systems

- Circuit Elements
- Kirchhoff's Laws
- Equivalent circuits and Voltage and current dividers
- Operational amplifiers
- First, second, and higher order circuits
- Transient and steady-state behavior
- AC circuits and power

ES 204
Mechanical Systems

Winter Quarter - 3 credits

Shared 3-hr Laboratory

ES204 - Mechanical Systems

- More Kinematics
 - Normal-Tangential coordinates
 - Radial - Transverse coordinates
 - Dependent motion
 - Relative motion
 - Rigid bodies
- Impacts (coefficient of restitution)

Mechanical Systems (cont.)

- Use Working Model, Maple, Concept maps
- Three labs
- Immediate application to kinetics problems
- Combination problems

Assessment - Is it worse?

- Year 2 - Gave 17 identical multiple choice and 1 identical workout problem to ES204 and to dynamics students
 - 4 ES204 sections/3 professors
 - 5 Dynamics sections/3 professors
- Year 3 - Gave identical finals to ES204 and to dynamics students (20 multiple choice, 3 workout)
 - 4 ES204 sections/2 professors
 - 5 Dynamics/3 professors

Year 2 - Multiple Choice

Prob. #	First Assessment			Second Assessment		
	SEC - ES204	Dynamics	Difference	SEC - ES204	Dynamics	Difference
1	45.7	43.0	2.7	40.2	32.0	8.2
2	24.7	48.6	-23.9	56.3	61.0	-4.7
3	88.9	90.8	-2.0	94.3	94.0	0.3
4				87.4	81.0	6.4
5	80.2	45.8	34.5	71.3	56.0	15.3
6	72.8	66.9	5.9	82.8	79.0	3.8
7	91.4	62.7	28.7	82.8	76.0	6.8
8	59.3	47.2	12.1	57.5	55.0	2.5
9	87.7	85.2	2.4	87.4	94.0	-6.6
10	74.1	28.9	45.2	78.2	49.0	29.2
11	95.1	95.8	-0.7	90.8	93.0	-2.2
12	48.1	33.8	14.3	46.0	57.0	-11.0
13				96.6	98.0	-1.4
14	92.6	88.0	4.6	90.8	95.0	-4.2
15	90.1	80.3	9.8	66.7	63.0	3.7
16				62.1	54.0	8.1
17	61.7	52.1	9.6	50.6	79.0	-28.4
18	45.7	39.4	6.2	41.4	47.0	-5.6
19				9.2	47.0	-37.8
20	71.6	44.4	27.2	63.2	56.0	7.2

*Workout problems**

Year 2			
Prob. #	SEC - ES204	Dynamics	Difference
1	33.3	23.3	10

Year 3			
Prob. #	SEC - ES204	Dynamics	Difference
1	35.8	17	19.8
2	70.1	22	48.1
3	46	6	40

* Essentially an “A” solution

ES 205
*Analysis & Design
of Engineering Systems*

Spring Quarter - 5 credits
3-hr Laboratory

ES205 - Analysis & Design of Engineering Systems

- Pre-vibrations/controls
- Mechanical, Electrical , Electro-mechanical, Hydraulic, Fluid, Thermal systems
- Governing differential equations
- System Response
- System identification

Systems Concepts in ES205

- Modeling of system elements
- Equations of motion
 - Natural frequency, Damping ratio, Static gain
 - 2nd order matrix form, state space form
- Transfer functions
- Free response
 - log decrement

Systems Concepts in ES205

(cont.)

- Forced Response
 - Step input
 - performance specifications
 - Harmonic input
 - Frequency response plots
 - General periodic forcing
 - Fourier Series
- Simulink, Matlab and Maple

Analysis & Design of Engineering Systems

Laboratory

- Introduction to the design process.
- Teams of students study and develop *design specifications*** for products.
- Includes written and oral presentations.

** S. Pugh. *Total Design*, Addison Wesley, 1991.

K. T. Ulrich and S. D. Eppinger. *Product Design and Development*, McGraw-Hill, 1995.

Mathematics Sequence

- Differential Equations & Matrix Algebra I
- Differential Equations & Matrix Algebra II
- Statistics for Engineers

Sophomore Engineering Curriculum

Mathematics

- Stresses Linear Structures
 - systems of algebraic equations ($Ax=b$)
 - 1st & 2nd order differential equations
 - systems of differential equations
 - Laplace transforms
 - Fourier series
 - linearization
- Applications of Statistics
- Students have laptops with access to MAPLE, MATLAB, and MINITAB.

Differential Equations & Matrix Algebra I

- Basic Matrix Algebra
 - systems of linear equations (algebraic and geometrical viewpoints)
 - least squares
 - eigenvalues and eigenvectors
- Differential Equations
 - Review of first-order de's
 - Second-order linear de's with constant coefficients (homogeneous and non-homogeneous cases)
- Introduction to Complex Arithmetic

Differential Equations & Matrix Algebra II

- Laplace Transforms
- Systems of First-Order Linear DE's
 - solution using Laplace transforms
 - investigation of solution structure determined by eigensystems.
- Phase Portrait Analysis and Stability of Critical Points for Systems of Equations
- Approximation of Functions
 - Taylor and Fourier series

Statistics for Engineers

- Introductory course in statistical data analysis emphasizing
 - hypothesis testing
 - analysis of variance
 - quality control charts
 - simple and multiple regression
 - simple experimental designs
- Computer Tools: MINITAB and Excel

Sophomore Engineering Curriculum

Assessment Activities

- Standard Rose-Hulman Course Evaluation
- Feedback from Student Council
- ES201 / MA211 Course Survey
- Focus Groups
- Sample EIT/FE Exam
- Comparison of performance on standard final exam test questions.
- Anecdotal information from upper-division courses.
- Sophomore surveys
- Survey of graduating seniors

Student Comments after Completing the SEC

Student A

“ES201 was an excellent foundation to start on. A solid handle on this class is a must for success in the following classes. All classes were connected to this class.”

Student Comments

Student B

“The sophomore curriculum has won me over. At first, I thought it was a complete waste of time. Then during winter quarter I saw the importance of it. Now, I am glad to have gone through it. The book didn’t help much, it was vague and made the class more difficult.”

Student Comments

Student C

“I was very pessimistic about the course (ES205) at the beginning of the quarter. This course defeated every pessimistic premise I had before it was completed. This course brought all the engineering disciplines together and, at the very least, made this skeptical EE a believer in the SEC. Not only was the course an eye-opener, but it also enhanced my ability to solve general complex-system problems regardless of what discipline they came from.?”

Thank You !

For further information about Sophomore
Engineering Curricula -----

Check the Foundation Coalition Web Site --

<http://www.foundationcoalition.org>

Contact Don Richards --

<http://www.rose-hulman.edu/~richards>

donald.e.richards@rose-hulman.edu