

# PH112 PHYSICS EQUATIONS

$$\theta = \frac{s}{r}$$

$$\omega = \frac{d\theta}{dt}$$

$$\alpha = \frac{d\omega}{dt}$$

$$\theta_f = \theta_i + \omega_i t + \frac{1}{2}\alpha(\Delta t)^2$$

$$\omega_f = \omega_i + \alpha\Delta t$$

$$\omega_f^2 = \omega_i^2 + 2\alpha\Delta\theta$$

$$v = R\omega \quad a = R\alpha$$

$$|\vec{A} \times \vec{B}| = AB \sin(\theta)$$

$$\vec{\tau} = \vec{r} \times \vec{F}$$

$$\tau = rF \sin(\phi)$$

$$\Sigma \tau = I\alpha$$

$$L = \Sigma m_i r_i^2$$

$$L_p = I_{cm} + Md^2$$

$$\vec{L} = \vec{r} \times \vec{p}$$

$$\vec{L} = I\vec{\omega}$$

$$K_{rot} = \frac{1}{2}I\omega^2$$

$$x(t) = A \cos(\omega t + \phi_0)$$

$$v_{MAX} = \omega A$$

$$\omega = \sqrt{\frac{k}{m}}$$

$$\omega = \frac{2\pi}{T} = 2\pi f$$

$$E = \frac{1}{2}kA^2$$

$$T = 2\pi\sqrt{\frac{l}{g}}$$

$$D(x, t) = A \sin[kx - \omega t + \phi_0]$$

$$v = \frac{\omega}{k} = \lambda f \quad v = \sqrt{\frac{T_s}{\mu}}$$

$$D(x, t) = [2a \sin(kx)] \cos(\omega t)$$

$$f = \frac{v}{\lambda} = m \frac{v}{2L} \quad k = \frac{2\pi}{\lambda}$$

$$\vec{F}_{1on2} = k \frac{q_1 q_2}{r_{12}^2} \hat{r}_{12}$$

$$\vec{E} = \frac{\vec{F}}{q_o} \quad E = \frac{1}{4\pi\epsilon_o} \frac{q}{r^2}$$

$$E_{rod} = \frac{|Q|}{4\pi\epsilon_o r \sqrt{r^2 + (L/2)^2}}$$

$$E_{ring} = \frac{1}{4\pi\epsilon_o} \frac{zQ}{(z^2 + R^2)^{3/2}}$$

$$E_{disk} = \frac{\eta}{2\epsilon_o} \left[ 1 - \frac{z}{\sqrt{z^2 + R^2}} \right]$$

$$E = \frac{1}{4\pi\epsilon_o} \frac{p}{z^3}$$

$$\vec{F} = q\vec{E}$$

$$E_x = -\frac{\partial V}{\partial x} \quad E_y = -\frac{\partial V}{\partial y} \quad E_z = -\frac{\partial V}{\partial z}$$

$$\Phi = \int \vec{E} \cdot d\vec{A}$$

$$\Phi_c = \oint \vec{E} \cdot d\vec{A} = \frac{Q_{enclosed}}{\epsilon_o}$$

$$\lambda = Q/L \quad \eta = Q/A \quad \rho = Q/V$$

$$E = \frac{\eta}{2\epsilon_o} \quad E = \frac{1}{4\pi\epsilon_o} \frac{2\lambda}{r}$$

$$E = \frac{\eta}{\epsilon_o} \quad V = Ed$$

$$V = \frac{U}{q_o} \quad V = \frac{1}{4\pi\epsilon_o} \frac{q}{r}$$

$$\Delta V = V_f - V_i = -\int_i^f \vec{E} \cdot d\vec{s}$$

$$V_{Total} = \frac{1}{4\pi\epsilon_o} \sum_{i=1}^n \left( \frac{q_i}{r_i} \right)$$

$$V = \frac{1}{4\pi\epsilon_o} \int \frac{dq}{r}$$

$$U = \frac{1}{4\pi\epsilon_o} \frac{q_1 q_2}{r}$$

$$Q = C\Delta V_C \quad C = \frac{\epsilon_o A}{d}$$

$$C = 4\pi\epsilon_o \frac{R_1 R_2}{R_2 - R_1}$$

$$C = 2\pi\epsilon_o \frac{L}{\ln(R_2 / R_1)}$$

$$C_{eq} = \sum_{j=1}^n C_j \quad \frac{1}{C_{eq}} = \sum_{j=1}^n \frac{1}{C_j}$$

$$U = \frac{Q^2}{2C} = \frac{1}{2} C \Delta V^2$$

$$v_d = \frac{e\tau}{m_e} E \quad i = nAv_d$$

$$I = \frac{dq}{dt} = ei$$

$$J = \frac{I}{A} = \sigma E = nev_d$$

$$\sigma = \frac{1}{\rho} = \frac{ne^2\tau}{m_e}$$

$$R = \frac{\rho L}{A} \quad \Delta V_R = IR$$

$$R_{eq} = \sum_{j=1}^n R_j \quad \frac{1}{R_{eq}} = \sum_{j=1}^n \frac{1}{R_j}$$

$$P = I\Delta V = \frac{\Delta V^2}{R} = I^2 R$$

$$u = \frac{1}{2} \epsilon_o E^2$$

$$q(t) = q_o \left( e^{-t/RC} \right)$$

$$q(t) = C\mathcal{E} \left( 1 - e^{-t/RC} \right)$$

$$K_{max} = eV_{stop} = hf - E_0$$

$$E = hf \quad c = f\lambda \quad E_0 = hf_0$$

$$\lambda = h/p = h/mv$$

| Physical Constants: |  |
|---------------------|--|
| k                   | = 1/4πϵ <sub>o</sub>   |
| ϵ <sub>o</sub>      | = 8.854 x 10 <sup>-12</sup> C <sup>2</sup> /N.m <sup>2</sup> |
| e                   | = 1.602 x 10 <sup>-19</sup> C                                |
| m <sub>e</sub>      | = 9.11 x 10 <sup>-31</sup> kg                                |
| m <sub>p</sub>      | = 1.67 x 10 <sup>-27</sup> kg                                |
| c                   | = 3.00 x 10 <sup>8</sup> m/s                                 |
| h                   | = 6.626 x 10 <sup>-34</sup> J.s                              |