

Name _____ Section _____

ES205
Examination III
May 16, 1997

Problem	Score
1	/25
2	/25
3	/25
4	/25
Total	/100

Show all work for credit
AND
Turn in your signed help sheet

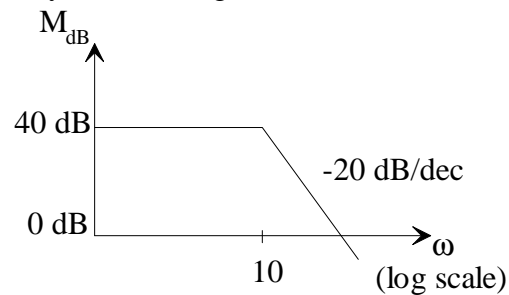
For problems 1.1-1.10 show all work for credit where appropriate (2.5 pts/part)

1.1 A mechanical system which has a natural frequency ω_n and a damping ratio ζ is subjected to a forced excitation frequency ω . At steady state, the system will vibrate at

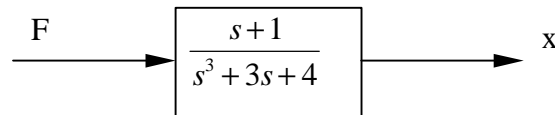
- a) ω_n b) ω_d c) $\omega_n \sqrt{1-\zeta^2}$ d) ω e) none of the above

1.2 A straight-line asymptotic magnitude plot, a.k.a. Bode magnitude diagram, for a system is shown below. Circle the transfer function that would yield this diagram.

- a) $TF = \frac{40}{\frac{s}{10} + 1}$ b) $TF = \frac{10}{10s + 1}$
 c) $TF = \frac{1000}{s + 10}$ d) $TF = \frac{10}{\frac{s}{40} + 1}$
 e) $TF = \frac{1000}{10s + 1}$ f) none of the above



1.3 What differential equation is represented by the following transfer function?



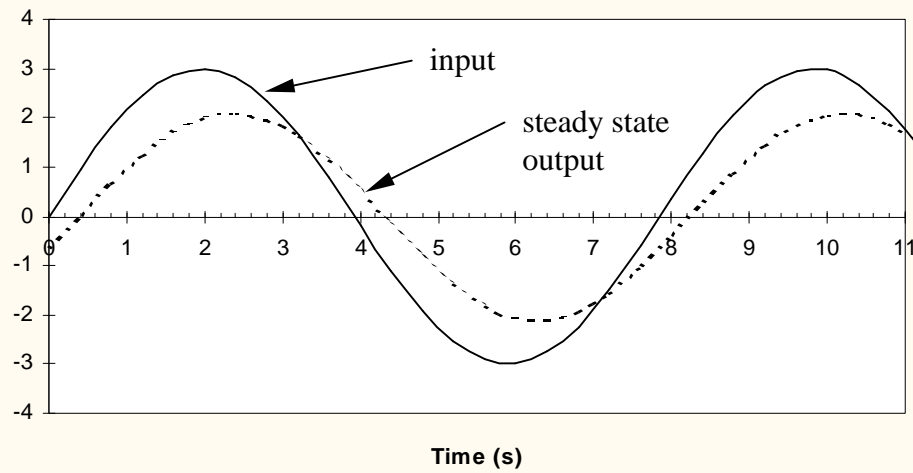
1.4 A step input of magnitude 2 is applied to a second order system described by the EOM $3\ddot{x} + 6\dot{x} + 12x = 36f(t)$. What is the amplitude of the output at steady state?

- a) 2.0 b) 6.0 c) 24.0 d) 72.0 e) none of the above

1.5 A harmonic input $f(t) = 2 \sin(4t)$ is applied to a first order system described by the EOM $6\dot{x} + 3x = 12f(t)$. What is the amplitude of the output at steady state?

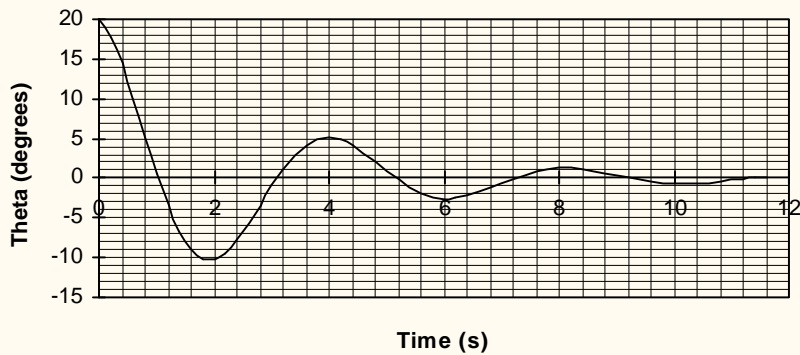
- a) 1.0 b) 2.0 c) 3.0 d) 8.0 e) 24.0

1.6 A first order system is excited harmonically and the input and steady-state output are shown below. What is the phase angle in radians between the input and the output. Circle the best answer.



- a) -0.32 rad b) -0.4 rad c) -0.051 rad d) -0.71 rad

Use the free response of a second order system shown below for problems 1.7-1.9

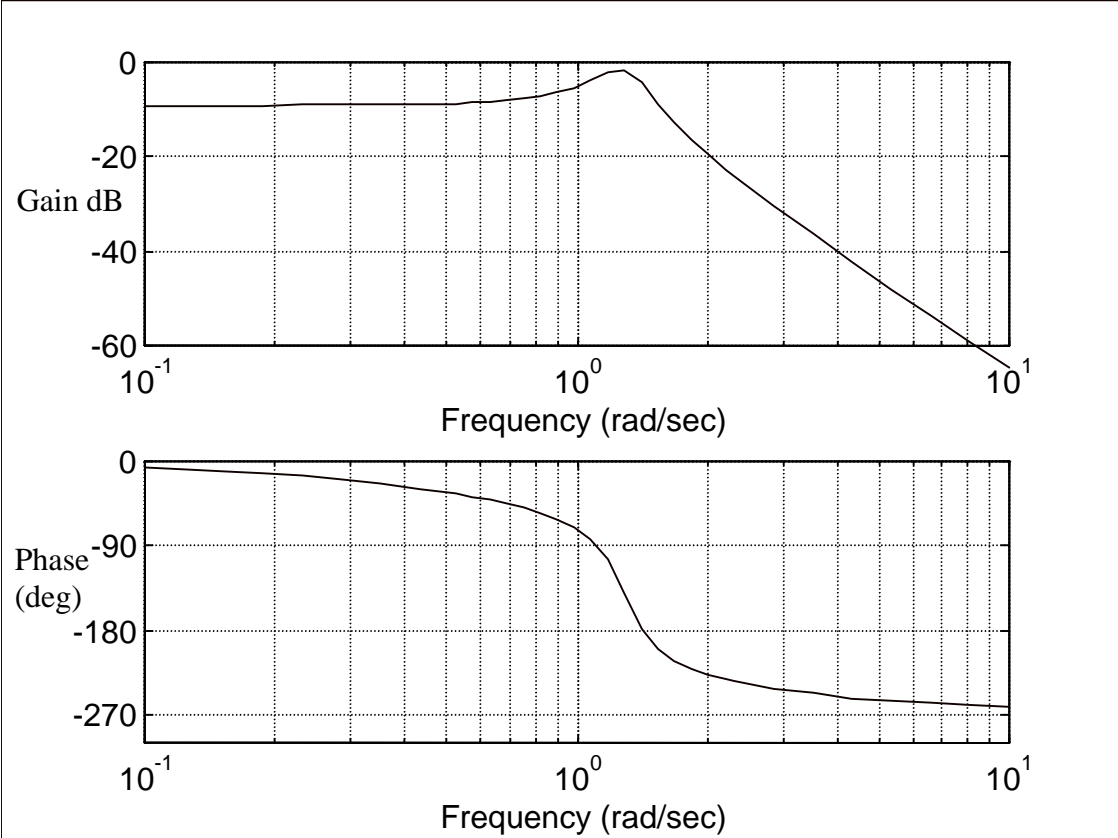


1.7 What is the log decrement?

1.8 What is the damping ratio?

1.9 What is the natural frequency?

1.10 The frequency response plots for a system are shown below. If this system is forced with $F(t) = 10\sin(2t)$ what is the steady state response?



- a) $0.1 \sin(2t-225^\circ)$
- b) $0.3 \sin(2t-240^\circ)$
- c) $1.0 \sin(2t-225^\circ)$
- d) $10 \sin(2t)$
- e) $10 \sin(2t-225^\circ)$
- f) $-200 \sin(2t-225^\circ)$

An electro-mechanical system was modeled and the following differential equations were derived using conservation principles. The system has two inputs r_1 and r_2 and one output c .

$$k_0 \dot{x} + x = k_1(r_1 - z)$$

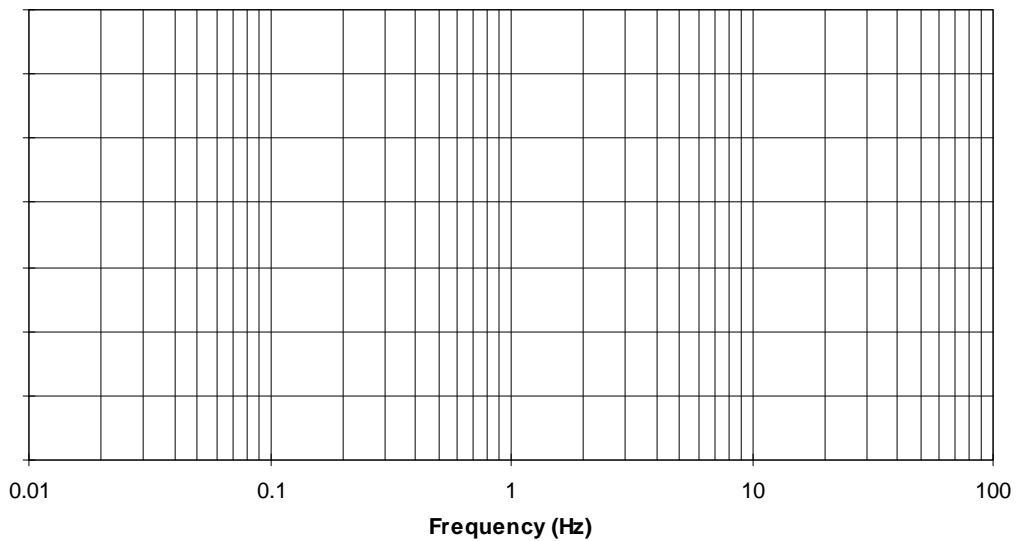
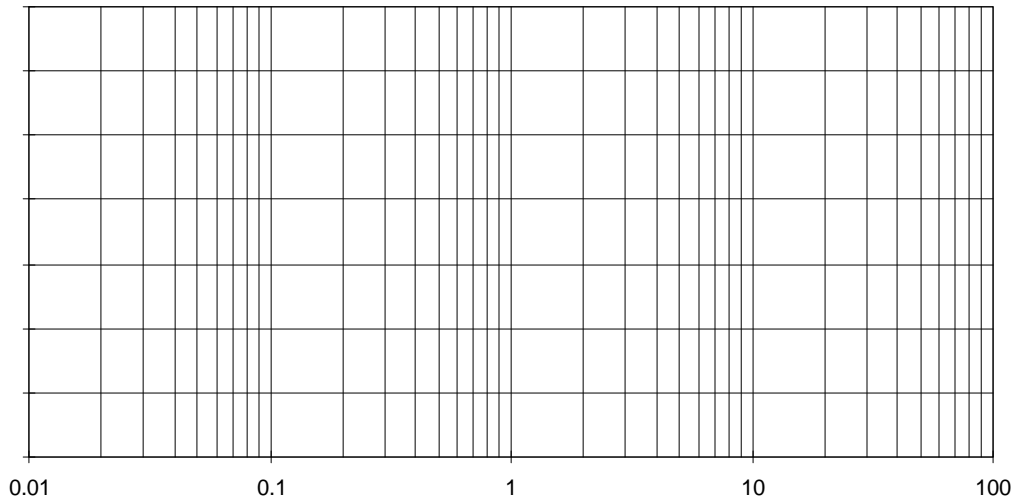
$$c = r_2 + x$$

$$k_2 \dot{z} = k_3 c$$

Draw the block diagram for this electro-mechanical system. Note: x and z are intermediate variables.

Sketch the straight line asymptotic frequency response plots for the following transfer function. Use the semi-log graph paper provided for this purpose. Be sure to show all your work for credit.

$$TF(s) = \frac{-5000(s+0.1)^2}{s^2(s+5)}$$



You have been hired to design a spring and a damper for an amusement park gate. The gate has already been purchased and consists of a concentrated mass M at the end of the bar and a distributed mass m as shown below. The mass moment of inertia of the gate about its hinge is found to be $I_0=80 \text{ kg}\cdot\text{m}^2$. Determine the values of the torsional spring constant, k_t , and the torsional viscous damper, C_t , required to meet the following performance specifications when it is released from rest from an initial position of $\theta = 75$ degrees. The equation of motion is: $I_0\ddot{q} + C_t\dot{q} + k_tq = 0$

Performance Specifications:

- The percent overshoot should be less than 15%
- The time to reach the first peak should be less than 0.5 seconds
- The time to reach 2% of the final resting position should be less than 2 seconds