ECE-420 Exam 1 **Fall 2015**

Calculators and Laptops cannot be used. You must show your work to receive credit.

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Total _____

1a) Use long division to determine the first three nonzero terms in the impulse response for the following transfer function $H(z) = \frac{z+1}{z^2+z+1}$

1b) Assume a system has impulse response $h(n) = (0.5)^n u(n)$ Determine the output if the input is $x(n) = 2\delta(n) - 3\delta(n-2)$

2) Assume we have a process which we expect to be able to model as $g(t) = \alpha t + \beta$. We perform an experiment and determine values for g(t) for a number of different values of *t*, so we have the values

$$\begin{array}{ll}t_{0}, & g(t_{0})\\ t_{1}, & g(t_{1})\\ t_{2}, & g(t_{2})\\ t_{3}, & g(t_{3})\\ t_{4}, & g(t_{4})\end{array}$$

We want to estimate α and β using a least squares type of approach, with the model z = Aw. Describe how you would do this. Be sure in your description, to indicate what the z, w, and A are in terms of the values given t_i , $g(t_i)$ [1

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3) Determine the rank of each of the following matrices (just write the number):

 $\begin{bmatrix} 1 & 0 & 2 \\ 0 & 2 & 1 \end{bmatrix}$ $\begin{bmatrix} 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 \end{bmatrix}$ $\begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$ $\begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & -1 \\ 0 & 0 & 0 \end{bmatrix}$ $\begin{bmatrix} 1 & 0 & 1 \\ 1 & 1 & 2 \\ 0 & 2 & 3 \end{bmatrix}$

4) Consider the discrete-time state variable system,

$$x(n+1) = \begin{bmatrix} 1 & 0 \\ 1 & 1 \end{bmatrix} x(n) + \begin{bmatrix} 1 \\ 0 \end{bmatrix} u(n)$$

Assuming we start at the origin (the point 0,0) after 3 time steps we have

$$x(3) = \begin{bmatrix} 1 & 1 & 1 \\ 2 & 1 & 0 \end{bmatrix} \begin{bmatrix} u(0) \\ u(1) \\ u(2) \end{bmatrix} = Au$$

a) If the input is $u^T = \begin{bmatrix} 1 & 1 & 1 \end{bmatrix}$ determine x(3)

b) Find a <u>unit vector</u> in the null space of the matrix A

c) Is the input vector in step (a) the input with the smallest magnitude to go from the origin to the point x(3)? Explain your answer.

5) Use a Lagrange multiplier to find the point on the plane 2x + 4y - 6 = 0 nearest the origin

6) Consider the overdetermined system Ax = b. Rather than just performing a normal least squares solution, we want to penalize the magnitude of the solution by some weighting scalar μ . Thus we want to find the value of x that minimizes

$$H = ||Ax-b||^{2} + \mu ||x||^{2} = (Ax-b)^{T}(Ax-b) + \mu (x^{T}Ix)$$

- a) Show that the solution to the above minimization problem is given by $x = (A^T A + \mu I)^{-1} A^T b$
- b) Assume now we compute the singular value decomposition of A, $A = USV^{T}$. Recall that U and V are unitary matrices, so $U^{T}U = V^{T}V = I$. This means that $U^{-1} = U^{T}$ and $V^{-1} = V^{T}$. S is a diagonal matrix with elements σ_{i} on the diagonal (assume *S* has full rank and is invertible). Assume that we can write $b = U\beta$ and $x = V\alpha$. Determine how α and β are related. *Hint: it may be helpful to write* $I = VIV^{T}$

Hints: μ *is* <u>**not**</u> *a Lagrange multiplier, there are no Lagrange multipliers in this problem. You can do both parts of this problem independently.*

Cultural Point: This technique is known as zero order Tikhonov regularization.

7) For impulse response $h(n) = \left(\frac{1}{2}\right)^n u(n-2)$ and input $x(n) = \left(\frac{1}{2}\right)^{-n} u(-n+1)$, the system output can be written as A(n)u(n-3) + B(n)u(2-n). Determine an expression for **both** A(n) and B(n). You do not need to simplify your expression but you must evaluate all sums. For my sanity (not that you care), evaluate the convolution using the form $y(n) = \sum_{k=\infty}^{k=\infty} h(n-k)x(k)$