

**ECE-420: Discrete-Time Control Systems**  
Homework 2

Due: Friday September 19 at the beginning of class

1) For the  $z$ -transform

$$X(z) = \frac{3}{z-2}$$

a) Show that, by multiplying and dividing by  $z$  and then using partial fractions, the corresponding discrete-time sequence is

$$x(k) = -\frac{3}{2} \delta(k) + \frac{3}{2} 2^k u(k)$$

b) By starting with the  $z$ -transform

$$G(z) = \frac{3z}{z-2}$$

where  $Y(z) = z^{-1}G(z)$  and the  $z$ -transform properties, show that

$$x(k) = 3 \cdot 2^{k-1} u(k-1)$$

2) For the following transfer functions, use **long division** to determine estimates of the first few terms of the impulse responses

a)  $H(z) = \frac{z^3 + 2z^2 + 3z + 2}{z + 2}$

b)  $H(z) = \frac{z^2 + 2z + 1}{z^3 + 3z}$

Answers:  $h(n) = \delta(n+2) + 3\delta(n) - 4\delta(n-1) + 8\delta(n-2) - 16\delta(n-3) + \dots$

$h(n) = \delta(n-1) + 2\delta(n-2) - 2\delta(n-3) - 6\delta(n-4) + \dots$

3) For impulse response  $h(n) = \left(\frac{1}{2}\right)^n u(n-2)$  and input  $x(n) = \left(\frac{1}{3}\right)^n u(n-2)$ , use  $z$ -transforms of the

input and impulse response to show the system output is  $y(n) = \frac{1}{6} \left[ \left(\frac{1}{2}\right)^{n-3} - \left(\frac{1}{3}\right)^{n-3} \right] u(n-3)$

*Hint:* Assume  $Y(z) = z^{-3}G(z)$ , determine  $g(n)$  and then  $y(n)$

4) For impulse response  $h(n) = \left(\frac{1}{3}\right)^{n+1} u(n-1)$  and input  $x(n) = \left(\frac{1}{2}\right)^{n-1} u(n-2)$ , use  $z$ -transforms of the input and impulse response to show the system output is  $y(n) = \frac{1}{3} \left[ \left(\frac{1}{2}\right)^{n-2} - \left(\frac{1}{3}\right)^{n-2} \right] u(n-2)$

*Hint:* Assume  $Y(z) = z^{-2}G(z)$ , determine  $g(n)$  and then  $y(n)$

5) For impulse response  $h(n) = \left(\frac{1}{2}\right)^{n-1} u(n)$  and input  $x(n) = \left(\frac{1}{5}\right)^{n-2} u(n-3)$ , use  $z$ -transforms of the input and impulse response to show the system output is  $y(n) = \frac{4}{3} \left[ \left(\frac{1}{2}\right)^{n-2} - \left(\frac{1}{5}\right)^{n-2} \right] u(n-2)$

*Hint:* Assume  $Y(z) = z^{-2}G(z)$ , determine  $g(n)$  and then  $y(n)$

6) In class we derived the relation ships

$$G(z) = \frac{rz[z \cos(\theta) - \gamma \cos(\beta - \theta)]}{z^2 - 2\gamma \cos(\beta)z + \gamma^2} = \frac{Az^2 + Bz}{z^2 + 2Cz + \gamma^2} \leftrightarrow g(n) = r\gamma^n \cos(\beta n + \theta)u(n)$$

with

$$\beta = \cos^{-1}\left(\frac{-C}{\gamma}\right), \theta = \tan^{-1}\left(\frac{CA - B}{A\sqrt{\gamma^2 - C^2}}\right), r = \sqrt{\frac{A^2\gamma^2 + B^2 - 2ABC}{\gamma^2 - C^2}}, \gamma > 0$$

a) Us the above formulas to find the impulse response  $g(n)$  for  $G(z) = \frac{z^2 + 0.5z}{z^2 + 0.2z + 0.125}$ .

b) Compute  $g(n)$  from part a for  $n = 0, 1, 2, 3, 4$  and then perform long division to verify that your answer to a is correct for these terms

c) Determine the unit step response  $y(n)$  for  $G(z) = \frac{1}{z^2 + 0.1z + 4}$ , by using the form

$$\frac{Y(z)}{z} = \frac{1}{(z-1)(z^2 + 0.1z + 4)} = \frac{\alpha_1}{z-1} + \frac{\alpha_2 z + \alpha_3}{z^2 + 0.1z + 4}$$

*Hint:*  $\alpha_1$  can be found using the cover-up method,  $\alpha_2$  can be found by multiplying both sides by  $z$  and letting  $z \rightarrow \infty$ , and  $\alpha_3$  can be found by substituting a convenient value for  $z$ , like  $z = 0$ .

d) Compute  $y(n)$  from part c for  $n = 0, 1, 2, 3, 4$  and then perform long division to verify that your answer to c is correct for these terms

7) Consider the following difference equation

$$x(k+2) - 4x(k+1) + 4x(k) = f(k)$$

Assume all initial conditions are zero.

- a) Determine the impulse response of the system, i.e., the response  $x(k)$  when  $f(k) = \delta(k)$ .
- b) Determine  $h(0)$ ,  $h(1)$ ,  $h(2)$ ,  $h(3)$ , and  $h(4)$  from your answer to **a**. Compare this answer with the known values of  $h(0)$  and  $h(1)$ . Using the difference equation compute  $h(3)$  and  $h(4)$  and compare these values to those in your solution (they should be the same!)
- c) Determine the step response of the system, i.e., the response  $x(k)$  when  $f(k) = u(k)$
- d) Determine  $x(0)$ ,  $x(1)$ ,  $x(2)$ ,  $x(3)$ , and  $x(4)$  from your answer to **c**. Compare this answer with the known values of  $x(0)$  and  $x(1)$ . Using the difference equation compute  $x(3)$  and  $x(4)$  and compare these values to those in your solution.

8) Consider the difference equation

$$x(k+2) - 5x(k+1) + 6x(k) = f(k)$$

where  $f(k) = u(k)$ , a unit step. Assume  $x(0) = 1$  and  $x(1) = 1$ .

- a) Determine the Zero Input Response (ZIR),  $x_{ZIR}(k)$ . This is the part of the solution  $x(k)$  due to the initial conditions alone (assume the input is zero).
- b) Determine the Zero State Response (ZSR),  $x_{ZSR}(k)$ . This is the part of the solution  $x(k)$  due to the input alone (assume all initial conditions are zero).
- c) Find the total response  $x(k) = x_{ZIR}(k) + x_{ZSR}(k)$
- d) Find the transfer function and the impulse response.
- e) Determine  $x(0)$ ,  $x(1)$ ,  $x(2)$ ,  $x(3)$ , and  $x(4)$  from your answer to **c**. Compare this answer with the known values of  $x(0)$  and  $x(1)$ . Using the difference equation compute  $x(3)$  and  $x(4)$  and compare these values to those in your solution.