## **ECE-420**: Discrete-Time Control Systems Homework 2

Due: Friday September 14 at the beginning of class

1) For the z-transform

$$X(z) = \frac{3}{z - 2}$$

a) Show that, by multiplying and dividing by z and then using partial fractions, the corresponding discrete-time sequence is

$$x(k) = -\frac{3}{2}\delta(k) + \frac{3}{2}2^{k}u(k)$$

**b)** By starting with the z-transform

$$G(z) = \frac{3z}{z - 2}$$

where  $Y(z) = z^{-1}G(z)$  and the z-transform properties, show that

$$x(k) = 3 2^{k-1} u(k-1)$$

**2)** For the following transfer functions, use **long division** to determine estimates of the first few terms of the impulse responses

a) 
$$H(z) = \frac{z^3 + 2z^2 + 3z + 2}{z + 2}$$

b) 
$$H(z) = \frac{z^2 + 2z + 1}{z^3 + 3z}$$

Answers:  $h(n) = \delta(n+2) + 3\delta(n) - 4\delta(n-1) + 8\delta(n-2) - 16\delta(n-3) + \dots$ 

$$h(n) = \delta(n-1) + 2\delta(n-2) - 2\delta(n-3) - 6\delta(n-4) + \dots$$

3) For impulse response  $h(n) = \left(\frac{1}{2}\right)^n u(n-2)$  and input  $x(n) = \left(\frac{1}{3}\right)^n u(n-2)$ , use z-transforms of the

input and impulse response to show the system output is  $y(n) = \frac{1}{6} \left[ \left( \frac{1}{2} \right)^{n-3} - \left( \frac{1}{3} \right)^{n-3} \right] u(n-3)$ 

*Hint*: Assume  $Y(z) = z^{-3}G(z)$ , determine g(n) and then y(n)

- **4)** For impulse response  $h(n) = \left(\frac{1}{3}\right)^{n+1} u(n-1)$  and input  $x(n) = \left(\frac{1}{2}\right)^{n-1} u(n-2)$ , use *z*-transforms of the input and impulse response to show the system output is  $y(n) = \frac{1}{3} \left[\left(\frac{1}{2}\right)^{n-2} \left(\frac{1}{3}\right)^{n-2}\right] u(n-2)$  *Hint:* Assume  $Y(z) = z^{-2}G(z)$ , determine g(n) and then y(n)
- 5) For impulse response  $h(n) = \left(\frac{1}{2}\right)^{n-1} u(n)$  and input  $x(n) = \left(\frac{1}{5}\right)^{n-2} u(n-3)$ , use z-transforms of the input and impulse response to show the system output is  $y(n) = \frac{4}{3} \left[\left(\frac{1}{2}\right)^{n-2} \left(\frac{1}{5}\right)^{n-2}\right] u(n-2)$ Hint: Assume  $Y(z) = z^{-2}G(z)$ , determine g(n) and then y(n)
- 6) In class we derived the relation ships

$$G(z) = \frac{rz[z\cos(\theta) - \gamma\cos(\beta - \theta)]}{z^2 - 2\gamma\cos(\beta)z + \gamma^2} = \frac{Az^2 + Bz}{z^2 + 2Cz + \gamma^2} \iff g(n) = r\gamma^n\cos(\beta n + \theta)u(n)$$

with

$$\beta = \cos^{-1}\left(\frac{-C}{\gamma}\right), \ \theta = \tan^{-1}\left(\frac{CA - B}{A\sqrt{\gamma^2 - C^2}}\right), \ r = \sqrt{\frac{A^2\gamma^2 + B^2 - 2ABC}{\gamma^2 - C^2}}$$

- a) Us the above formulas to find the impulse response g(n) for  $G(z) = \frac{z^2 + 0.5z}{z^2 + 0.2z + 0.125}$ .
- **b)** Compute g(n) from part **a** for n = 0, 1, 2, 3, 4 and then perform long division to verify that your answer to **a** is correct for these terms
- c) Determine the unit step response y(n) for  $G(z) = \frac{1}{z^2 + 0.1z + 4}$ , by using the form

$$\frac{Y(z)}{z} = \frac{1}{(z-1)(z^2+0.1z+4)} = \frac{\alpha_1}{z-1} + \frac{\alpha_2 z + \alpha_3}{z^2+0.1z+4}$$

Hint:  $\alpha_1$  can be found using the cover-up method,  $\alpha_2$  can be found by multiplying both sides by z and letting  $z \to \infty$ , and  $\alpha_3$  can be found by substituting a convenient value for z, like z = 0.

**d**) Compute y(n) from part **e** for n = 0, 1, 2, 3, 4 and then perform long division to verify that your answer to **e** is correct for these terms

7) Consider the following difference equation

$$x(k+2)-4x(k+1)+4x(k) = f(k)$$

Assume all initial conditions are zero.

- a) Determine the <u>impulse response</u> of the system, i.e., the response x(k) when  $f(k) = \delta(k)$ .
- **b**) Determine h(0), h(1), h(2), h(3), and h(4) from your answer to **a**. Compare this answer with the known values of h(0) and h(1). Using the difference equation compute h(3) and h(4) and compare these values to those in your solution (they should be the same!)
- c) Determine the step response of the system, i.e., the response x(k) when f(k) = u(k)
- **d**) Determine x(0), x(1), x(2), x(3), and x(4) from your answer to **c**. Compare this answer with the known values of x(0) and x(1). Using the difference equation compute x(3) and x(4) and compare these values to those in your solution.
- 8) Consider the difference equation

$$x(k+2)-5x(k+1)+6x(k) = f(k)$$

where f(k) = u(k), a unit step. Assume x(0) = 1 and x(1) = 1.

- a) Determine the <u>Zero Input Response</u> (ZIR),  $x_{ZIR}(k)$ . This is the part of the solution x(k) due to the initial conditions alone (assume the input is zero).
- **b)** Determine the <u>Zero State Response</u> (ZSR),  $x_{ZSR}(k)$ . This is the part of the solution x(k) due to the input alone (assume all initial conditions are zero).
- c) Find the total response  $x(k) = x_{ZIR}(k) + x_{ZSR}(k)$
- **d)** Find the transfer function and the impulse response.
- e) Determine x(0), x(1), x(2), x(3), and x(4) from your answer to **c.** Compare this answer with the known values of x(0) and x(1). Using the difference equation compute x(3) and x(4) and compare these values to those in your solution.