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Quiz #6

For problems 1-3 , consider a closed loop system with transfer function

$$G_0(s) = \frac{s+a}{s^2+bs+k}$$

1) The sensitivity to variations in *k*, $S_k^{G_0}(s)$, is

a) $\frac{k}{s^2+bs+k}$ b) $\frac{-k}{s^2+bs+k}$ c) 1 d) $\frac{k}{s+a} - \frac{k}{s^2+bs+k}$ e) none of these

2) The sensitivity to variations in *b*, $S_b^{G_0}(s)$, is

a) $\frac{-b}{s^2+bs+k}$ b) $\frac{-bs}{s^2+bs+k}$ c) 1 d) $\frac{b}{s+a} - \frac{bs}{s^2+bs+k}$ e) none of thes

3) The sensitivity to variations in *a*, $S_a^{G_0}(s)$, is

a) $\frac{a}{s^2+bs+k}$ b) $\frac{-a}{s^2+bs+k}$ c) 1) d) $\frac{a}{s+a}$ e) none of these

4) Assume we compute the sensitivity of a system with nominal value $a = 4$ to be

$$S_a^{G_0}(s) = \frac{1}{s+a}$$

For what frequencies will the sensitivity function be less than $\frac{1}{\sqrt{32}}$?

a) $\omega < 4$ rad / sec b) $\omega > 4$ rad / sec c) $\omega > 16$ rad / sec d) $\omega < 16$ rad / sec e) none of these

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5) Assume we compute the sensitivity of a system with nominal value $a = 3$

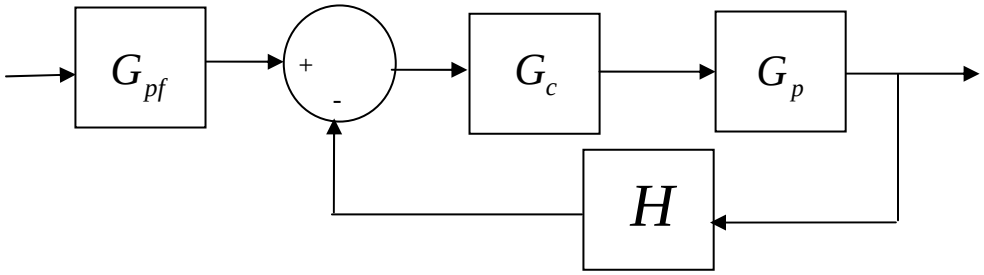
to be

$$S_a^{G_0}(s) = \frac{s+2}{s+1+a}$$

For what frequencies will the sensitivity function be greater than $\sqrt{\frac{10}{16}}$?

a) $\omega < 4$ rad / sec b) $\omega > 4$ rad / sec c) $\omega > 16$ rad / sec d) $\omega < 16$ rad / sec e) none of these

Problems 6-9 refer to the following system



6) To reduce the sensitivity of the closed loop transfer function variations in the plant G_p , we should

a) make $|G_c(j\omega)G_p(j\omega)H(j\omega)|$ large b) make $|G_c(j\omega)G_p(j\omega)H(j\omega)|$ small

c) make G_{pf} large d) do nothing, we cannot change the sensitivity

7) To reduce the sensitivity of the closed loop transfer function to variations in the prefilter G_{pf} , we should

a) make $|G_c(j\omega)G_p(j\omega)H(j\omega)|$ large b) make $|G_c(j\omega)G_p(j\omega)H(j\omega)|$ small

c) make G_{pf} small d) do nothing, we cannot change the sensitivity

8) To reduce the sensitivity of the closed loop transfer function to variations in the controller G_c we should

a) make $|G_c(j\omega)G_p(j\omega)H(j\omega)|$ large b) make $|G_c(j\omega)G_p(j\omega)H(j\omega)|$ small

c) make $|H(j\omega)|$ large d) do nothing, we cannot change the sensitivity

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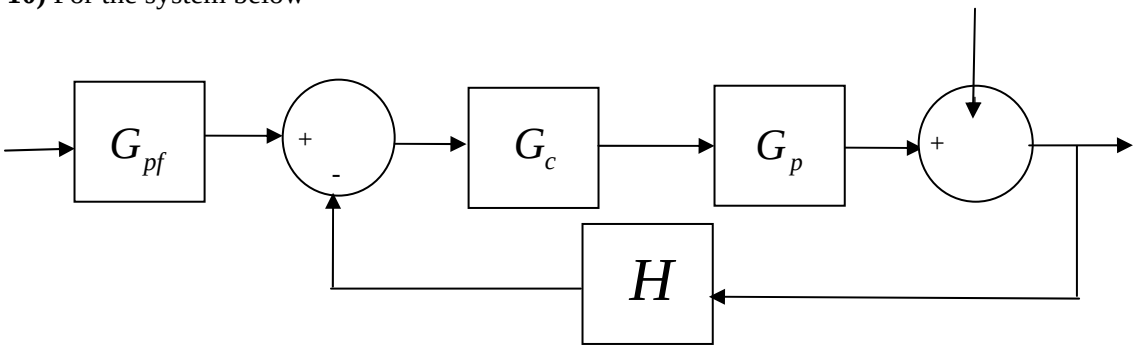
9) To reduce the sensitivity of the closed loop transfer function to variations in the sensor H , we should

a) make $|G_c(j\omega)G_p(j\omega)H(j\omega)|$ large b) make $|G_c(j\omega)G_p(j\omega)H(j\omega)|$ small

c) make G_{pf} large d) do nothing, we cannot change the sensitivity

D

10) For the system below

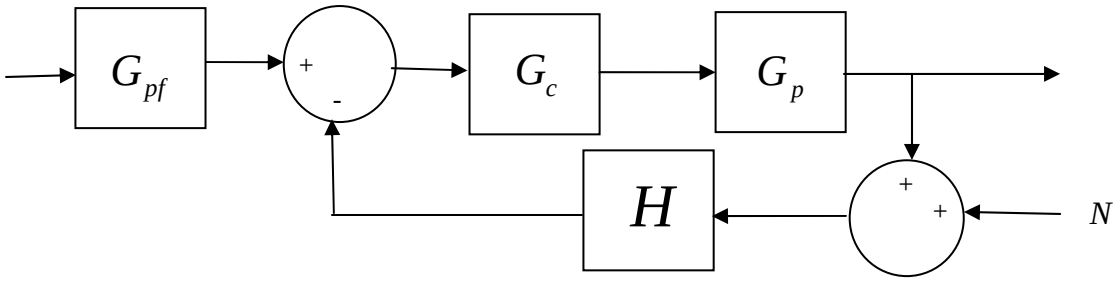


to reduce the effects of the external disturbance D on the system output, we should

a) make $|G_c(j\omega)G_p(j\omega)H(j\omega)|$ large b) make $|G_c(j\omega)G_p(j\omega)H(j\omega)|$ small

c) make G_{pf} large d) do nothing, we cannot change the sensitivity

11) For the system below



to reduce the effects of sensor noise N on the closed loop system , we should

a) make $|G_c(j\omega)G_p(j\omega)H(j\omega)|$ large b) make $|G_c(j\omega)G_p(j\omega)H(j\omega)|$ small

c) make $|H(j\omega)|$ large d) do nothing, we cannot change the sensitivity

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12) Consider the characteristic equation $\Delta(s) = s^3 + ks^2 + 2s + 3$. Using the Routh-Hurwitz array, we can determine the system is stable for

a) all $k > 0$ b) no value of k c) $0 < k < 1.5$ d) $k > 1.5$

13) Consider the characteristic equation $\Delta(s) = 4s^4 + 3s^3 + ks^2 + s + 3$. Using the Routh-Hurwitz array, we can determine the system is stable for

a) all $k > 0$ b) no value of k c) $k > 31/3$ d) $k > 4/3$

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Problems 14-17 refer to a characteristic equation that leads to the following Routh array

s^5	1	3	2
s^4	1	3	2
s^3	0	0	
s^2	α	β	
s^1			
s^0			

14) One of the factors of $\Delta(s)$ is

a) $s^4 + 3s^3 + 2s$ b) $s^3 + 3s^2 + 2s$ c) $s^5 + 3s^3 + 2s$ d) none of these

15) We should replace the row of zeros with which of the following rows

a) 1 3 b) 4 3 c) 4 6 d) none of these

16) The value of α is a) 1 b) 0 c) 9/2 d) 3/2 e) none of these

17) The value of β is a) 0 b) 1 c) 2 d) 3 e) none of these