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ECE-320 Linear Control Systems

Spring 2012, Exam 1

No calculators or computers allowed, except for Problem 8 when you should use Matlab's sisotool.

You must simplify your answers as much as possible, or points will be deducted.

Problem 1 _____/7

Problem 2 _____/7

Problem 3 _____/7

Problem 4 _____/7

Problem 5 _____/7

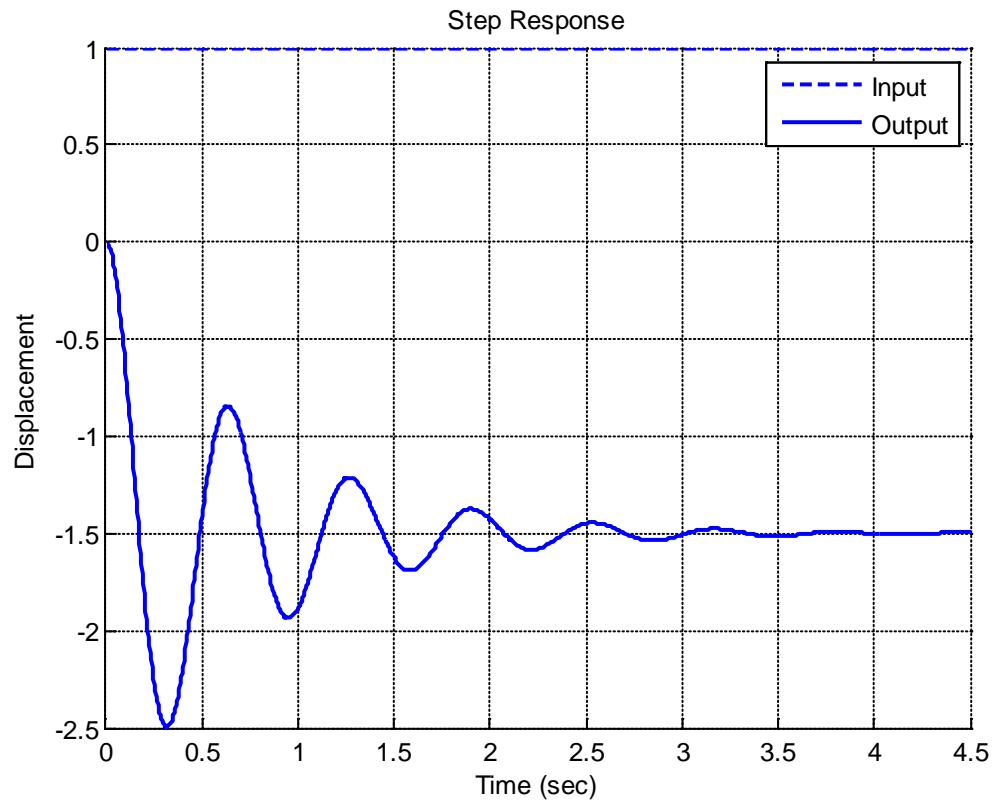
Problem 6 _____/20

Problem 7 _____/20

Problem 8 _____/25

Total _____/100

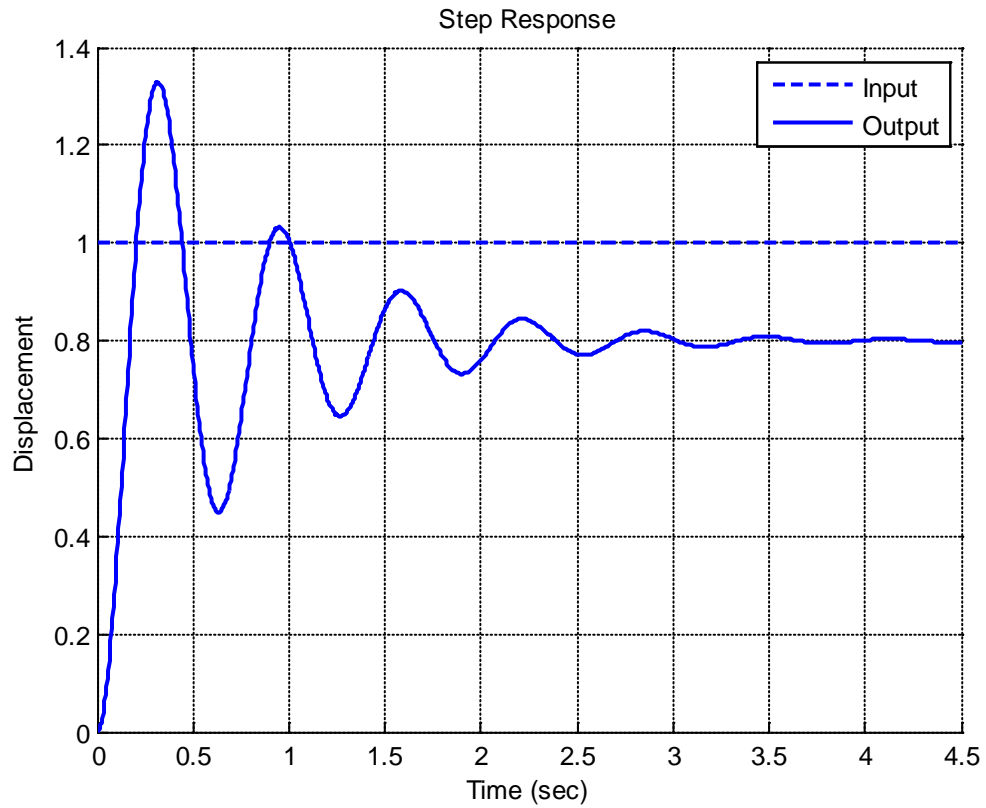
1) (7 points) The following graph shows the **unit step response** for a system.



a) Estimate the **percent overshoot**

b) Estimate the **static gain**

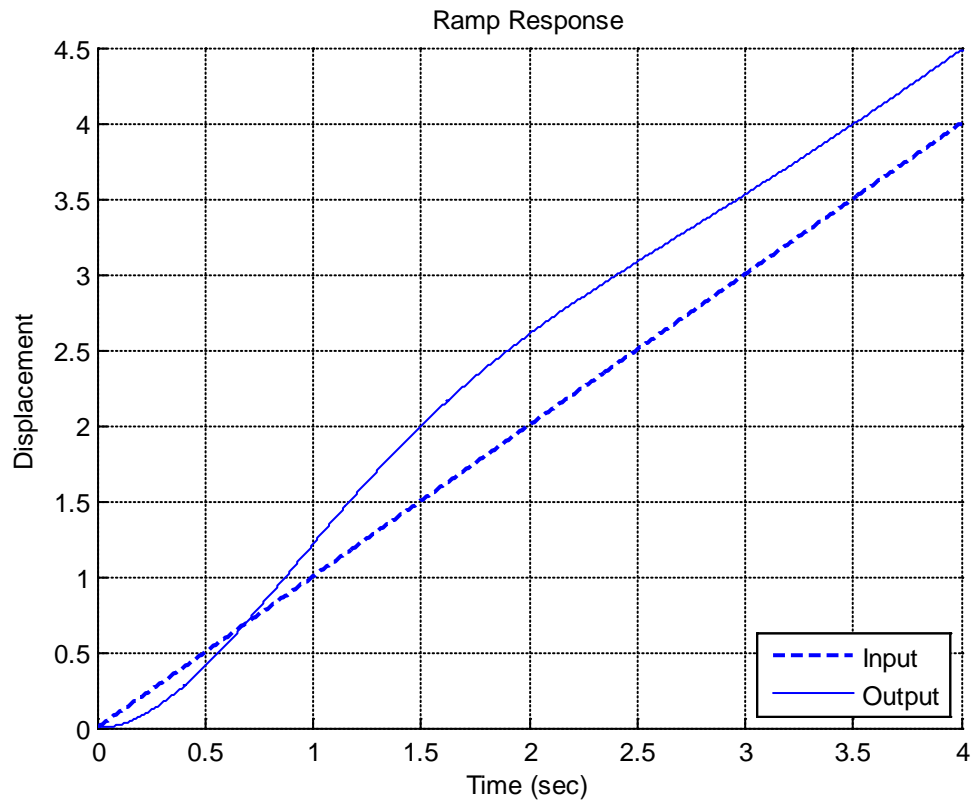
2) (7 points) The following graph shows the unit step response of a system.



a) Estimate the **steady state error**.

b) Estimate the steady state error for a unit ramp input.

3) (7 points) The following figure shows the unit ramp response of a system.



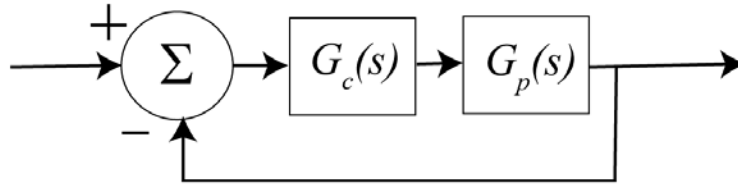
a) Estimate the **steady state error**.

b) Estimate the steady state error for a unit step input.

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4) (7 points) For the following systems, assume $G_c(s) = \frac{s+2}{s+3}$ and $G_p(s) = \frac{s+5}{s+4}$



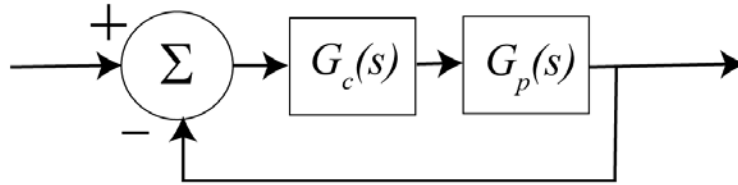
a) Determine the position error constant K_p

b) Determine the steady state error for a unit step input.

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5) (7 points) For the following systems, assume $G_c(s) = \frac{2}{s}$ and $G_p(s) = \frac{s+5}{s+4}$



a) Determine the velocity error constant K_v .

b) Determine the steady state error for a unit ramp input.

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6) (20 points) For a system with the transfer function $H(s) = \frac{1}{s(s+1)}$

a) Determine the **impulse response** $h(t)$

b) Determine the **unit step response**.

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7) (20 points) For the system with closed loop transfer function $G_o(s) = \frac{k}{s^2 + 2s + k}$

a) Determine an expression for the sensitivity of G_o to k as a function of s , $S_k^{G_o}$

b) Determine an expression for the magnitude of the sensitivity function as a function of frequency, ω . Simplify your answers as much as possible.

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8) (25 points) (*sisotool* problem)

Consider the plant

$$G_p(s) = \frac{30}{s^2 + 6s + 10}$$

Design a PID controller using *sisotool* with **real zeros** so that

$$T_s \leq 1.5 \text{ sec}$$

$$P.O. \leq 10\%$$

In addition, your controller must be designed so that

$$k_p \leq 0.5$$

$$k_i \leq 2$$

$$k_d \leq 0.05$$

Write your final values for k_p , k_i , k_d , and the transfer function of the controller in the space below.

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