# ECE-320 Linear Control Systems Spring-2010

## Dr. Bob Throne x-8414, Room D-221

**Text:** There is no single textbook that works for all topics. For most of the topics we cover, I will put some notes on the class website. These notes are similar to the notes I will be using in class but will generally have different examples than those I use in class. However, these notes are not complete yet.

## **GRADING POLICY**

Each Exam	20%
Labs	10%
Homework/Matlab/Simulink	10%
Quizes	10%
Lab/Matlab Practical	10%

#### **Notes:**

- (1) You must have a passing average (greater than or equal to 60%) on the exams to pass the class!
- (2) Homework assignments are <u>due at the beginning of class on Thursday</u>. No late homework will be accepted without prior approval.
- (3) You must acceptably complete each lab to pass the class.
- (4) For the majority of the labs, you will be required in the preceding homework to derive some relationships we will be using in lab or simulate a system (or systems). If you understand the homework the lab should not be a problem. You will be told which parts of the homework are required for the lab. You will receive a 0 on the corresponding lab if you have not done this acceptably! However, you must still complete the homework and do the lab to pass the course. *The prelab portions are to be done individually, not with your lab partner. They are part of the homework assignment*
- (5) Many of the homework problems will require you to use Matlab or Simulink as part of the problem. If you do not do these parts of the problem, do not expect to receive credit for any parts of the problem.
- (6) You are expected to do your own work. You can certainly talk with each other and help each other, but the work you hand in should be your own. As an example, if two people hand in the same Simulink plot and both came from the same directory, neither will receive any points!
- (7) Unless specifically told otherwise on a particular problem, you are expected to work out the problem by hand (or use Matlab). *If you write on your assignment that you used Maple and are copying the answer, expect to get no points.* You can use Maple to check your answers. You cannot turn in any Maple code or plot as part of the solution to a problem.

## **Quizes:**

Each week we will have a quiz, usually (though not always) on Thursday. Usually before the quiz a "practice quiz" will be posted to give you an idea of the kinds of problems you are expected to be able to solve on that week's quiz.

### Labs:

- 1) You cannot use your laptop during the lab except for transferring files or running simulations. Points will be deducted for inappropriate behavior.
- 2) You can work individually or in groups of two.
- 3) You must write a short memo summarizing your results and *e-mail the memo to me*. This memo is due *before* your next lab period. You should include as attachments in the memo the plots and you made for the lab. The lab write up is to be computer generated and each graph needs to be labeled as a figure (with a caption). Usually students find it easier to just copy and paste all the figures they need into a document and explain the figure or answer questions as they are doing the lab. For the most part, the memos should be short since I mostly look at the pictures.
- 4) You are expected to do the labs during the assigned lab time each week. If for some reason you do not finish during this time, you may finish on your own time. <u>However, this does not mean you are free to do the labs whenever you want.</u>
- 5) You are required to leave the software you used for each lab on the computer you used for the lab. <u>If I check</u> on your folder and the code necessary for a lab is not present and you have turned in a lab report, you will fail the course and be charged with academic misconduct.
- 6) Each lab group is to write/edit their own code. It is certainly acceptable to talk with other groups and, with their knowledge and permission, look at their code. However, you cannot take their code (and they cannot give it to you), unless you have my explicit permission to do so (it may be necessary in unusual circumstances). If you take or share electronic files (code) without my permission, you will fail the course and be charged with academic misconduct.

#### **SYLLABUS**

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Class 1 (3/8) - Laplace Transforms/Partial Fractions
Class 2 (3/9) – Laplace Transforms/Partial Fractions
Class 3 (3/11) – Laplace Transforms, Final Value Theorem
Lab 1 - System Identification and Model Matching Control of a 1 dof Rectilinear System
Class 4 (3/15) – Steady State Errors
Class 5 (3/16) - Response of 2<sup>nd</sup> Order Systems, Performance Specifications
Class 6 (3/18) - Characteristic Polynomial and Modes, Stability
Lab 2 – System Identification and Model Matching Control of a 1 dof Torsional System
Class 7 (3/22) – Block Diagram Manipulation
Class 8 (3/23) – Model Matching (ITAE, Deadbeat)
Class 9 (3/25) - Steady State Errors, System Type
Lab 3 – System Identification and Model Matching Control of a 2 dof Rectilinear System
Class 10 (3/29) – Root Locus for Compensator Design
Class 11 (3/30) – Root Locus for Compensator Design
Class 12 (4/1) – Exam 1
Lab 4 – Root Locus Design (Matlab's sisotool)
Class 13 (4/12) – Root Locus for Compensator Design
Class 14 (4/13) – Lag Compensators
Class 15 (4/15) – System Sensitivity
Lab 5 - Root Locus (PID) Design
Class 16 (4/19) – System Sensitivity
Class 17 (4/20) - Routh Array
Class 18 (4/22) – Routh Array
Lab 6 – PI-D and I-PD Configurations
Class 19 (4/26) – State Variable Systems
Class 20 (4/27) – State Variable Systems
Class 21 (4/29) – Exam 2
Lab 7 - State variable control for 1 and 2 degree of freedom systems
Class 22 (5/3) – State Variable Systems
Class 23 (5/4) – Integral Control and State Variable Systems
Class 24 (5/6) – Full Order Observers and State Variable Systems
Lab 8 – State Variable Control of an Inverted Pendulum
Class 25 (5/10) – Bode Plots, Phase and Gain Margins
Class 26 (5/11) - Bode Plots, Phase Lead Compensators
Class 27 (5/13) - Bode Plots, Phase Lead Compensators
Lab 9 – State variable control with integral control and full order observers
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Class 28 (5/17) – Nyquist Plots Class 29 (5/18) – Nyquist Plots Class 30 (5/20) – **Exam 3** Lab 10 - Matlab/Lab Practical