## ECE 300 **Signals and Systems**

## Exam 2 29 January, 2009

This exam is closed-book in nature. Credit will not be given for work not shown. You may use calculators for simple calculations, but show what you are calculating!

/ 30
/ 25
/ 20
/ 25

Exam 2 Total Score: \_\_\_\_\_ / 100

**1.** (**30 points**) The next few questions are based on the plot of x(t) below.



(a) What is the fundamental frequency of x(t) in r/s?

(b) Determine the Fourier Series coefficients for x(t). Express your answer in terms of a sinc function with a gain and phase term if necessary.

(c) If a periodic signal x(t) is inserted into a system given by y(t) = x(t+1.5) - 1, express the Fourier coefficients of the output y(t),  $c_k^y$ , in terms of the input Fourier coefficients of x(t),  $c_k^x$ . This problem is independent of part (b).

 $c_0^y =$ 

 $c_k^y =$ 

$$x(t) = e^{-t} \quad 0 < t < 2$$

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x(t) has the Fourier series representation

$$x(t) = \sum_{k} \frac{0.4323}{1 + jk\pi} e^{jk\pi t}$$

The system is an ideal lowpass filter with unit amplitude that eliminates all signals with frequency content higher than 1.25 Hz.

a) Find the average power in x(t).

b) Determine an expression for the output, y(t). Your expression for y(t) must be real, and written in terms of sines and/or cosines.

c) Determine the average power in y(t). Be sure to show what you are calculating, not just the final answer!

**3.** (20 points) A periodic signal x(t) with period  $T_0 = 3$  seconds is the input to an LTI system with transfer function  $H(j\omega)$ . The relevant non-zero spectra are shown below. Determine an expression for the output of the system y(t). All angles are multiples of 45 degrees. Your final answer must be in terms of sines and/or cosines. *You do not need to simplify you answer*.



Figure 1. Spectrum of the input signal x(t).



Figure 2. Samples of the transfer function  $H(jk\omega_0)$ 

4. (25 points) Consider a causal linear time invariant system with impulse response

$$h(t) = \left[1 - 0.5t^2\right] [u(t+2) - u(t-1)]$$

The input to the system is

$$x(t) = u(t+1) - u(t-1) - 2u(t-2) + 2u(t-3)$$

These two functions are plotted below:



Using *graphical convolution*, set up the integrals to determine the output y(t) for  $t \le 1$ . Note that we are only interested in a limited range!!

Specifically, you must

- Flip and slide h(t)
- Show graphs displaying  $h(t \lambda)$  relative to  $x(\lambda)$  for each region of interest.
- Determine the ranges of *t* for which each part of your solution is valid.
- Set up any necessary integrals to compute *y*(*t*). Your integrals must be complete and simplified as much as possible (no unit step functions)
- <u>Do Not Evaluate the Integrals!</u>!

Some Potentially Useful Relationships

$$E_{\infty} = \lim_{T \to \infty} \int_{-T}^{T} |x(t)|^{2} dt = \int_{-\infty}^{\infty} |x(t)|^{2} dt$$
$$P_{\infty} = \lim_{T \to \infty} \frac{1}{2T} \int_{-T}^{T} |x(t)|^{2} dt$$

$$e^{jx} = \cos(x) + j\sin(x) \qquad j = \sqrt{-1}$$
$$\cos(x) = \frac{1}{2} \left[ e^{jx} + e^{-jx} \right] \qquad \sin(x) = \frac{1}{2j} \left[ e^{jx} - e^{-jx} \right]$$

$$\cos^{2}(x) = \frac{1}{2} + \frac{1}{2}\cos(2x) \qquad \sin^{2}(x) = \frac{1}{2} - \frac{1}{2}\cos(2x)$$
$$\operatorname{rect}\left(\frac{t - t_{0}}{T}\right) = u\left(t - t_{0} + \frac{T}{2}\right) - u\left(t - t_{0} - \frac{T}{2}\right)$$