

ECE 300
Signals and Systems

Exam 3
10 November, 2009

This exam is closed-book in nature. You are not to use a calculator or computer during the exam. Do not write on the back of any page, use the extra pages at the end of the exam. **You must show your work to receive credit for a problem.**

Problem 1 _____ / 35
Problem 2 _____ / 30
Problem 3 _____ / 20
Problem 4 _____ / 15

Exam 3 Total Score: _____ / 100

1. (35 points) Assume $x(t) = 4 \operatorname{sinc}\left[\frac{1}{\pi}(t-2)\right] \cos(4(t-2))$ is the input to an LTI system with transfer function

$$H(\omega) = \begin{cases} \frac{1}{\pi} e^{-j\omega 3} & |\omega| > 4 \\ 0 & \text{else} \end{cases}$$

- a) Determine the Fourier transform $X(\omega)$ of $x(t)$
- b) Accurately sketch the magnitude and phase of $X(\omega)$
- c) Determine the energy in $x(t)$
- d) Sketch the magnitude and phase of $Y(\omega)$
- e) Determine the system output $y(t)$

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2. (30 points) Fill in the following table, show all your work

$x(t)$	$X(\omega)$
	$\left[\text{rect}\left(\frac{\omega+2}{3}\right) + \text{rect}\left(\frac{\omega-2}{3}\right) \right] e^{j\omega 3}$
	$\frac{3}{2 + j\left(\frac{\omega}{5} + 2\right)}$
$\frac{4}{4 + (2t - 4)^2}$	

3. (20 points) Consider the signal $x(t) = \cos(4t) + \cos(6t)$

a) Sketch the spectrum of $X(\omega)$

b) $x(t)$ is the input to an ideal sampler sampling at rate $f_s = \frac{5}{2\pi} = \frac{1}{T}$ seconds. Sketch the spectrum of the sampled signal $X_s(\omega)$.

c) Assume $x_s(t)$ is the input to an ideal lowpass filter with a cutoff frequency of 7 rad/sec and passband gain of T . Determine the output signal $x_r(t)$ and write it in terms of the original signal $x(t)$ plus any aliased terms.

4) (15 points) The periodic signal $x(t)$ has the Fourier series representation

$$x(t) = 2 + \sum_{k=-\infty}^{k=\infty} \frac{1}{1+kj} e^{jk3t}$$

$x(t)$ is the input to an LTI system (a high pass filter) with the transfer function

$$H(j\omega) = \begin{cases} 0 & |\omega| < 2 \\ 4e^{-j2\omega} & |\omega| > 2 \end{cases}$$

The steady state output of the system can be written as

$$y(t) = ax(t-b) + c + d \cos(e(t-b) + f).$$

Determine the output, writing it in as simple a form (like that above) as you can.

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Some Potentially Useful Relationships

$$E_{\infty} = \lim_{T \rightarrow \infty} \int_{-T}^T |x(t)|^2 dt = \int_{-\infty}^{\infty} |x(t)|^2 dt$$

$$P_{\infty} = \lim_{T \rightarrow \infty} \frac{1}{2T} \int_{-T}^T |x(t)|^2 dt$$

$$e^{jx} = \cos(x) + j \sin(x) \quad j = \sqrt{-1}$$

$$\cos(x) = \frac{1}{2} [e^{jx} + e^{-jx}] \quad \sin(x) = \frac{1}{2j} [e^{jx} - e^{-jx}]$$

$$\cos^2(x) = \frac{1}{2} + \frac{1}{2} \cos(2x) \quad \sin^2(x) = \frac{1}{2} - \frac{1}{2} \cos(2x)$$

$$\text{rect}\left(\frac{t-t_0}{T}\right) = u\left(t-t_0 + \frac{T}{2}\right) - u\left(t-t_0 - \frac{T}{2}\right)$$