

Name Solutions CM _____

ECE 300
Signals and Systems

Exam 3
10 November, 2009

This exam is closed-book in nature. You are not to use a calculator or computer during the exam. Do not write on the back of any page, use the extra pages at the end of the exam. **You must show your work to receive credit for a problem.**

Problem 1 _____ / 35
Problem 2 _____ / 30
Problem 3 _____ / 20
Problem 4 _____ / 15

Exam 3 Total Score: _____ / 100

90-100 3
80-89 13
70-79 6
60-69 8
<60 8
median = 71

1. (35 points) Assume $x(t) = 4 \text{sinc}\left[\frac{1}{\pi}(t-2)\right] \cos(4(t-2))$ is the input to an LTI system with transfer function

$$H(\omega) = \begin{cases} \frac{1}{\pi} e^{-j\omega 3} & |\omega| > 4 \\ 0 & \text{else} \end{cases}$$

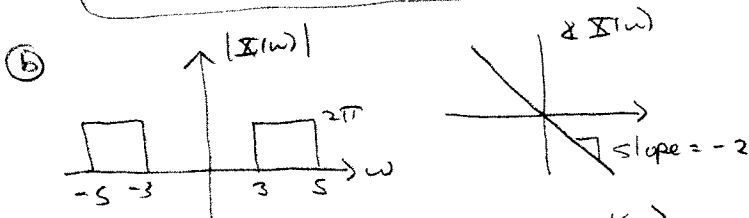
- a) Determine the Fourier transform $X(\omega)$ of $x(t)$
- b) Accurately sketch the magnitude and phase of $X(\omega)$
- c) Determine the energy in $x(t)$
- d) Sketch the magnitude and phase of $Y(\omega)$
- e) Determine the system output $y(t)$

Ⓐ for $x_1(t) = 4 \text{sinc}\left(\frac{t}{\pi}\right) \leftrightarrow \mathcal{X}_1(\omega) = 4\pi \text{rect}\left(\frac{\omega}{2}\right)$

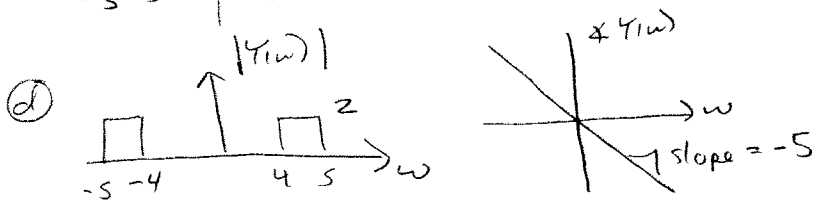
$\omega = \frac{1}{2\pi}$

for $x_2(t) = x_1(t) \cos(4t) \leftrightarrow \mathcal{X}_2(\omega) = 2\pi \text{rect}\left(\frac{\omega+4}{2}\right) + 2\pi \text{rect}\left(\frac{\omega-4}{2}\right)$

$$\mathcal{X}(\omega) = 2\pi \left[\text{rect}\left(\frac{\omega+4}{2}\right) + \text{rect}\left(\frac{\omega-4}{2}\right) \right] e^{-j2\omega}$$



Ⓒ $E = 2 \left[\frac{1}{2\pi} \int_{-3}^3 (2\pi)^2 d\omega \right]$
 $= 2 \frac{1}{2\pi} (2\pi)^2 \cdot 2 = 8\pi = E$



Ⓔ $Y(\omega) = \left[2 \text{rect}(\omega+4, 1) + 2 \text{rect}(\omega-4, 1) \right] e^{-j5\omega}$

$\omega \text{sinc}(\omega t) \leftrightarrow \text{rect}\left(\frac{\omega}{2\pi t}\right)$ $\omega = \frac{1}{2\pi}$ so $\frac{1}{2\pi} \text{sinc}\left(\frac{t}{2\pi}\right) \leftrightarrow \text{rect}(\omega)$

$\frac{1}{2\pi} \text{sinc}\left(\frac{t}{2\pi}\right) \cos(4, 1t) \leftrightarrow \frac{1}{2} \text{rect}(\omega+4, 1) + \frac{1}{2} \text{rect}(\omega-4, 1)$

$\frac{2}{\pi} \text{sinc}\left(\frac{t}{2\pi}\right) \cos(4, 1t) \leftrightarrow 2 \text{rect}(\omega+4, 1) + 2 \text{rect}(\omega-4, 1)$

$$Y(\omega) = \frac{2}{\pi} \text{sinc}\left(\frac{t-5}{2\pi}\right) \cos(4, 1(t-5))$$

2. (30 points) Fill in the following table, show all your work

	$x(t)$	$X(\omega)$
(a)		$\left[\text{rect}\left(\frac{\omega+2}{3}\right) + \text{rect}\left(\frac{\omega-2}{3}\right) \right] e^{j\omega 3}$
(b)		$\frac{3}{2+j\left(\frac{\omega}{5}+2\right)}$
(c)	$\frac{4}{4+(2t-4)^2}$	

(a) $\text{rect}\left(\frac{\omega}{2\pi W}\right) \leftrightarrow W \text{rect}(Wt)$ $2\pi W = 3$ $W = \frac{3}{2\pi}$

for $x_1(t) = \frac{3}{2\pi} \text{rect}\left(\frac{3}{2\pi}t\right) \leftrightarrow \mathcal{X}_1(\omega) = \text{rect}\left(\frac{\omega}{3}\right)$

for $x_2(t) = x_1(t) \cos(2t) \leftrightarrow \mathcal{X}_2(\omega) = \frac{1}{2} \text{rect}\left(\frac{\omega+2}{3}\right) + \frac{1}{2} \text{rect}\left(\frac{\omega-2}{3}\right)$

$x(t) = \frac{3}{2\pi} \text{rect}\left(\frac{3}{2\pi}(t+3)\right) \cos(2(t+3))$

(b) for $x_1(t) = 3e^{-2t} u(t) \leftrightarrow \mathcal{X}_1(\omega) = \frac{3}{2+j\omega}$

for $x_2(t) = x_1(t) e^{-j^2 t} \leftrightarrow \mathcal{X}_2(\omega) = \mathcal{X}_1(\omega+2) = \frac{3}{2+j(\omega+2)}$

for $\mathcal{X}_3(\omega) = \mathcal{X}_2\left(\frac{\omega}{5}\right) = \frac{3}{2+j\left(\frac{\omega}{5}+2\right)} \leftrightarrow x_3(t) = 5x_2(5t) = \boxed{15e^{-10t} e^{-j10t} u(t) = x(t)}$

(c) for $x_1(t) = e^{-2|t|} \leftrightarrow \mathcal{X}_1(\omega) = \frac{4}{4+\omega^2}$

for $x_2(t) = \mathcal{X}_1(t) = \frac{4}{4+t^2} \leftrightarrow \mathcal{X}_2(\omega) = 2\pi \mathcal{X}_1(-\omega) = 2\pi e^{-2|\omega|}$

for $x_3(t) = x_2(2t) = \frac{4}{4+(2t)^2} \leftrightarrow \mathcal{X}_3(\omega) = \frac{1}{2} \mathcal{X}_2\left(\frac{\omega}{2}\right) = \pi e^{-|\omega|}$

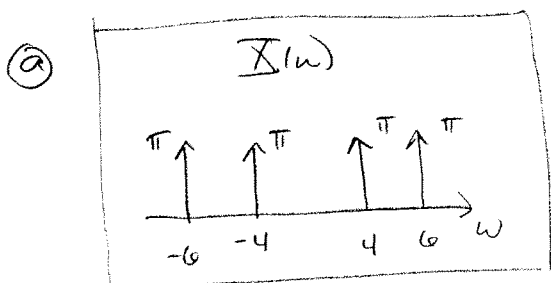
for $x_4(t) = x_3(t-2) = \frac{4}{4+(2(t-2))^2} \leftrightarrow \mathcal{X}_4(\omega) = \mathcal{X}_3(\omega) e^{-j2\omega} = \boxed{\pi e^{-|\omega|} e^{-j2\omega} = \mathcal{X}(\omega)}$

3. (20 points) Consider the signal $x(t) = \cos(4t) + \cos(6t)$

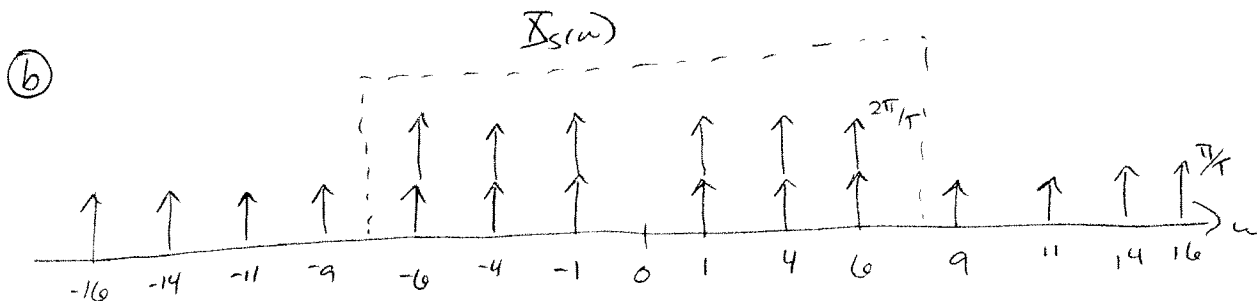
a) Sketch the spectrum of $X(\omega)$

b) $x(t)$ is the input to an ideal sampler sampling at rate $f_s = \frac{5}{2\pi} = \frac{1}{T}$ seconds. Sketch the spectrum of the sampled signal $X_s(\omega)$.

c) Assume $x_s(t)$ is the input to an ideal lowpass filter with a cutoff frequency of 7 rad/sec and passband gain of T . Determine the output signal $x_r(t)$ and write it in terms of the original signal $x(t)$ plus any aliased terms.



$$\omega_0 = \frac{2\pi}{T} = 2\pi \left(\frac{5}{2\pi} \right) = \boxed{5 \text{ rad/sec} = \omega_0}$$



(c) $x_r(t) = 2\cos(6t) + 2\cos(4t) + 2\cos(t)$

$$x_r(t) = x(t) + \underbrace{[2\cos(t) + \cos(4t) + \cos(6t)]}_{\text{aliased term}}$$

4) (15 points) The periodic signal $x(t)$ has the Fourier series representation

$$x(t) = 2 + \sum_{k=-\infty}^{k=\infty} \frac{1}{1+kj} e^{jk3t}$$

$x(t)$ is the input to an LTI system (a high pass filter) with the transfer function

$$H(j\omega) = \begin{cases} 0 & |\omega| < 2 \\ 4e^{-j2\omega} & |\omega| > 2 \end{cases}$$

The steady state output of the system can be written as

$$y(t) = ax(t-b) + c + d \cos(e(t-b) + f).$$

Determine the output, writing it in as simple a form (like that above) as you can.

only DC term passes through filter

$$c_0^x = 3$$

$$y(t) = 4(x(t-2) - 3) = \boxed{4x(t-2) - 12 = y(t)}$$