

Name Solutions Mailbox \_\_\_\_\_

# **ECE-205**

## **Exam 2**

### **Winter 2015**

**Calculators and computers are not allowed. You must show your work to receive credit.**

**Problem 1** \_\_\_\_\_/13

**Problem 2** \_\_\_\_\_/13

**Problem 3** \_\_\_\_\_/20

**Problem 4** \_\_\_\_\_/30

**Problem 5** \_\_\_\_\_/24

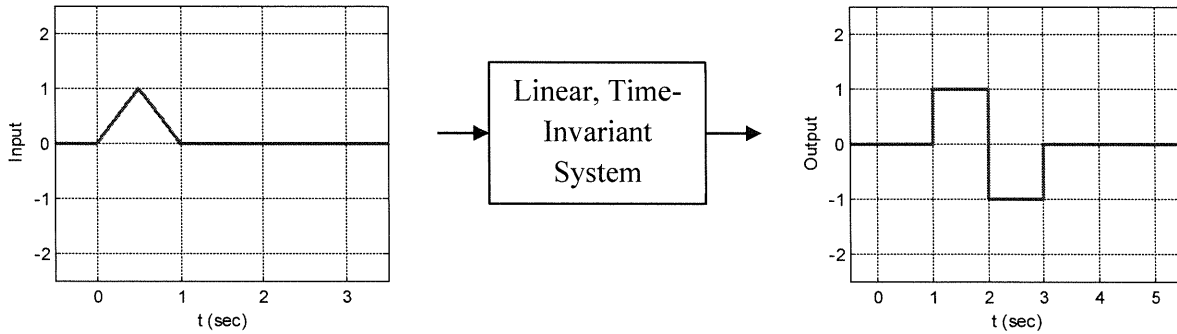
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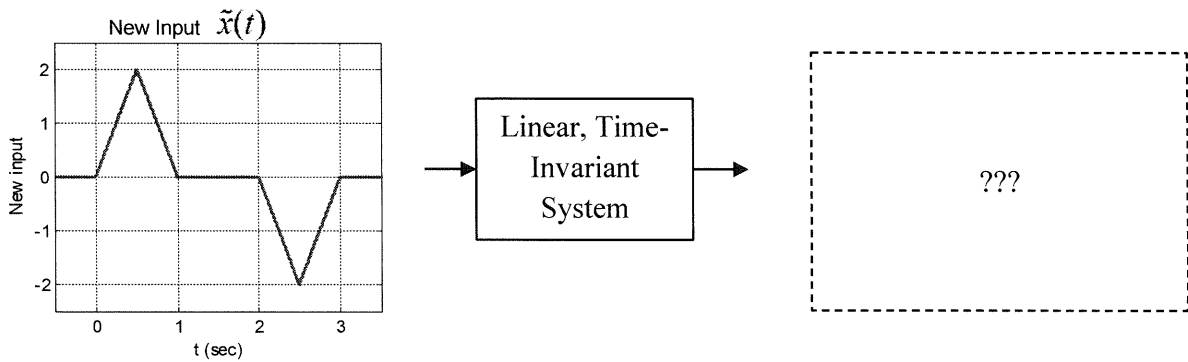
1) (13 points) Fill in the non-shaded part of the following table. You do not need to show any work.

	Linear? (Y/N)	Time Invariant? (Y/N)	BIBO Stable? (Y/N)
$y(t) = \int_{-\infty}^{t+1} \lambda^2 x(\lambda) d\lambda$	Y	N	
$y(t) = 3 + \int_{-\infty}^t e^{-(t-\lambda)} x(\lambda) d\lambda$	N	Y	
$\dot{y}(t) + \cos(t)y(t) = 3x(t)$	Y	N	
$y(t) = \dot{x}(t) + 2x(t)$	Y	Y	
$y(t) = x( t )$	Y	N	Y
$y(t) = \ln( x(t)  + 1)$			Y
$y(t) = \cos(2x(t+1))$			Y

2) (13 points) A linear and time-invariant system with the following input  $x(t)$  produces the output  $y(t)$  below:

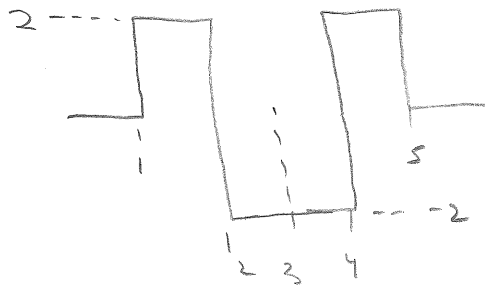


If the following new input  $\tilde{x}(t)$  is fed in, sketch the corresponding system output.  
 (Hint: Note that  $\tilde{x}(t)$  is a linear combination of  $x(t)$ )



$$\tilde{x}(t) = 2x(t) - 2x(t-2)$$

$$\tilde{y}(t) = 2y(t) - 2y(t-2)$$



3) (20 Points) Simplify the following as much as possible. Be sure to include any necessary step functions.

a)  $y(t) = \delta(t-1) * \delta(t+1)$  (Note: \* denotes the convolution)

$$y(t) = \int_{-\infty}^{\infty} \delta(t-\lambda-1) \delta(\lambda+1) d\lambda = \delta(t) \int_{-\infty}^{\infty} \delta(t-\lambda-1) d\lambda = \boxed{\delta(t)}$$

b)  $y(t) = \int_{-\infty}^{t+1} \lambda \cdot \delta(\lambda-3) d\lambda = \int_{-\infty}^{t+1} 3 \delta(\lambda-3) d\lambda$



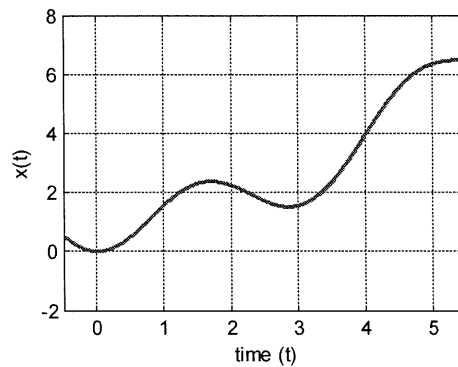
$$= \boxed{3u(t-2)}$$

c)  $y(t) = \int_{t-1}^{\infty} \delta(\lambda) \delta(t-\lambda) d\lambda = \delta(t) \int_{t-1}^{\infty} \delta(\lambda) d\lambda$



$$= \delta(t) u(1-t) = \boxed{\delta(t)}$$

For the remaining parts (d) and (e), suppose a signal  $x(t)$  is given by the following:



d) Determine  $x(t)\delta(t-4)$

$$\boxed{4 \delta(t-4)}$$

e) For what value(s) of  $t_0$  is  $x(t)\delta(t-t_0) = 0$ ?

$$\boxed{t_0 = 0} \quad \text{since } x(0) = 0$$

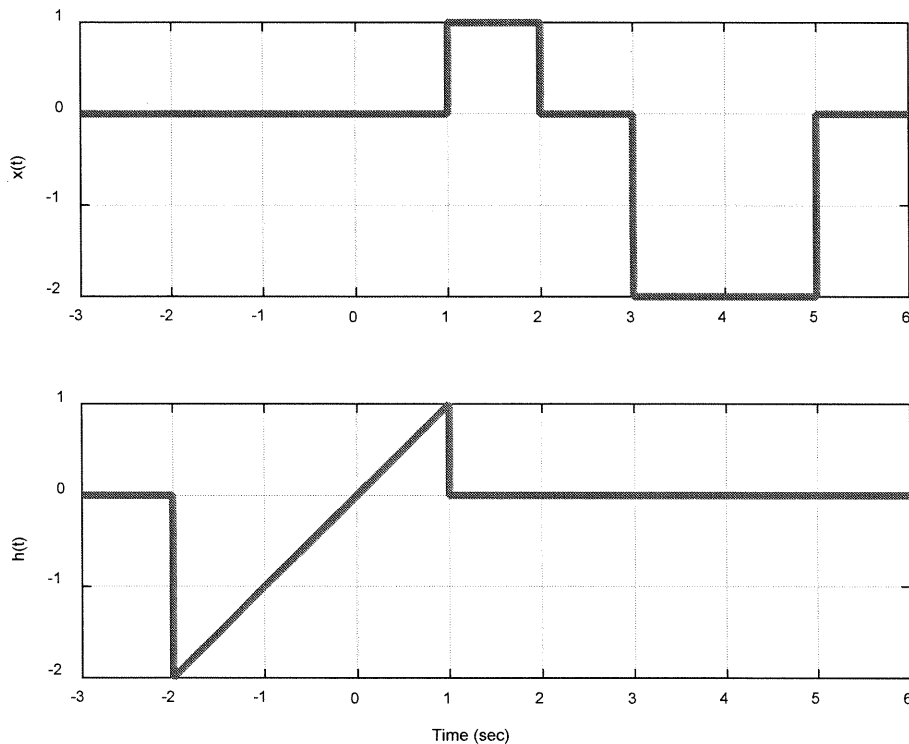
4) (30 points) Consider a linear time invariant system with impulse response given by

$$h(t) = t[u(t+2) - u(t-1)]$$

The input to the system is

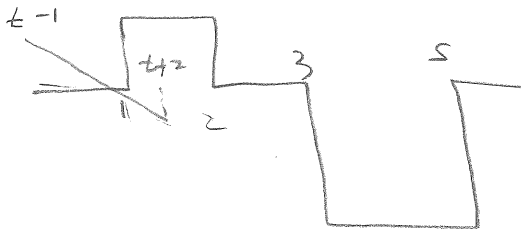
$$x(t) = [u(t-1) - u(t-2)] - 2[u(t-3) - u(t-5)]$$

These two functions are shown below:



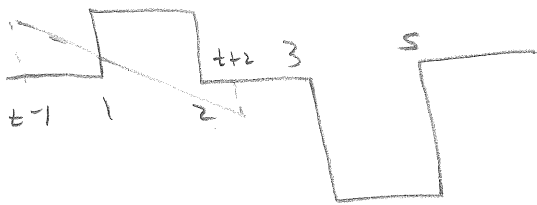
Using **graphical evaluation**, determine the output  $y(t)$ . Specifically, you must

- Flip and slide  $h(t)$ , **NOT**  $x(t)$
- Show graphs displaying both  $h(t - \lambda)$  and  $x(\lambda)$  for each region of interest
- Determine the range of  $t$  for which each part of your solution is valid
- Set up any necessary integrals to compute  $y(t)$ . Your integrals must be complete, in that they cannot contain the symbols  $x(\lambda)$  or  $h(t - \lambda)$  but must contain the actual functions.
- Your integrals **cannot contain any unit step functions**
- **DO NOT EVALUATE THE INTEGRALS!!**

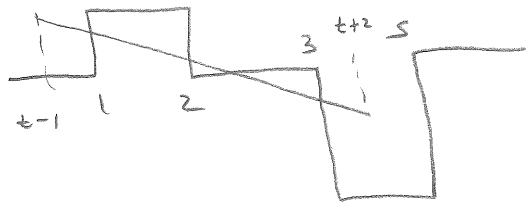


$$y(t) = 0 \quad t+2 \leq 1 \quad \text{or} \quad \boxed{t \leq -1}$$

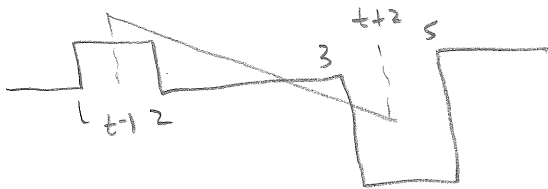
$$y(t) = \int_1^{t+2} (t-\lambda)(1) d\lambda \quad \begin{matrix} 1 \leq t+2 \leq 2 \\ \boxed{-1 \leq t \leq 0} \end{matrix}$$



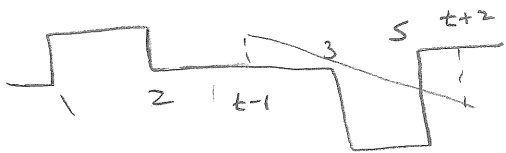
$$y(t) = \int_1^2 (t-\lambda)(1) d\lambda \quad \begin{matrix} 2 \leq t+2 \leq 3 & t-1 \leq 1 \\ \boxed{0 \leq t \leq 1} & t \leq 2 \end{matrix}$$



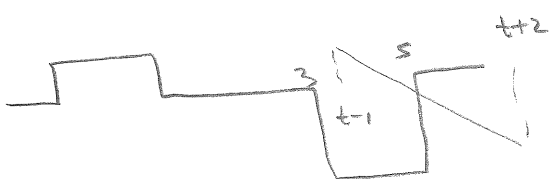
$$y(t) = \int_1^2 (t-\lambda)(1) d\lambda + \int_3^{t+2} (t-\lambda)(-2) d\lambda \quad \begin{matrix} t-1 \leq 1 & 3 \leq t+2 \leq 5 \\ t \leq 2 & 1 \leq t \leq 3 \\ \boxed{1 \leq t \leq 2} \end{matrix}$$



$$y(t) = \int_{t-1}^2 (t-\lambda)(1) d\lambda + \int_3^{t+2} (t-\lambda)(-2) d\lambda \quad \begin{matrix} 1 \leq t-1 \leq 2 & 3 \leq t+2 \leq 5 \\ 2 \leq t \leq 3 & 1 \leq t \leq 3 \\ \boxed{2 \leq t \leq 3} \end{matrix}$$



$$y(t) = \int_2^5 (t-\lambda)(-2) d\lambda \quad \begin{matrix} 2 \leq t-1 \leq 3 & t+2 \geq 5 \\ \boxed{3 \leq t \leq 4} & t \geq 3 \end{matrix}$$



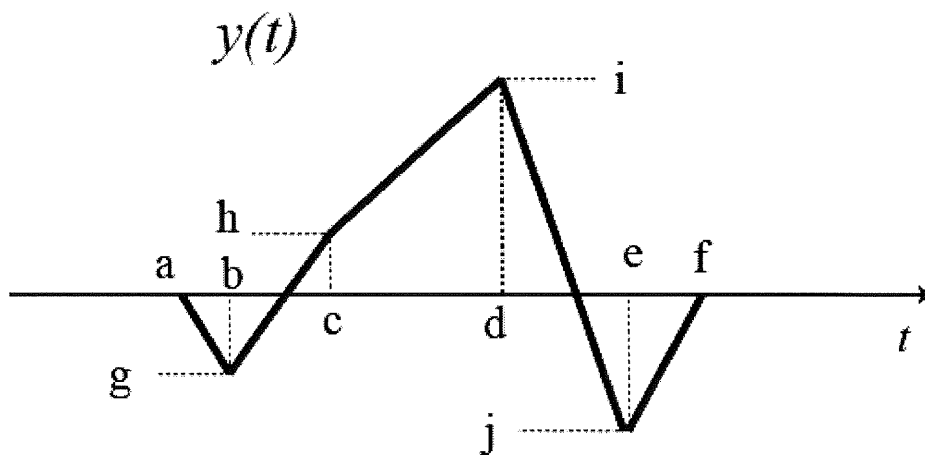
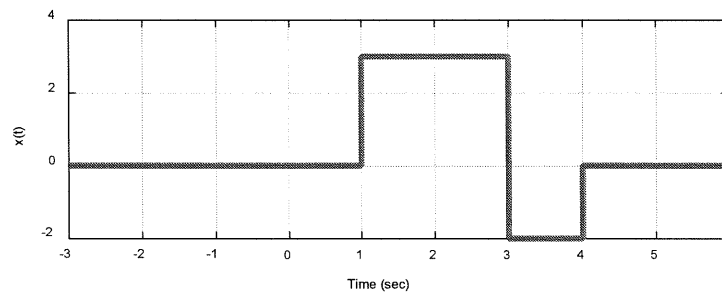
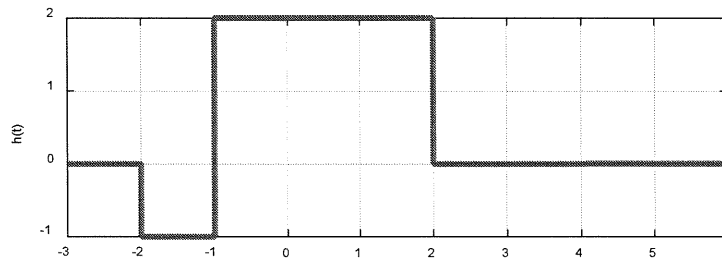
$$y(t) = \int_{t-1}^5 (t-\lambda)(-2) d\lambda \quad \begin{matrix} 3 \leq t-1 \leq 5 \\ \boxed{4 \leq t \leq 6} \end{matrix}$$

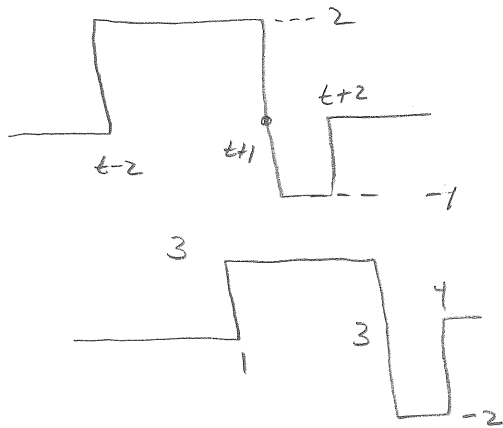
$$y(t) = 0 \quad \boxed{t \geq 6}$$

5) (24 Points) An LTI system has input, impulse response, and output as shown below. Determine numerical values for the parameters  $a-j$ . Note that parameters  $a-f$  correspond to *times* (not equally spaced, these are located where the slopes change), and  $g-i$  correspond to *amplitudes*.

Hints:

- Note that the output is not drawn to scale, it just represents the general shape of the output.
- A good way to check your answer is to flip and slide one of them, then flip and slide the other one.
- It is probably much easier to get the times correct than the amplitudes.





$$t+2=1 \quad t = \boxed{-1 = a}$$

$$t+1=1 \quad t = \boxed{0 = b}$$

$$g = 3 \cdot (-1) \cdot 1 = \boxed{-3 = g}$$

$$t+2=3 \quad t = \boxed{1 = c}$$

$$h = 3(-1) \cdot (1) + 3 \cdot (2) \cdot (1) = \boxed{3 = h}$$

$$t+2=4 \quad t = \boxed{2 = d}$$

$$i = (-2)(-1)(1) + 2 \cdot 3 \cdot 2 = \boxed{14 = i}$$

$$t-2=3 \quad t = \boxed{5 = e}$$

$$j = (2)(-2)(1) = \boxed{-4 = j}$$

$$t-2=4 \quad t = \boxed{6 = f}$$