

# **ECE-205**

## **Exam 1**

### **Winter 2010-2011**

**Calculators can only be used for simple calculations. Solving integrals, differential equations, systems of equations, etc. does not count as a simple calculation.**

**You must show your work to receive credit.**

**Problem 1** \_\_\_\_\_/20

**Problem 2** \_\_\_\_\_/30

**Problem 3** \_\_\_\_\_/18

**Problem 4-11** \_\_\_\_\_/32

**Total** \_\_\_\_\_

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1) (20 points) Assume we have a first order system with the governing differential equation

$$0.6\dot{y}(t) + y(t) = 2x(t)$$

The system has the initial value of 2, so  $y(0) = 2$ . The input to this system is

$$x(t) = \begin{cases} 0 & t < 0 \\ 1 & 0 \leq t < 1 \\ -2 & 1 \leq t < 3 \\ 3 & 3 < t \end{cases}$$

Determine the output of the system in each of the above time intervals. *Simplify your final answer as much as possible and box it. Be sure to include the correct initial value in the first interval!*

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**2) (30 points)** For the following three differential equations, assume the input is  $x(t) = 4u(t)$  (the input is equal to four for time greater than zero), and the initial conditions are  $y(0) = \dot{y}(0) = 0$

Determine the solution to each of the following differential equations and put your final answer in a box. Be sure to use the initial conditions to solve for all unknowns. You must show all your work to receive credit.

**a)**  $\ddot{y}(t) + 3\dot{y}(t) + 2y(t) = x(t)$

**b)**  $\ddot{y}(t) + 4\dot{y}(t) + 4y(t) = 8x(t)$

**c)**  $\ddot{y}(t) + 4\dot{y}(t) + 16y(t) = 4x(t)$

**3) (18 points)** The form of the under damped ( $0 < \zeta < 1$ ) solution to the second order differential equation

$$\ddot{y}(t) + 2\zeta\omega_n\dot{y}(t) + \omega_n^2y(t) = K\omega_n^2x(t)$$

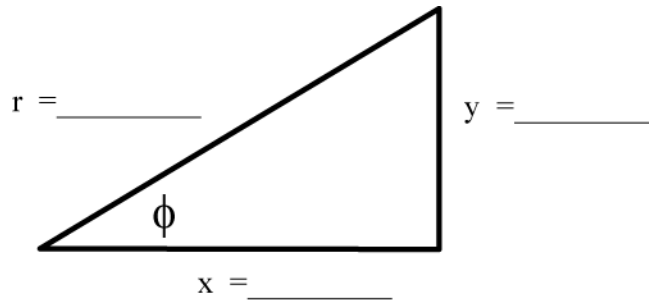
for a step input  $x(t) = Au(t)$  is

$$y(t) = KA + ce^{-\zeta\omega_n t} \sin(\omega_d t + \phi)$$

where  $c$  and  $\phi$  are constants to be determined and the damped frequency  $\omega_d = \omega_n\sqrt{1-\zeta^2}$

a) Using the initial condition  $\dot{y}(0) = 0$  show that  $\tan(\phi) = \frac{\sqrt{1-\zeta^2}}{\zeta}$

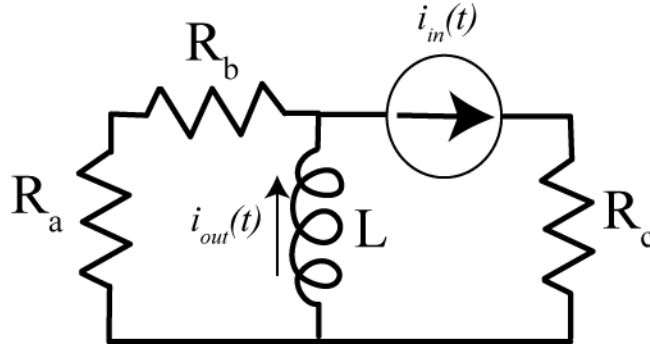
b) We can express the relationship in part a using the following triangle. Fill in the blanks and then use this triangle determine an expression for  $\sin(\phi)$ .



c) Use your answer to part b, and the initial condition  $y(0) = 0$  to determine the remaining unknown constant, and write out the complete solution for  $y(t)$ .

**Problems 4-11, 4 points each, no partial credit (32 points)**

Problems 4 and 5 refer to the following circuit



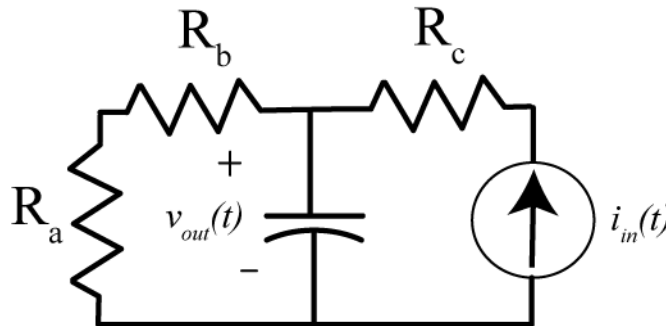
4) The Thevenin resistance seen from the ports of the inductor is

- a)  $R_{th} = R_c \parallel (R_a + R_b)$    b)  $R_{th} = R_c$    c)  $R_{th} = R_a + R_b$    d)  $R_{th} = R_a + R_b + R_c$    e) none of these

5) The static gain for the system is

- a)  $K = 1$    b)  $K = \frac{R_a + R_b}{R_a + R_b + R_c}$    c)  $K = \frac{R_c}{R_a + R_b + R_c}$    d)  $K = \frac{R_c}{R_a + R_b}$    e) none of these

Problems 6 and 7 refer to the following circuit



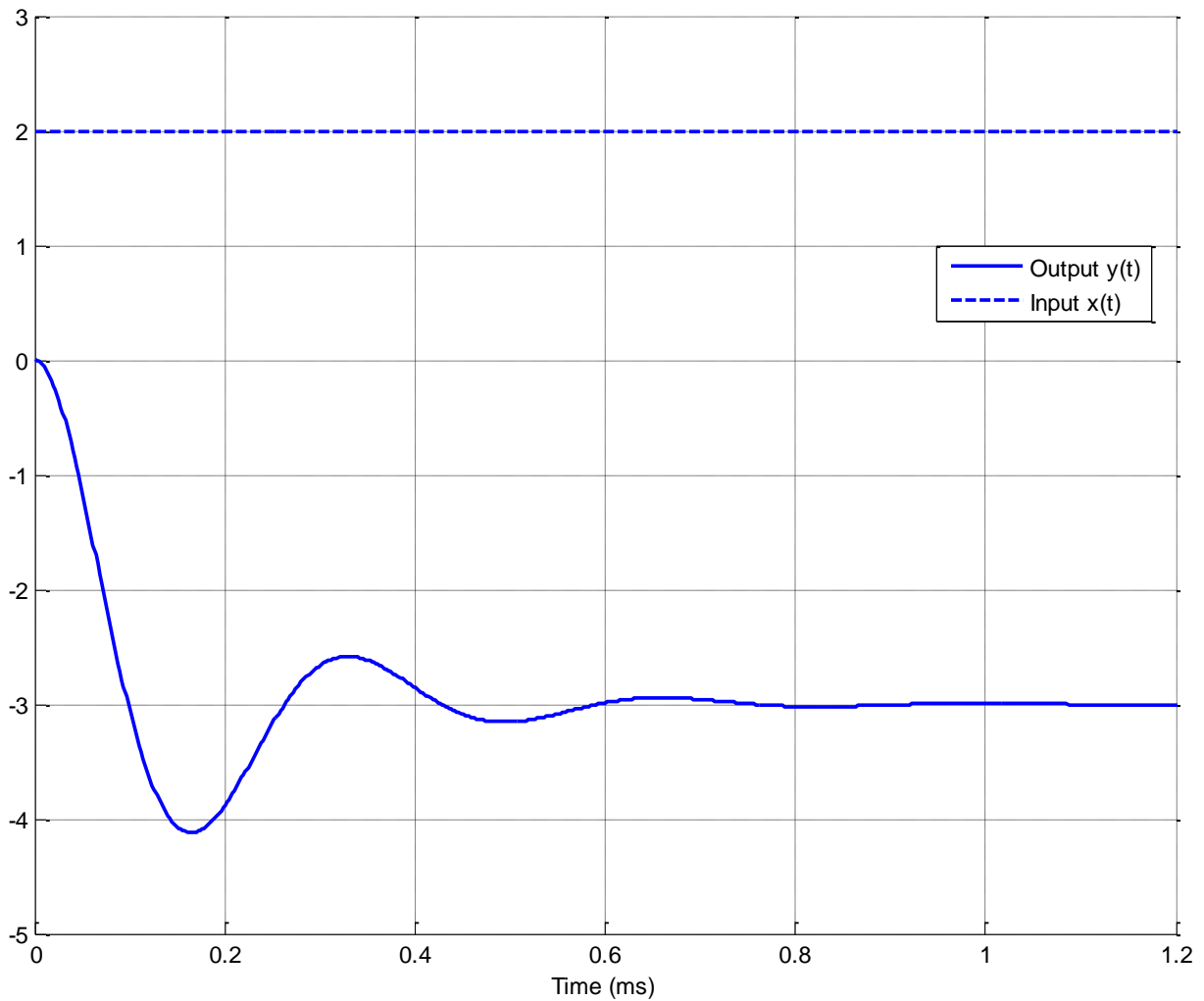
6) The Thevenin resistance seen from the ports of the capacitor is

- a)  $R_{th} = R_a + R_b$    b)  $R_{th} = R_c$    c)  $R_{th} = R_c \parallel (R_a + R_b)$    d)  $R_{th} = R_a + R_b + R_c$    e) none of these

7) The static gain for the system is

- a)  $K = 1$    b)  $K = R_c$    c)  $K = R_a + R_b$    d)  $K = R_c \parallel (R_a + R_b)$    e) none of these

Problems 8 and 9 refer the following graph showing the response of a second order system to a step input.



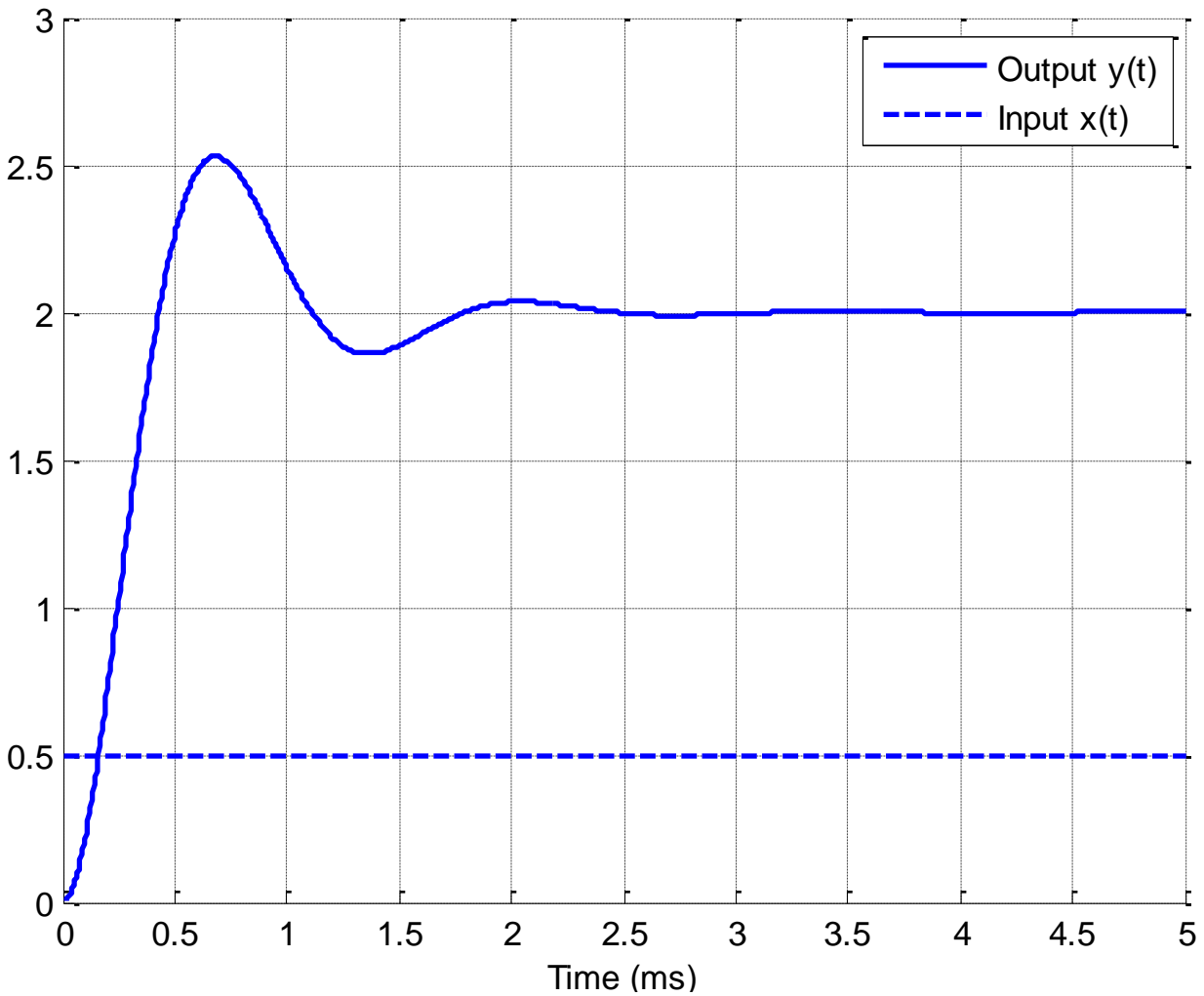
8) The percent overshoot for this system is best estimated as

- a) 400%   b) -400 %   c) 300%   d) -300 %   e) -33%   f) 33%

9) The static gain for this system is best estimated as

- a) 1.5   b) 3   c) -1.5   d) -3

Problems 10-11 refer the following graph showing the response of a second order system to a step input.



10) The percent overshoot for this system is best estimated as

- a) 400%   b) 250 %   c) 200%   d) 150 %   e) 100 %   f) 25%

11) The static gain for this system is best estimated as

- a) 1   b) 2   c) 3   d) 4

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