

ECE-205 *Solutions*

Exam 3

Winter 2010-2011

Calculators and computers are not allowed. You must show your work to receive credit.

Problem 1 _____/30

Problem 2 _____/20

Problem 3 _____/20

Problem 4 _____/15

Problems 5-9 _____/15 (3 points each)

Total _____

1) (30 points) For the following transfer functions, determine the unit step response of the system. Do not forget any necessary unit step functions.

a) $H(s) = \frac{1}{(s+1)(s+2)}$

b) $H(s) = \frac{e^{-3s}}{(s+1)^2}$

c) $H(s) = \frac{13}{s^2 + 4s + 13}$

Ⓐ $Y(s) = \frac{1}{s(s+1)(s+2)} = \frac{A}{s} + \frac{B}{s+1} + \frac{C}{s+2}$ $A = \frac{1}{2}$ $B = -1$ $C = \frac{1}{2}$

$$y(t) = \left(\frac{1}{2} - e^{-t} + \frac{1}{2} e^{-2t} \right) u(t)$$

Ⓑ $Y(s) = e^{-3s} G(s)$ $G(s) = \frac{1}{s(s+1)^2} = \frac{A}{s} + \frac{B}{s+1} + \frac{C}{(s+1)^2}$ $A = 1$
 $C = -1$
 $x \left(\lim_{s \rightarrow \infty} 0 = A + B \right)$
 $B = -1$

$$g(t) = (1 - e^{-t} - te^{-t}) u(t)$$

$$y(t) = \left[1 - e^{-(t-3)} - (t-3)e^{-(t-3)} \right] u(t-3)$$

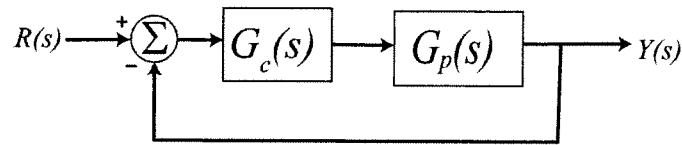
Ⓒ $Y(s) = \frac{13}{s(s^2 + 4s + 13)} = \frac{13}{s[(s+2)^2 + 3^2]} = \frac{A}{s} + \frac{B}{(s+2)^2 + 9} + \frac{C(s+2)}{(s+2)^2 + 9}$

$A = 1$ $x \left(\lim_{s \rightarrow \infty} 0 = A + C \right)$ $C = -1$

$\left(\lim_{s \rightarrow -2} \frac{13}{(-2)(9)} = \frac{1}{-2} + \frac{3B}{9} \right)$ $13 = 9 - 6B$ $4 = -6B$ $B = -\frac{2}{3}$

$$y(t) = \left[1 - \frac{2}{3} e^{-2t} \sin(3t) - e^{-2t} \cos(3t) \right] u(t)$$

2) (20 points) Consider the following simple feedback control block diagram. The plant, the thing we want to control, has the transfer function $G_p(s) = \frac{5}{s+2}$



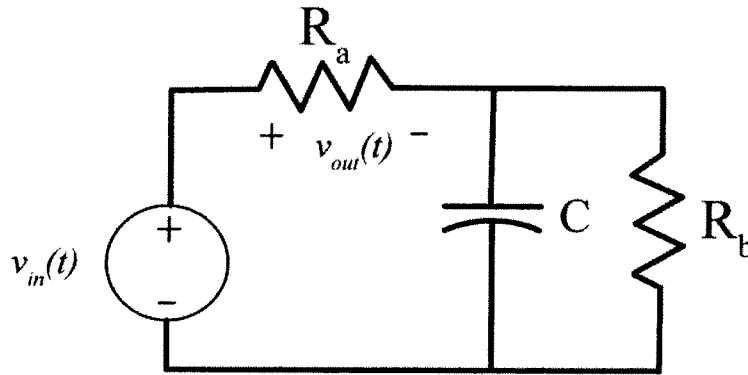
- a) Determine the settling time of the plant alone (assuming there is no feedback)
- b) For a proportional controller, $G_c(s) = k_p$, determine the closed loop transfer function $G_0(s)$ and then
- the settling time, in terms of k_p
 - the steady state error for a unit step, in terms of k_p
- c) For an integral controller, $G_c(s) = \frac{k_i}{s}$, determine the closed loop transfer function $G_0(s)$ and the steady state error for a unit step in terms of k_i

a) $T_s = \frac{4}{2} = \boxed{2 = T_s}$

b) $G_0(s) = \frac{5k_p}{s+2+5k_p}$ $T_s = \frac{4}{2+5k_p}$ $e_{ss} = \frac{2}{2+5k_p}$

c) $G_0(s) = \frac{\frac{k_i}{s} \cdot \frac{5}{s+2}}{1 + \frac{k_i}{s} \cdot \frac{5}{s+2}} = \frac{5k_i}{s^2 + 2s + 5k_i} = G_0(s)$ $e_{ss} = 0$ since $G_0(0) = 1$

3) (20 points) For the following circuit determine the transfer function and the corresponding impulse response.



$$\frac{V_{out}(s)}{R_a} = \frac{V_{in}(s) - V_{out}(s)}{1/Cs} + \frac{V_{in}(s) - V_{out}(s)}{R_b}$$

$$V_{out}(s) \left[\frac{1}{R_a} + \frac{1}{R_b} + Cs \right] = V_{in}(s) \left[Cs + \frac{1}{R_b} \right]$$

$$V_{out}(s) \left[\frac{R_b + R_a + R_a R_b Cs}{R_a R_b} \right] = V_{in}(s) \left[\frac{R_b Cs + 1}{R_b} \right]$$

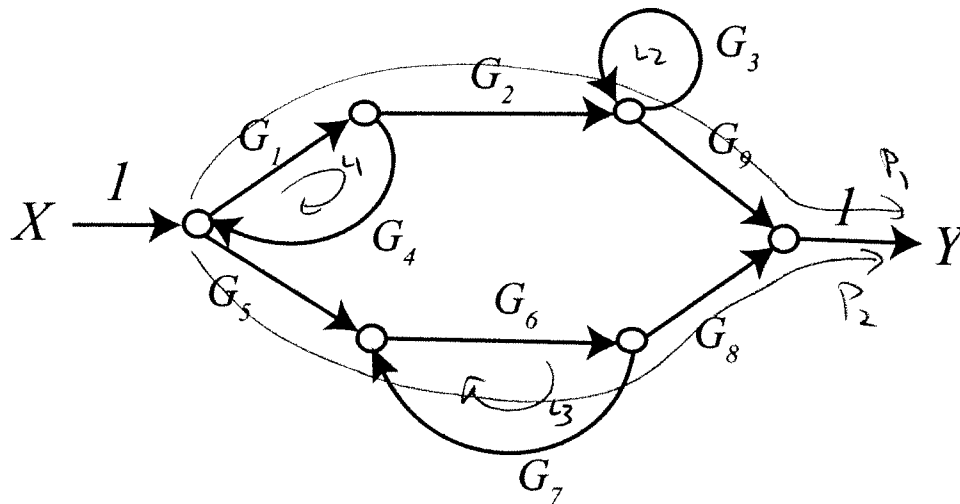
$$\frac{V_{out}(s)}{V_{in}(s)} = H(s) = \left[\frac{R_b Cs + 1}{R_b} \right] \left[\frac{R_a R_b}{R_a + R_b + R_a R_b Cs} \right] = \boxed{\frac{R_a R_b Cs + R_a}{R_a R_b Cs + R_a + R_b^2} = H(s)}$$

$$\frac{R_a R_b Cs + R_a}{R_a R_b Cs + R_a + R_b^2} = \frac{1}{\frac{R_a R_b Cs + R_a}{R_a R_b Cs + R_a + R_b^2} - R_b}$$

$$H(s) = 1 - \frac{R_b}{R_a R_b Cs + R_a + R_b^2} = 1 - \frac{R_b}{R_a R_b C \left(s + \frac{R_a + R_b^2}{R_a R_b C} \right)} = 1 - \frac{1}{R_a C \left(s + \frac{R_a + R_b^2}{R_a R_b C} \right)}$$

$$\boxed{h(t) = \delta(t) - \frac{1}{R_a C} e^{-\left(\frac{R_a + R_b^2}{R_a R_b C} \right) t} u(t)}$$

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 4) (20 points) For the following signal flow diagram



Determine the system transfer function using Mason's gain rule. You must clearly indicate all of the paths, the loops, the determinant and the cofactors, but you do not need to simplify your final answer (it can be written in terms of the P_i, L_i , and Δ_i)

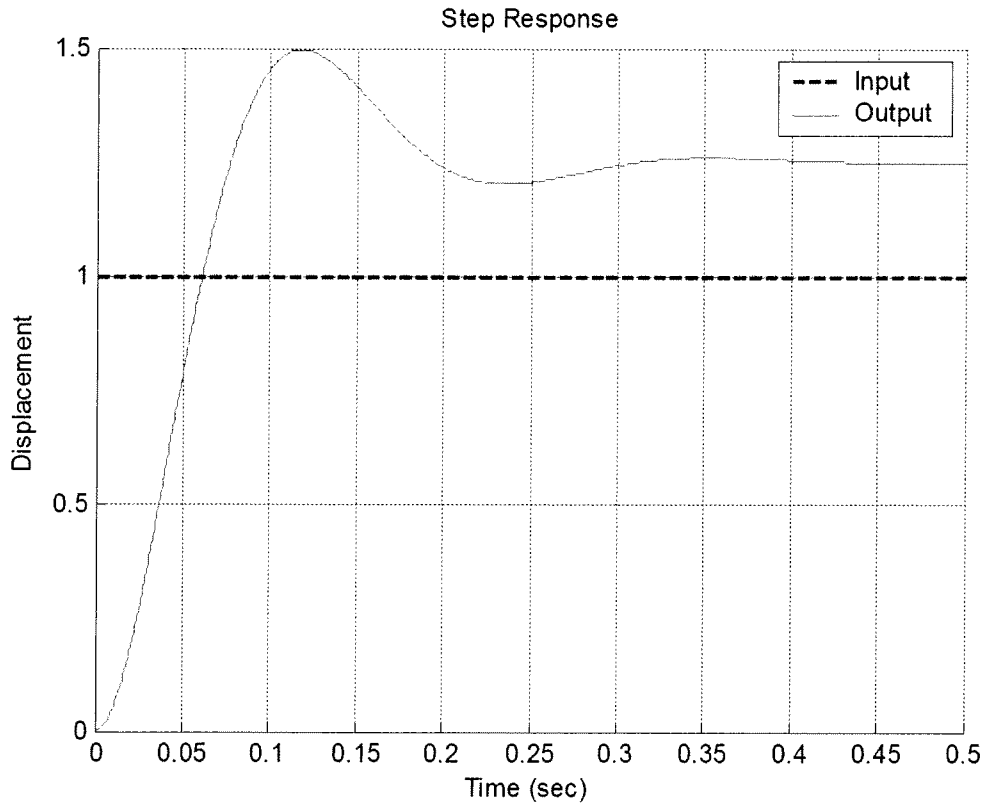
$$P_1 = G_1 G_2 G_9 \quad P_2 = G_5 G_6 G_8 \quad L_1 = G_3 \quad L_2 = G_7 \quad L_3 = G_4$$

$$\Delta = 1 - (L_1 + L_2 + L_3) + (L_1 L_2 + L_1 L_3 + L_2 L_3) - (L_1 L_2 L_3)$$

$$\Delta_1 = 1 - L_3 \quad \Delta_2 = 1 - L_2$$

$$G_0 = \frac{Y}{X} = \frac{P_1 \Delta_1 + P_2 \Delta_2}{\Delta}$$

Problems 5 and 6 refer to the unit step response of a system, shown below



5) The best estimate of the steady state error for a unit step input is

- a) 0.50 b) 0.25 **c) -0.25** d) 0.0 e) impossible to determine

6) The best estimate of the percent overshoot is **a) 20%** b) 50% c) 25% d) 150%

$$\frac{1.5 - 1.25}{1.25} = \frac{0.25}{1.25} = \frac{1}{5} = 20\%$$

7) How many of the following transfer functions represents (asymptotically) **stable** systems?

$$G_a(s) = \frac{s+1}{s-1}$$

$$G_b(s) = \frac{1}{s(s+1)}$$

$$G_c(s) = \frac{s}{s^2-1}$$

$$G_d(s) = \frac{s+1}{(s+1+j)(s+1-j)}$$

$$G_e(s) = \frac{(s-1-j)(s-1+j)}{s}$$

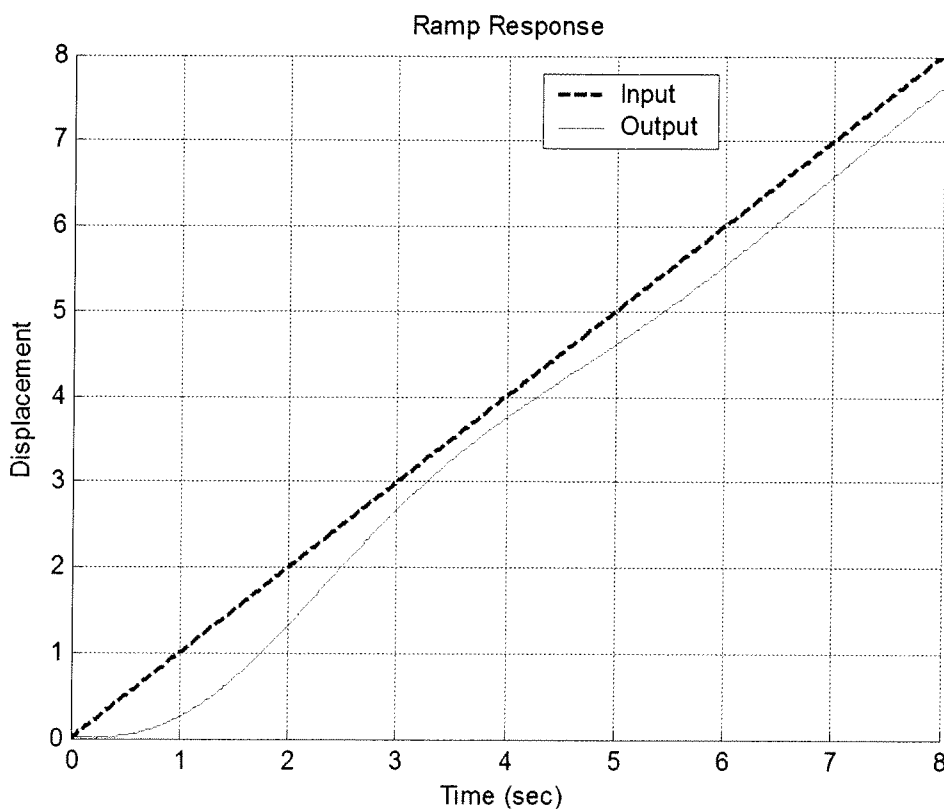
$$G_f(s) = \frac{(s-1-j)(s-1+j)}{(s+1-j)(s+1+j)}$$

- a) 0 b) 1 **c) 2** d) 3 e) 4 f) 5 g) 6

8) For the **unit ramp response** of a system shown below, the best estimate of the **steady state error** is

$$8 - 7.5 = 0.5$$

- a) 0.8 b) -0.8 **c) 0.5** d) -0.5



9) For a plant with transfer function $G_p(s) = \frac{5}{(s+4)(s+2)}$ The (2%) settling time for this plant is

- a) 1 seconds **b) 2 seconds** c) 3 seconds d) 4 seconds e) none of these

$$\frac{4}{4}, \frac{4}{2} \Rightarrow 2$$