

ECE-205 : Dynamical Systems

Homework #7

Due : Thursday January 28 at the beginning of class

1) In this problem we will derive some useful properties of Laplace transforms starting from the basic relationship

$$X(s) = \int_{0^-}^{\infty} x(t)e^{-st} dt$$

a) Let's assume $x(t)$ is a causal signal (it is zero for $t < 0$). We can then write $x(t) = x(t)u(t)$ to emphasize the fact that $x(t)$ is zero before time zero. If there is a delay in the signal and it starts at time t_0 , then we can write the signal as $x(t-t_0) = x(t-t_0)u(t-t_0)$ to emphasize the fact that the signal is zero before time t_0 .

Using the definition of the Laplace transform and a simple change of variable in the integral, show that $\mathcal{L}\{x(t-t_0)u(t-t_0)\} = X(s)e^{-st_0}$

b) Using the results from part **a**, determine the inverse Laplace transform of $X(s) = \frac{e^{-3s}}{(s+2)(s+4)}$

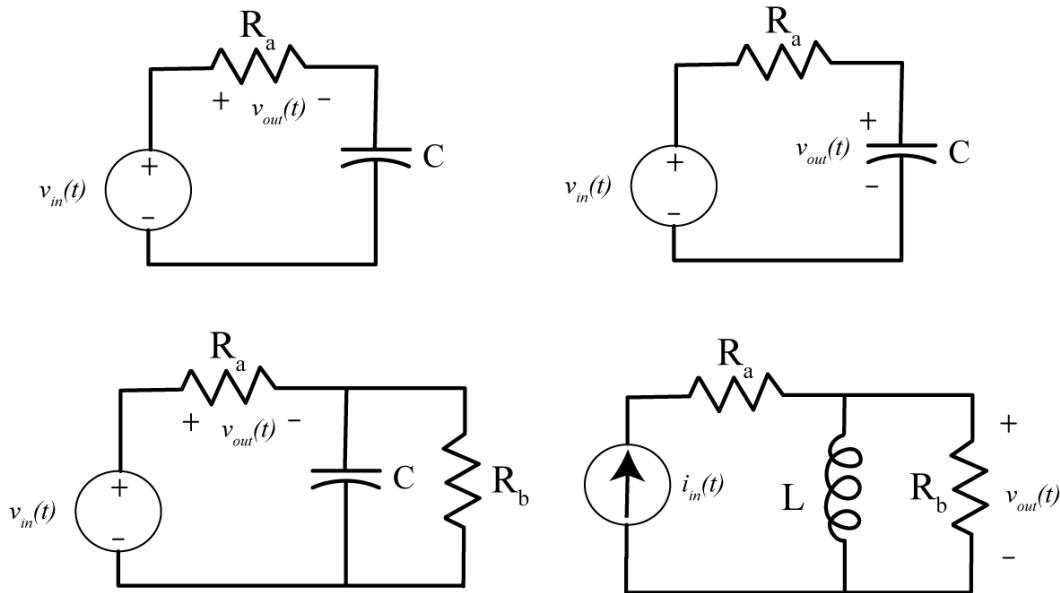
Answer: $x(t) = \frac{1}{2} [e^{-2(t-3)} - e^{-4(t-3)}] u(t-3)$

c) Starting from the definition of the Laplace transform, show that $\mathcal{L}\{tx(t)\} = -\frac{dX(s)}{ds}$.

d) Using the result from part **c**, and the transform pair $x(t) = e^{-at}u(t) \leftrightarrow X(s) = \frac{1}{s+a}$, and some simple calculus, show that

$$\mathcal{L}\{te^{-at}u(t)\} = \frac{1}{(s+a)^2}, \mathcal{L}\{t^2e^{-at}u(t)\} = \frac{2}{(s+a)^3}, \mathcal{L}\{t^3e^{-at}u(t)\} = \frac{6}{(s+a)^4}$$

2) For the following circuits, determine the transfer function and the corresponding impulse responses.



Scrambled Answers:

$$h(t) = R_b \delta(t) - \frac{R_b^2}{L} e^{-tR_b/L} u(t), \quad h(t) = \delta(t) - \frac{1}{R_a C} e^{-t/R_a C} u(t), \quad h(t) = \frac{1}{R_a C} e^{-t/R_a C} u(t), \quad h(t) = \left[1 - \frac{1}{R_a C} e^{-t \frac{R_a + R_b}{CR_a R_b}} \right] u(t)$$

3) For the following impulse responses and inputs, compute the system output using transfer functions.

a) $h(t) = e^{-t} u(t)$, $x(t) = u(t)$ **b)** $h(t) = e^{-2t} u(t)$, $x(t) = \delta(t)$ **c)** $h(t) = e^{-2(t-1)} u(t-1)$, $x(t) = e^{-2t} u(t)$

d) $h(t) = e^{-t} u(t)$, $x(t) = (t-1)u(t-1)$ **e)** $h(t) = e^{-2t} u(t)$, $x(t) = u(t) - u(t-1)$

f) $h(t) = e^{-2(t-1)} u(t-1)$, $x(t) = te^{-3t} u(t)$

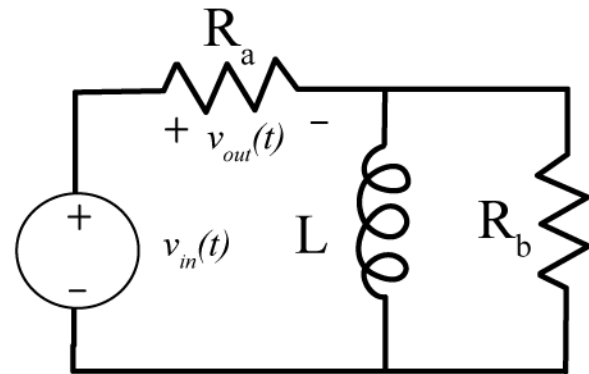
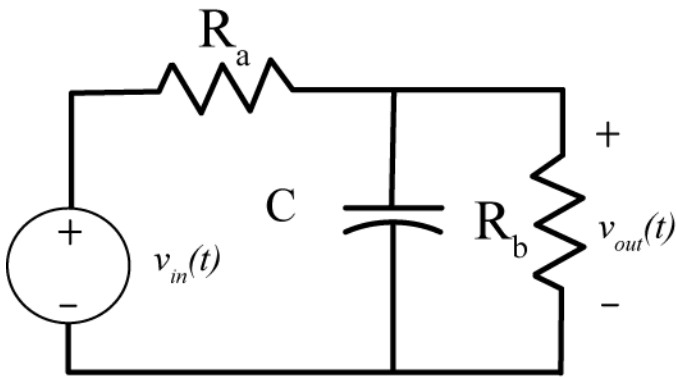
Scrambled Answers :

$$y(t) = \frac{1}{2} [1 - e^{-2t}] u(t) - \frac{1}{2} [1 - e^{-2(t-1)}] u(t-1), \quad y(t) = (1 - e^{-t}) u(t), \quad y(t) = (t-1) e^{-2(t-1)} u(t-1)$$

$$y(t) = e^{-2t} u(t), \quad y(t) = [-1 + (t-1) + e^{-(t-1)}] u(t-1),$$

$$y(t) = [e^{-2(t-1)} - e^{-3(t-1)} - (t-1)e^{-3(t-1)}] u(t-1)$$

4) For the following circuits, determine an expression for the output $V_{out}(s)$ in terms of the ZSR and ZIR. Do not assume the initial conditions are zero. Also determine the system transfer function.



Answers:

$$V_{out}(s) = \left[\frac{R_b}{R_a R_b C s + R_a + R_b} \right] V_{in}(s) + \left[\frac{R_a R_b C}{R_a R_b C s + R_a + R_b} \right] v(0^-)$$

$$V_{out}(s) = \left[\frac{R_a (R_b + L s)}{(R_a + R_b) L s + R_a R_b} \right] V_{in}(s) + \left[\frac{R_a R_b L}{(R_a + R_b) L s + R_a R_b} \right] i(0^-)$$