

ECE-205

Exam 1

Spring 2013

Calculators can only be used for simple calculations. Solving integrals, differential equations, systems of equations, etc. does not count as a simple calculation.

You must show your work to receive credit.

- Problem 1** _____/16
- Problem 2** _____/16
- Problem 3** _____/14
- Problem 4** _____/10
- Problem 5** _____/12
- Problem 6** _____/16
- Problem 7-10** _____/16

Total _____

1) (16 points) Assume we have a first order system with the governing differential equation

$$0.2\dot{y}(t) + y(t) = 3x(t)$$

The system has the initial value of 0.4, so $y(0) = 0.4$. The input to this system is

$$x(t) = \begin{cases} 0 & t < 0 \\ 0.2 & 0 \leq t < 0.6 \\ 0 & 0.6 \leq t \end{cases}$$

- a) Determine the output of the system in each of the above time intervals. *Simplify your final answer as much as possible and box it. Be sure to include the correct initial value in the first interval!*
- b) Make a sketch of $y(t)$. (I am looking mostly at the shape of $y(t)$ from 0 to 0.6 and from 0.6 on.)

$$y(t) = [y(t_0) - KA]e^{-(t-t_0)/\tau} + KA$$

a) $0 \leq t < 0.6$ $y(0) = 0.4$ $KA = (3)(0.2) = 0.6$ $\tau = 0.2$

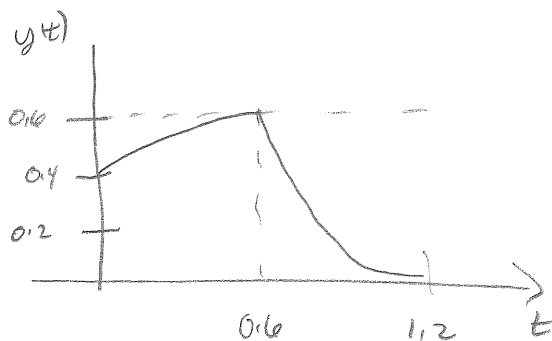
$$y(t) = [0.4 - 0.6]e^{-t/0.2} + 0.6 = \boxed{-0.2e^{-t/0.2} + 0.6 = y(t)}$$

$0.6 \leq t$ $y(0.6) = -0.2e^{-3} + 0.6 = 0.59$

$$KA = (3)(0) = 0$$

$$y(t) = [0.59 - 0]e^{-(t-0.6)/0.2} + 0 = \boxed{0.59e^{-(t-0.6)/0.2} = y(t)}$$

b)



2) (16 points) For the following three differential equations, assume the input is $x(t) = 3u(t)$ (the input is equal to one for time greater than zero), and the initial conditions are $y(0) = \dot{y}(0) = 0$

Determine the solution to each of the following differential equations and put your final answer in a box. Be sure to use the initial conditions to solve for all unknowns. You must show all your work to receive credit, you cannot simply use the formula from problem 3.

a) $\ddot{y}(t) + 6\dot{y}(t) + 9y(t) = 9x(t)$

$$r^2 + 6r + 9 = 0$$

$$9y_f = 9 \cdot 3$$

$$(r+3)^2 = 0$$

$$y_f = 3$$

$$y(t) = 3 + c_1 e^{-3t} + c_2 t e^{-3t}$$

$$y(0) = 0 = 3 + c_1 \quad \boxed{c_1 = -3}$$

$$\dot{y}(t) = 0 - 3c_1 e^{-3t} + c_2 e^{-3t} - 3c_2 t e^{-3t} \quad \dot{y}(0) = -3c_1 + c_2 = 0 \quad c_2 = 3c_1 = \boxed{-9 = c_2}$$

$$\boxed{y(t) = 3 - 3e^{-3t} - 9te^{-3t}}$$

b) $\ddot{y}(t) + 4\dot{y}(t) + 13y(t) = 26x(t)$

$$r^2 + 4r + 13 = 0$$

$$13y_f = 26 \cdot 3$$

$$(r+2)^2 + 3^2 = 0$$

$$y_f = 6$$

$$r = -2 \pm j3$$

$$y(t) = 6 + c e^{-2t} \sin(3t + \theta)$$

$$y(0) = 0 = 6 + c \sin(\theta)$$

$$\dot{y}(t) = 0 - 2c e^{-2t} \sin(3t + \theta) + 3c e^{-2t} \cos(3t + \theta)$$

$$\dot{y}(0) = 0 = -2 \sin(\theta) + 3 \cos(\theta)$$

$$\tan(\theta) = \frac{3}{2} \quad \boxed{\theta = 56.31^\circ}$$

$$c = \frac{-6}{\sin(56.31^\circ)} = \boxed{-7.21 = c}$$

$$\boxed{y(t) = 6 - 7.21 e^{-2t} \sin(3t + 56.31^\circ)}$$

3) (14 points) The form of the under damped ($0 < \zeta < 1$) solution to the second order differential equation

$$\ddot{y}(t) + 2\zeta\omega_n\dot{y}(t) + \omega_n^2 y(t) = K \omega_n^2 x(t)$$

for a step input $x(t) = Au(t)$ is

$$y(t) = KA + ce^{-\zeta\omega_n t} \sin(\omega_d t + \phi)$$

where c and ϕ are constants to be determined and the damped frequency $\omega_d = \omega_n \sqrt{1 - \zeta^2}$

a) Using the initial condition $\dot{y}(0) = 0$ show that $\tan(\phi) = \frac{\sqrt{1 - \zeta^2}}{\zeta}$

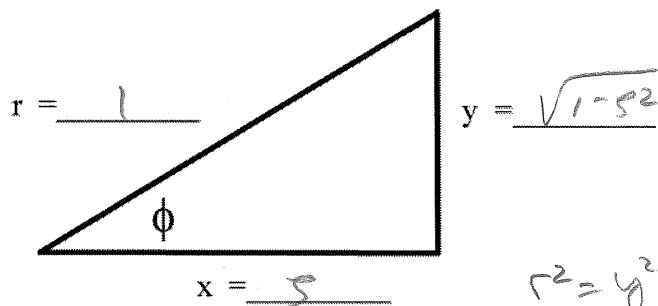
$$\dot{y}(t) = 0 - \zeta\omega_n c e^{-\zeta\omega_n t} \sin(\omega_d t + \phi) + \omega_d c e^{-\zeta\omega_n t} \cos(\omega_d t + \phi)$$

$$\dot{y}(0) = 0 = -\zeta\omega_n c \sin(\phi) + \omega_d c \cos(\phi)$$

$$\tan(\phi) = \frac{\omega_d}{\zeta\omega_n} = \frac{\omega_n \sqrt{1 - \zeta^2}}{\omega_n \zeta}$$

$$\boxed{\tan(\phi) = \frac{\sqrt{1 - \zeta^2}}{\zeta}}$$

b) We can express the relationship in part a using the following triangle. Fill in the blanks and then use this triangle determine an expression for $\sin(\phi)$.



$$r^2 = y^2 + x^2 = 1 - \zeta^2 + \zeta^2 = 1$$

$$\boxed{\sin(\phi) = \sqrt{1 - \zeta^2}}$$

c) Use your answer to part b, and the initial condition $y(0) = 0$ to determine the remaining unknown constant, and write out the complete solution for $y(t)$.

$$y(0) = 0 = KA + c \sin(\phi) = KA + c \sqrt{1 - \zeta^2} \quad c = \frac{-KA}{\sqrt{1 - \zeta^2}}$$

$$\boxed{y(t) = KA \left[1 - \frac{e^{-\zeta\omega_n t}}{\sqrt{1 - \zeta^2}} \sin(\omega_d t + \phi) \right]}$$

4) (10 points) For the following first order differential equation,

$$3\dot{y}(t) + y(t) = x^2(t)$$

determine an expression for the output assuming $t_0 = 0$ and $y(t_0) = y(0) = 1$.

$$\dot{y}(t) + \frac{1}{3}y(t) = \frac{1}{3}x^2(t)$$

$$\frac{d}{dt}[y(t)e^{t/3}] = \frac{1}{3}e^{t/3}x^2(t)$$

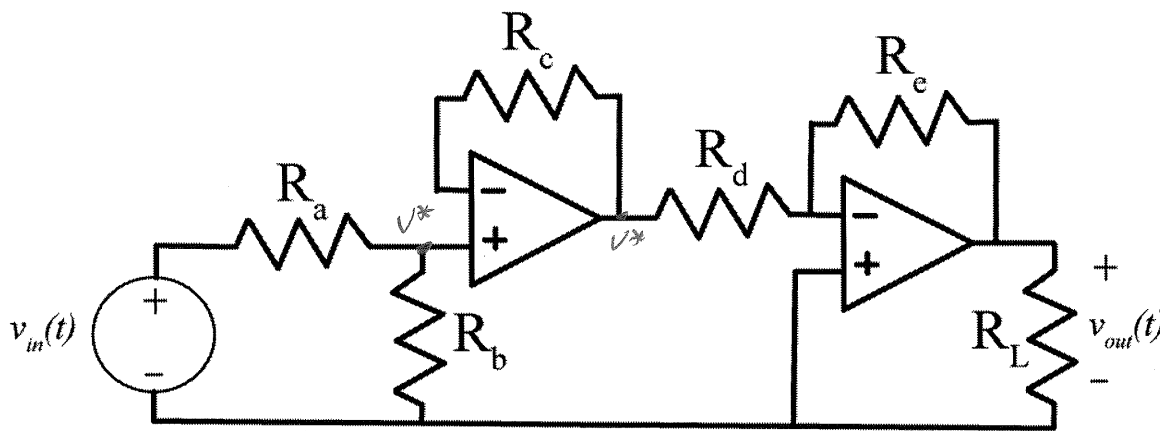
$$y(t)e^{t/3} - y(t_0)e^{t_0/3} = \frac{1}{3} \int_{t_0}^t e^{\tau/3} x^2(\tau) d\tau$$

$$y(t)e^{t/3} - 1 = \frac{1}{3} \int_0^t e^{\tau/3} x^2(\tau) d\tau$$

$$y(t)e^{t/3} = 1 + \frac{1}{3} \int_0^t e^{\tau/3} x^2(\tau) d\tau$$

$$y(t) = e^{-t/3} + \frac{1}{3}e^{-t/3} \int_0^t e^{\tau/3} x^2(\tau) d\tau$$

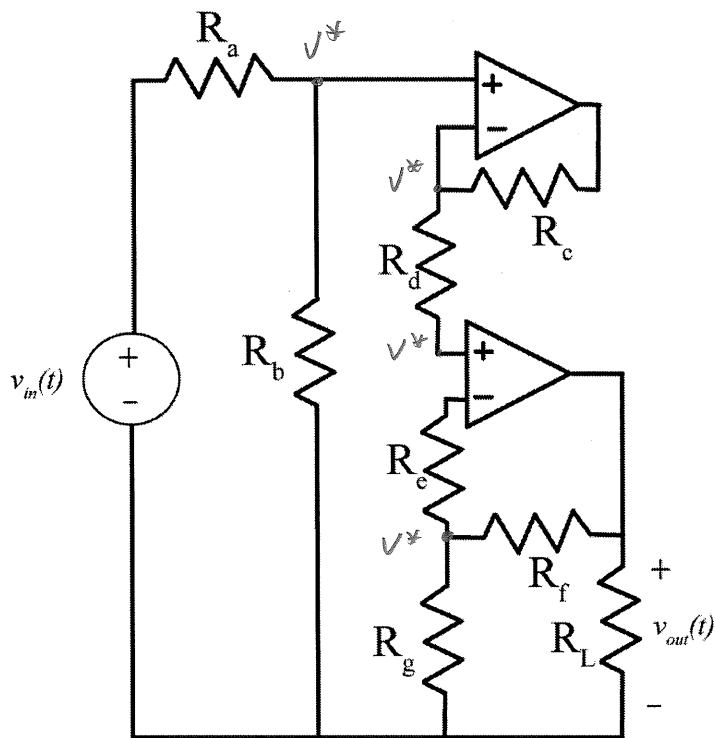
5) (12 points) For the following two op-amps circuits, we can write $v_{out}(t) = G v_{in}(t)$. Determine the value of G for each circuit.



$$V^* = \frac{V_{in} R_b}{R_a + R_b} \quad \frac{V^*}{R_d} + \frac{V_{out}}{R_e} = 0 \quad V_{out} = -\frac{R_e}{R_d} V^*$$

$$= \left(-\frac{R_e}{R_d} \frac{R_b}{R_a + R_b} \right) V_{in}$$

$$G = -\frac{R_e}{R_d} \frac{R_b}{R_a + R_b}$$



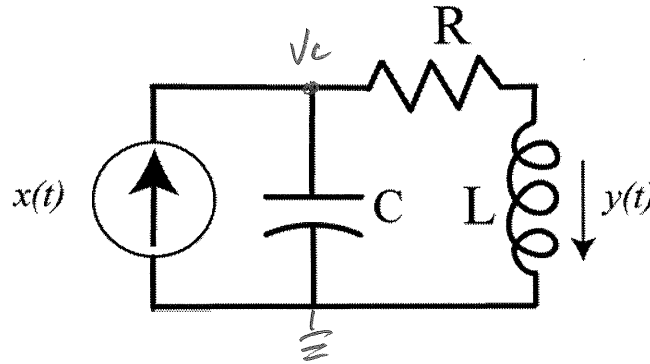
$$V^* = \frac{V_{in} R_b}{R_a + R_b}$$

$$\frac{V_{out} R_g}{R_g + R_f} = V^* = \frac{R_b}{R_a + R_b} V_{in}$$

$$V_{out} = \left(\frac{R_g + R_f}{R_g} \frac{R_b}{R_a + R_b} \right) V_{in}$$

$$G = \frac{R_g + R_f}{R_g} \frac{R_b}{R_a + R_b}$$

6) (16 points) For the second order circuit below,



Derive the governing second order differential equation for the output $y(t)$ and input $x(t)$. You do not need to put the equation in standard form.

$$x(t) = C \frac{dv_c(t)}{dt} + y(t) \quad v_c(t) - y(t)R - L \dot{y}(t) = 0$$

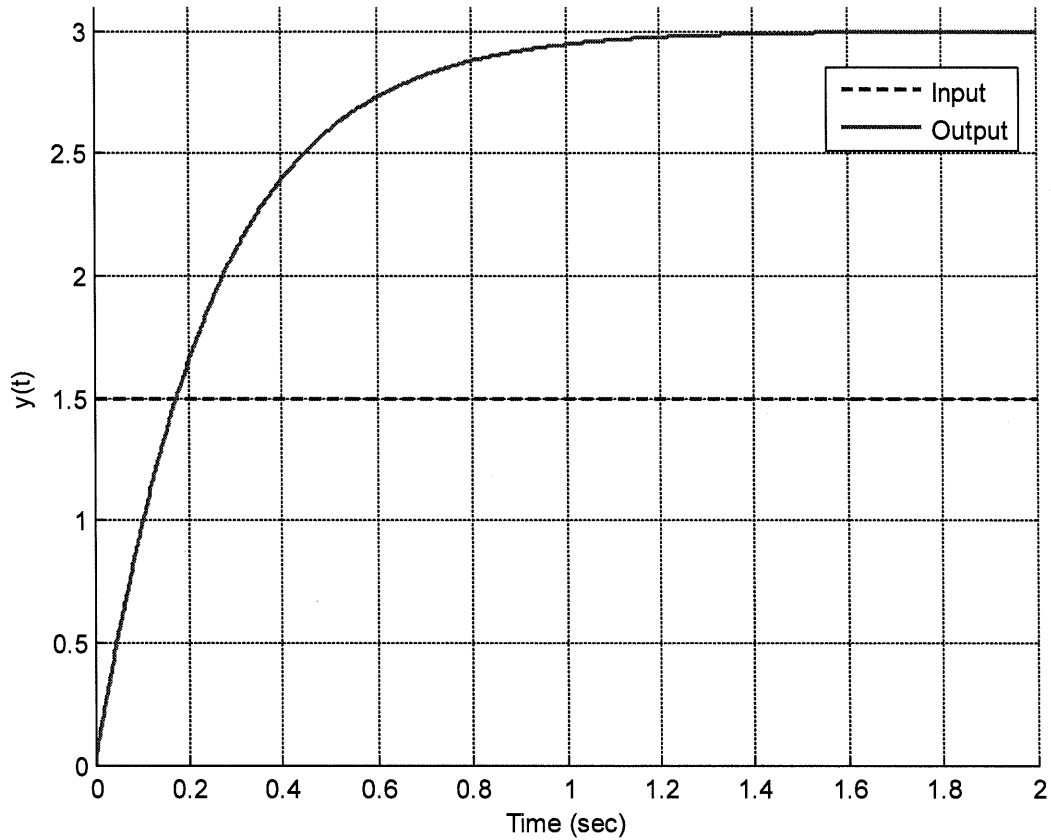
$$v_c(t) = y(t)R + L \dot{y}(t)$$

$$x(t) = C [\dot{y}(t)R + L \ddot{y}(t)] + y(t)$$

$$x(t) = LC \ddot{y}(t) + RC \dot{y}(t) + y(t)$$

Problems 7-10, 4 points each (16 points)

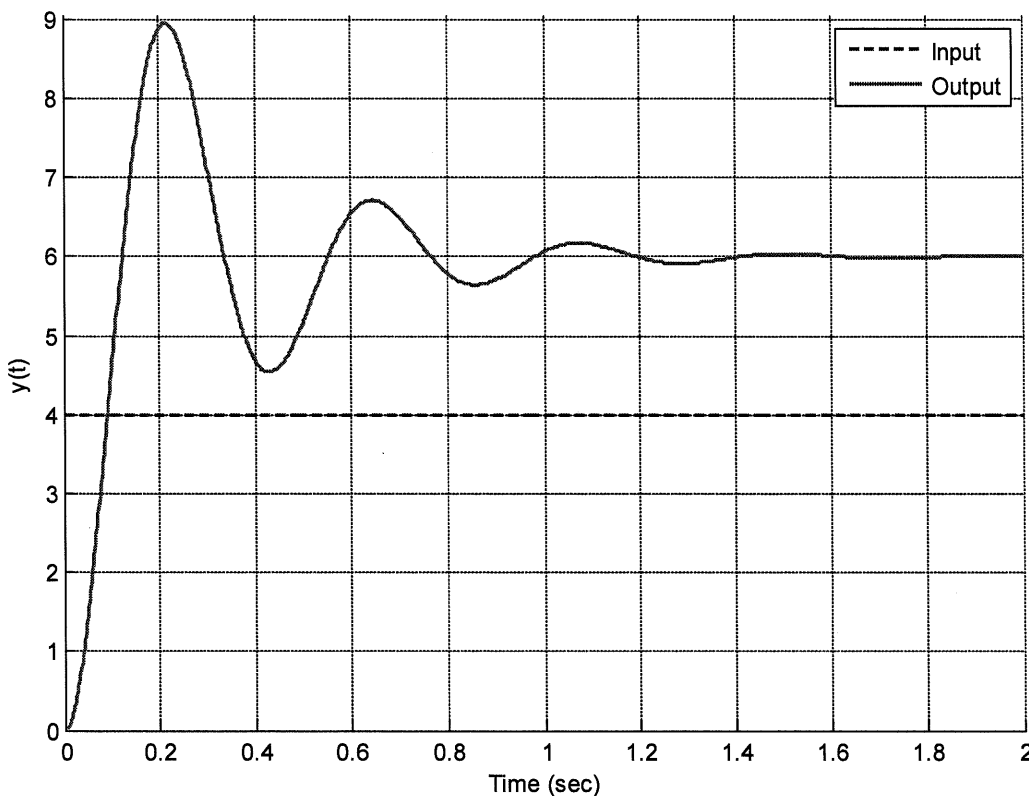
For problems 7 and 8, refer to the following graph showing the input and output of a first order system. For this system the input is a step of amplitude 1.5.



7) What is the static gain? $R(1.5) = 3$ $K = 2$

8) What is the time constant? $T_S = 4\tau = 1 \text{ sec}$ $\tau = 0.25 \text{ sec}$

For problems 9 and 10, refer to the following graph showing the input and output of a second order system. For this system the input is a step of amplitude 4.



9) What is the static gain of the system?

$$K(4) = 6 \quad K = \frac{6}{4} = 1.5 = K$$

10) What is the percent overshoot?

$$\frac{9-4}{4} \times 100\% = 50\% = PO$$