

Dynamical Systems Dynamical Systems Spring 2010 - 2011

Midterm Exam 2

# **ECE205 Dynamical Systems**

Midterm Exam 2 4/14/11

NAME: \_\_\_\_\_ CM: \_\_\_\_\_

- You must **<u>show work</u>** to receive partial and full credit.
- Put a box around your final answer and it must include units, if necessary.
- Time allowed : 50 minutes.

Question #	Possible Points	Awarded Points		
1	10			
2	30			
3	15			
4	15			
5	30			
Total	100			





### 1) (10 points)

A linear time invariant (LTI) system has the following input, x(t) and the impulse response, h(t). The output of the system, y(t), is the convolution of the impulse response with the input, y(t) = h(t) \* x(t).



a) Is the system causal, why or why not?

b) Is the system BIBO stable, why or why not?







2) (30 points) Consider a linear time invariant system with impulse response given by

$$h(t) = (1-t^2)[u(t+1)-u(t-1)]$$

The input to the system is given by x(t) = [u(t-1) - u(t-2)] - 2[u(t-3) - u(t-4)]



Using *graphical evaluation*, determine the output y(t) Specifically, you must

- Flip and slide h(t), **<u>NOT</u>** x(t)
- Show graphs displaying both  $h(t \lambda)$  and  $x(\lambda)$  for each region of interest
- Determine the range of t for which each part of your solution is valid
- Set up any necessary integrals to compute y(t). Your integrals must be complete, in that they cannot contain the symbols  $x(\lambda)$  or  $h(t \lambda)$  but must contain the actual functions.
- Your integrals cannot contain any unit step functions
- DO NOT EVALUATE THE INTEGRALS!!

### Problem 2 continuted on the next page.





## 2) continued





**3)** (15 points) The LTI system in Figure 1 has the following input, x(t), impulse response, h(t), and output, y(t). Use the convolution to determine the time parameters (*a*, *b*, *c*, *d*) and the amplitude, e. Note that these figures are not drawn to scale and you must show detailed work to justify your answer.

$$x(t) \rightarrow h(t) \rightarrow y(t)$$









### 4) (15 points)

For the following LTI systems, detrmine the **impulse response**.

a) 
$$y(t) = 6x(t) + \int_{-\infty}^{t-1} e^{-(t+\lambda)} x(\lambda+3) d\lambda$$

**b)**  $3\dot{y}(t) - y(t) = 2x(t+1)$ 

For the following LTI systems, detrmine the **step response**.

c) 
$$y(t) = 6x(t) + \int_{-\infty}^{t-1} e^{-\lambda} x(\lambda) d\lambda$$





**5)** (**30 points)** Fill in the following table with a Y (yes) or N (no) for each of the system models given. Assume  $-\infty < t < \infty$  for all of the systems and all initial conditions are zero. <u>You do not need to show any work!</u>

System	System Model	Causal	Memoryless	Linear	Time- Invariant	BIBO Stable	Invertible
1	y(t) = x(1-t)						
2	$y(t) = \cos\left(\frac{1}{1+x(t)}\right)$						
3	y(t) = x(t-1) + x(t-2)						
4	y(t) = tx(t)						
5	$y(t) = \sqrt{x(t)}$						



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