

# ECE-205

## Exam 2

### Fall 2011

**Calculators and computers are not allowed. You must show your work to receive credit.**

**Problem 1 \_\_\_\_\_/22**

**Problem 2 \_\_\_\_\_/20**

**Problem 3 \_\_\_\_\_/15**

**Problems 4 \_\_\_\_\_/18**

**Problem 5 \_\_\_\_\_/25**

**Total \_\_\_\_\_**

1) (22 points) Fill in the non-shaded part of the following table.

	Linear? (Y/N)	Time Invariant? (Y/N)	BIBO Stable? (Y/N)
$y(t) = \cos(t)x(t)$	Y	N	
$\dot{y}(t) + y(t) = e^{-t}x(t)$	Y	N	
$y(t) = x\left(\frac{t}{2}\right)$	Y	N	
$y(t) = \int_{-\infty}^t e^{\lambda}x(\lambda)d\lambda$			N
$y(t) = \int_{-\infty}^t e^{-\lambda}x(\lambda)d\lambda$			N
$y(t) = \cos\left(\frac{1}{x(t)}\right)$			Y
$h(t) = \delta(t)$			Y
$h(t) = u(t)$			N

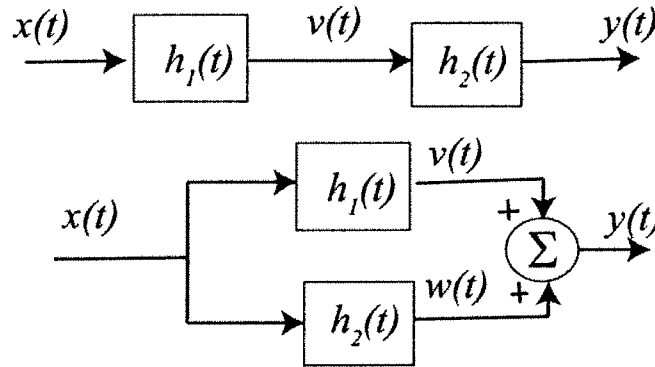
$$y(t) = \int_{-\infty}^t e^{\lambda}x(\lambda)d\lambda \leq \int_{-\infty}^t e^{\lambda}N d\lambda = e^t N \quad \text{not BIBO}$$

$$y(t) = \int_{-\infty}^t e^{-\lambda}x(\lambda)d\lambda \leq \int_{-\infty}^t e^{-\lambda}N d\lambda = -e^{-\lambda} \Big|_{-\infty}^t N \quad \text{not BIBO}$$

2) (20 points) For the following interconnected systems,

i) determine the overall impulse response (the impulse response between input  $x(t)$  and output  $y(t)$ ) and

ii) determine if the system is causal.



a)  $h_1(t) = \delta(t+2), h_2(t) = \delta(t-1)$

b)  $h_1(t) = u(t+1), h_2(t) = u(t-2)$

**Parallel Connections:**

a)  $h(t) = h_1(t) + h_2(t) = \delta(t+2) + \delta(t-1) = h(t)$  not causal

b)  $h(t) = h_1(t) + h_2(t) = u(t+1) + u(t-2) = h(t)$  not causal

**Series Connections:**

a)  $h(t) = h_1(t) * h_2(t) = \int_{-\infty}^{\infty} h_1(\lambda) h_2(t-\lambda) d\lambda = \int_{-\infty}^{\infty} \delta(\lambda+2) \delta(t-\lambda-1) d\lambda = \delta(t+1)$   
 $h(t) = \delta(t+1)$  not causal!

b)  $h(t) = h_1(t) * h_2(t) = \int_{-\infty}^{\infty} h_1(\lambda) h_2(t-\lambda) d\lambda = \int_{-\infty}^{\infty} u(\lambda+1) u(t-\lambda-2) d\lambda = \int_{-1}^{t-2} d\lambda = (t-1)u(t-1)$   
 $h(t) = (t-1)u(t-1)$  causal!

3) (18 Points) Determine the impulse response for the following systems. Don't forget any necessary unit step functions

a)  $y(t) = x(t-1) + x(t+1)$

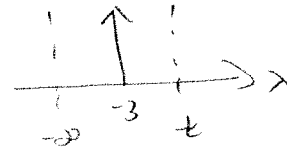
b)  $y(t) = \int_{-\infty}^t e^{-(t-\lambda)} x(\lambda+3) d\lambda$

c)  $2\dot{y}(t) + y(t) = 3x(t)$

a)  $h(t) = \delta(t-1) + \delta(t+1)$

b)  $h(t) = \int_{-\infty}^t e^{-(t-\lambda)} \delta(\lambda+3) d\lambda$

$= e^{-(t+3)} u(t+3) = h(t)$



c)  $2\dot{h}(t) + h(t) = 3\delta(t)$

$\dot{h}(t) + \frac{1}{2}h(t) = \frac{3}{2}\delta(t)$

$\frac{d}{dt} [h(t) e^{t/2}] = e^{t/2} \frac{3}{2}\delta(t) = \frac{3}{2}\delta(t)$

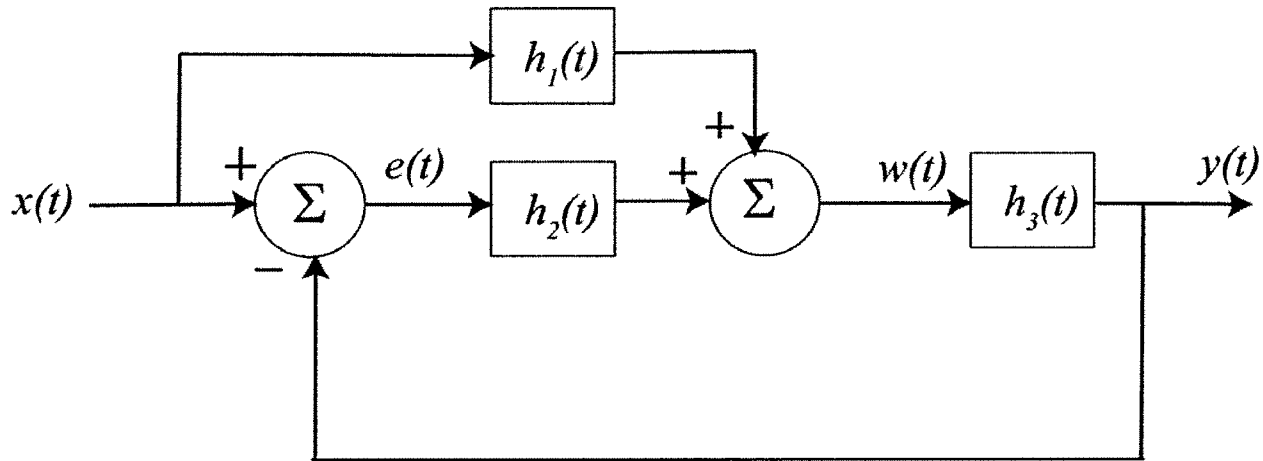
$h(t) e^{t/2} = \int_{-\infty}^t \frac{3}{2}\delta(\lambda) d\lambda = \frac{3}{2}u(t)$

$h(t) = \frac{3}{2}e^{-t/2}u(t)$

4) (15 points) The input-output relationship for the following system can be written as

$$y(t) * A(t) = x(t) * B(t)$$

Determine  $A(t)$  and  $B(t)$



$$e(t) = x(t) - y(t) \quad w(t) = e(t) * h_2(t) + h_1(t) * x(t) \quad y(t) = w(t) * h_3(t)$$

$$y(t) = [e(t) * h_2(t) + h_1(t) * x(t)] * h_3(t)$$

$$= e(t) * h_2(t) * h_3(t) + x(t) * h_1(t) * h_3(t)$$

$$= (x(t) - y(t)) * h_2(t) * h_3(t) + x(t) * h_1(t) * h_3(t)$$

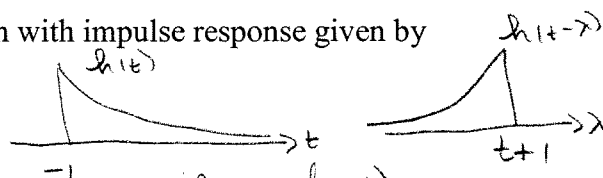
$$= x(t) * h_2(t) * h_3(t) - y(t) * h_2(t) * h_3(t) + x(t) * h_1(t) * h_3(t)$$

$$y(t) + y(t) * h_2(t) * h_3(t) = x(t) * [h_2(t) * h_3(t) + h_1(t) * h_3(t)]$$

$$\underbrace{y(t) * [\delta(t) + h_2(t) * h_3(t)]}_{A(t)} = x(t) * \underbrace{[h_2(t) * h_3(t) + h_1(t) * h_3(t)]}_{B(t)}$$

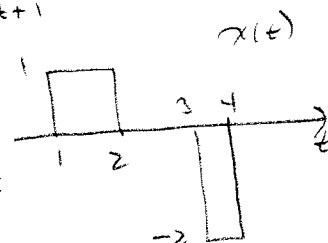
5) (25 points) Consider a linear time invariant system with impulse response given by

$$h(t) = e^{-(t+1)}u(t+1)$$



The input to the system is given by

$$x(t) = [u(t-1) - u(t-2)] - 2[u(t-3) - u(t-4)]$$



Using **graphical evaluation**, determine the output  $y(t)$ . Specifically, you must

- Flip and slide  $h(t)$ , **NOT**  $x(t)$
- Show graphs displaying both  $h(t-\lambda)$  and  $x(\lambda)$  for each region of interest
- Determine the range of  $t$  for which each part of your solution is valid
- Set up any necessary integrals to compute  $y(t)$ . Your integrals must be complete, in that they cannot contain the symbols  $x(\lambda)$  or  $h(t-\lambda)$  but must contain the actual functions.
- Your integrals cannot contain any unit step functions
- **DO NOT EVALUATE THE INTEGRALS!!**

①

$t+1 < 2$     $0 < t < 1$

$$y(t) = \int_{t+1}^{2} e^{-(t-\lambda+1)} (1) d\lambda$$

③

$3 < t+1 < 4$     $2 < t < 3$

$$y(t) = \int_1^2 e^{-(t-\lambda+1)} (1) d\lambda + \int_3^{t+1} e^{-(t-\lambda+1)} (-2) d\lambda$$

②

$2 < t+1 < 3$     $1 < t < 2$

$$y(t) = \int_1^2 e^{-(t-\lambda+1)} (1) d\lambda$$

④

$4 < t+1$     $t > 3$

$$y(t) = \int_1^2 e^{-(t-\lambda+1)} (1) d\lambda + \int_3^4 e^{-(t-\lambda+1)} (-2) d\lambda$$