

$$\mathcal{L}\{\delta(t)\} = 1$$

$$\mathcal{L}\{u(t)\} = \frac{1}{s}$$

$$\mathcal{L}\{tu(t)\} = \frac{1}{s^2}$$

$$\mathcal{L}\left\{\frac{t^{m-1}}{(m-1)!}u(t)\right\} = \frac{1}{s^m}$$

$$\mathcal{L}\{e^{-at}u(t)\} = \frac{1}{s+a}$$

$$\mathcal{L}\{te^{-at}u(t)\} = \frac{1}{(s+a)^2}$$

$$\mathcal{L}\left\{\frac{t^{(m-1)}}{(m-1)!}e^{-at}u(t)\right\} = \frac{1}{(s+a)^m}$$

$$\mathcal{L}\{\cos(\omega_0 t)u(t)\} = \frac{s}{s^2 + \omega_0^2}$$

$$\mathcal{L}\{\sin(\omega_0 t)u(t)\} = \frac{\omega_0}{s^2 + \omega_0^2}$$

$$\mathcal{L}\{e^{-at} \cos(\omega_0 t)u(t)\} = \frac{s + \alpha}{(s + \alpha)^2 + \omega_0^2}$$

$$\mathcal{L}\{e^{-at} \sin(\omega_0 t)u(t)\} = \frac{\omega_0}{(s + \alpha)^2 + \omega_0^2}$$

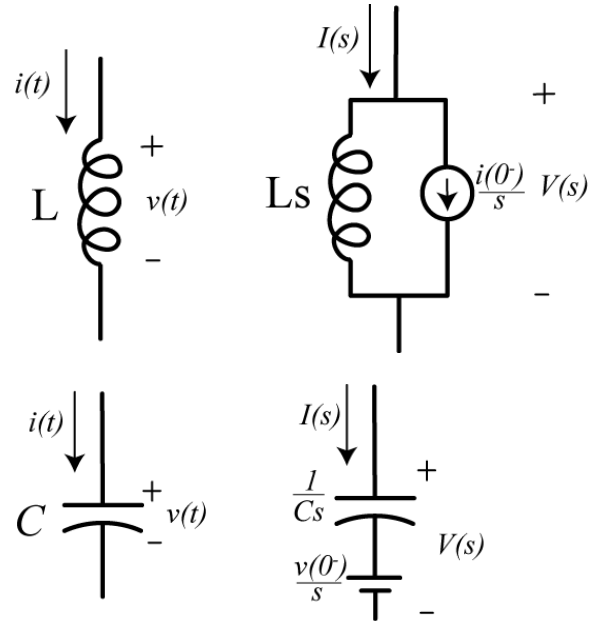
$$\mathcal{L}\left\{\frac{dx(t)}{dt}\right\} = sX(s) - x(0^-)$$

$$\mathcal{L}\left\{\frac{d^2x(t)}{dt^2}\right\} = s^2X(s) - sx(0^-) - \dot{x}(0^-)$$

$$\mathcal{L}\{x(t-a)\} = e^{-as}X(s)$$

$$\mathcal{L}\{e^{-at}x(t)\} = X(s+a)$$

$$\mathcal{L}\left\{x\left(\frac{t}{a}\right), a > 0\right\} = aX(as)$$



Second Order System Properties

$$\text{Percent Overshoot: } P.O. = e^{\frac{-\zeta\pi}{\sqrt{1-\zeta^2}}} \times 100\%$$

$$\text{If } \beta = \frac{PO^{max}}{100} \text{ then } \zeta = \frac{-\ln(\beta)}{\pi \sqrt{1 + \left(\frac{-\ln(\beta)}{\pi}\right)^2}},$$

$$\theta = \cos^{-1}(\zeta) \text{ Time to Peak:}$$

$$T_p = \frac{\pi}{\omega_d}, \quad \omega_d = \omega_n \sqrt{1 - \zeta^2}$$

$$2\% \text{ Settling Time: } T_s = \frac{4}{\zeta\omega_n} = 4\tau$$

Initial Value Theorem: If $x(t) \leftrightarrow X(s)$ $\lim_{t \rightarrow 0^+} x(t) = \lim_{s \rightarrow \infty} sX(s)$

Final Value Theorem: If $x(t) \leftrightarrow X(s)$ $\lim_{t \rightarrow \infty} x(t) = \lim_{s \rightarrow 0} sX(s)$