

ECE-205

Exam 1

Fall 2010

Calculators can only be used for simple calculations. Solving integrals, differential equations, systems of equations, etc. does not count as a simple calculation.

You must show your work to receive credit.

- Problem 1 _____/10
- Problem 2 _____/20
- Problem 3 _____/30
- Problem 4-13 _____/40

Total _____

90-100 7
80-89 10
70-79 4
60-69 2
50-59 4
median = 83

1) (10 points) For a first order system described by the differential equation

$$2\dot{y}(t) + 3ty(t) = x(t-1)$$

with $t_0 = 0$ and $y(t_0) = 1$, use integrating factors to solve the differential equation. Include the initial conditions in your solution.

$$\dot{y}(t) + \frac{3}{2}t y(t) = \frac{1}{2} x(t-1) \quad \frac{d\phi(t)}{dt} = \frac{3}{2}t \quad \phi(t) = \frac{3}{4}t^2$$

$$\frac{d}{dt} \left(y(t) e^{\frac{3}{4}t^2} \right) = \frac{1}{2} x(t-1) e^{\frac{3}{4}t^2}$$

$$y(t) e^{\frac{3}{4}t^2} - y(t_0) e^{\frac{3}{4}t_0^2} = \int_{t_0}^t \frac{1}{2} x(\lambda-1) e^{\frac{3}{4}\lambda^2} d\lambda$$

$$y(t) e^{\frac{3}{4}t^2} - 1 = \int_0^t \frac{1}{2} x(\lambda-1) e^{\frac{3}{4}\lambda^2} d\lambda$$

$$y(t) = e^{-\frac{3}{4}t^2} + e^{-\frac{3}{4}t^2} \int_0^t \frac{1}{2} x(\lambda-1) e^{\frac{3}{4}\lambda^2} d\lambda$$

2) (20 points) Assume we have a first order system with the governing differential equation

$$0.4\dot{y}(t) + y(t) = 3x(t)$$

The system has the initial value of 1, so $y(0) = 1$. The input to this system is

$$x(t) = \begin{cases} 0 & t < 0 \\ -1 & 0 \leq t < 1 \\ 3 & 1 \leq t < 2 \\ -2 & 2 < t \end{cases} \quad \begin{array}{l} \tau = 0.4 \\ K = 3 \end{array}$$

Determine the output of the system in each of the above time intervals. *Simplify your final answer as much as possible and box it. Be sure to include the correct initial value in the first interval!*

$$y(t) = [y(0) - y(\infty)]e^{-t/\tau} + y(\infty)$$

(a) $0 \leq t < 1$ $y(0) = 1$ $y(\infty) = -3$

$$y(t) = [1 - (-3)]e^{-t/0.4} - 3 = \boxed{4e^{-t/0.4} - 3 = y(t)}$$

(b) $1 \leq t < 2$ "y(0)" = $y(1) = 4e^{-1/0.4} - 3 = -2.67166$ $y(\infty) = +9$

$$y(t) = [-2.67166 - (9)]e^{-(t-1)/0.4} + 9 = \boxed{-11.67166e^{-(t-1)/0.4} + 9 = y(t)}$$

(c) $2 \leq t$ "y(0)" = $y(2) = -11.67166e^{-(2-1)/0.4} + 9 = 8.04193$ $y(\infty) = -6$

$$y(t) = [8.04193 - (-6)]e^{-(t-2)/0.4} - 6 = \boxed{14.04193e^{-(t-2)/0.4} - 6 = y(t)}$$

3) (30 points) For the following three differential equations, assume the input is $x(t) = 4u(t)$ (the input is equal to four for time greater than zero), and the initial conditions are $y(0) = \dot{y}(0) = 0$

Determine the solution to each of the following differential equations and put your final answer in a box. Be sure to use the initial conditions to solve for all unknowns. You must show all your work to receive credit.

a) $\ddot{y}(t) + 3\dot{y}(t) + 2y(t) = x(t)$

$$2y_f = 4 \quad \boxed{y_f = 2} \quad r^2 + 3r + 2 = 0 \quad (r+1)(r+2) = 0$$

$$y(t) = c_1 e^{-t} + c_2 e^{-2t} + 2$$

$$y(0) = 0 = c_1 + c_2 + 2 \quad \left. \begin{array}{l} \text{adding} \rightarrow -c_2 + 2 = 0 \\ \end{array} \right\}$$

$$\dot{y}(t) = -c_1 e^{-t} - 2c_2 e^{-2t}$$

$$\dot{y}(0) = 0 = -c_1 - 2c_2 \quad \left. \begin{array}{l} \end{array} \right\} \quad \boxed{c_2 = 2} \quad \boxed{c_1 = -4}$$

$$\boxed{y(t) = -4e^{-t} + 2e^{-2t} + 2}$$

b) $\ddot{y}(t) + 4\dot{y}(t) + 4y(t) = 8x(t)$

$$4y_f = 8 \cdot 4 \quad y_f = 8 \quad r^2 + 4r + 4 = 0 \quad (r+2)(r+2) = 0$$

$$y(t) = c_1 e^{-2t} + c_2 t e^{-2t} + 8$$

$$y(0) = 0 = c_1 + 8 \quad \boxed{c_1 = -8}$$

$$\dot{y}(t) = -2c_1 e^{-2t} + c_2 e^{-2t} - 2c_2 t e^{-2t}$$

$$\dot{y}(0) = 0 = -2c_1 + c_2$$

$$c_2 = 2c_1 = \boxed{-16 = c_2}$$

$$\boxed{y(t) = -8e^{-2t} - 16te^{-2t} + 8}$$

c) $\ddot{y}(t) + 4\dot{y}(t) + 16y(t) = 4x(t)$

$$16y_f = 4 \cdot 4 \quad y_f = 1$$

$$r^2 + 4r + 16 = 0$$

$$r = \frac{-4 \pm \sqrt{16 - 64}}{2} = -2 \pm j\sqrt{12}$$

$$y(t) = 1 + c e^{-2t} \sin(\sqrt{12}t + \theta)$$

$$\dot{y}(t) = -2c e^{-2t} \sin(\sqrt{12}t + \theta) + c e^{-2t} \sqrt{12} \cos(\sqrt{12}t + \theta)$$

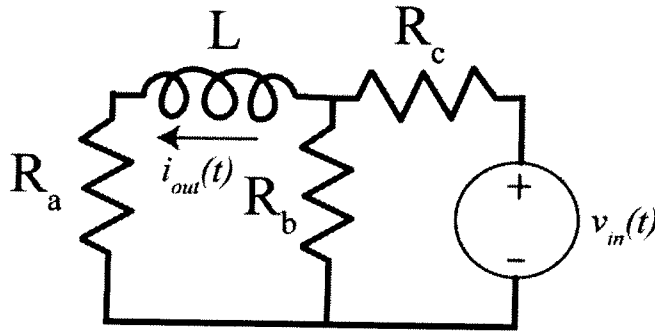
$$\dot{y}(0) = 0 = -2 \sin(\theta) + \sqrt{12} \cos(\theta) \quad \tan(\theta) = \frac{\sqrt{12}}{2} \quad \boxed{\theta = 60^\circ}$$

$$y(0) = 0 = 1 + c \sin(\theta) \quad c = \frac{-1}{\sin(\theta)} = -1.15470$$

$$\boxed{y(t) = 1 - 1.15470 e^{-2t} \sin(\sqrt{12}t + 60^\circ)}$$

Problems 4-13, 4 points each, no partial credit (40 points)

Problems 4 and 5 refer to the following circuit



4) The Thevenin resistance seen from the ports of the inductor is

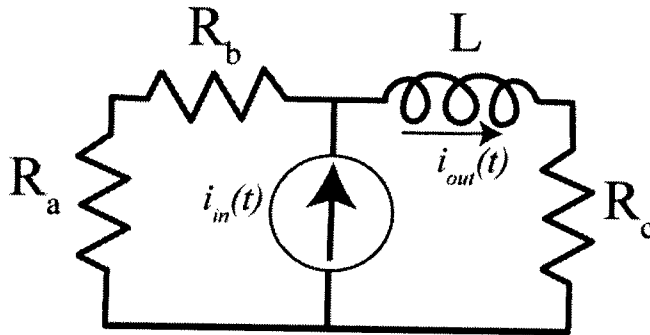
- a) $R_{th} = R_a + R_b \parallel R_c$ b) $R_{th} = R_c + R_a \parallel R_b$ c) $R_{th} = R_a + R_b$ d) $R_{th} = R_a + R_c$ e) none of these

5) The static gain for the system is

- a) $K = 1$ b) $K = \frac{R_b}{R_a + R_b}$ c) $K = \frac{R_a}{R_a + R_b}$ d) $K = \frac{R_b}{R_c + R_b}$ e) none of these

$$i_{out} = \frac{v_{in}}{R_c + R_a \parallel R_b} \cdot \frac{R_b}{R_a + R_b}$$

Problems 6 and 7 refer to the following circuit



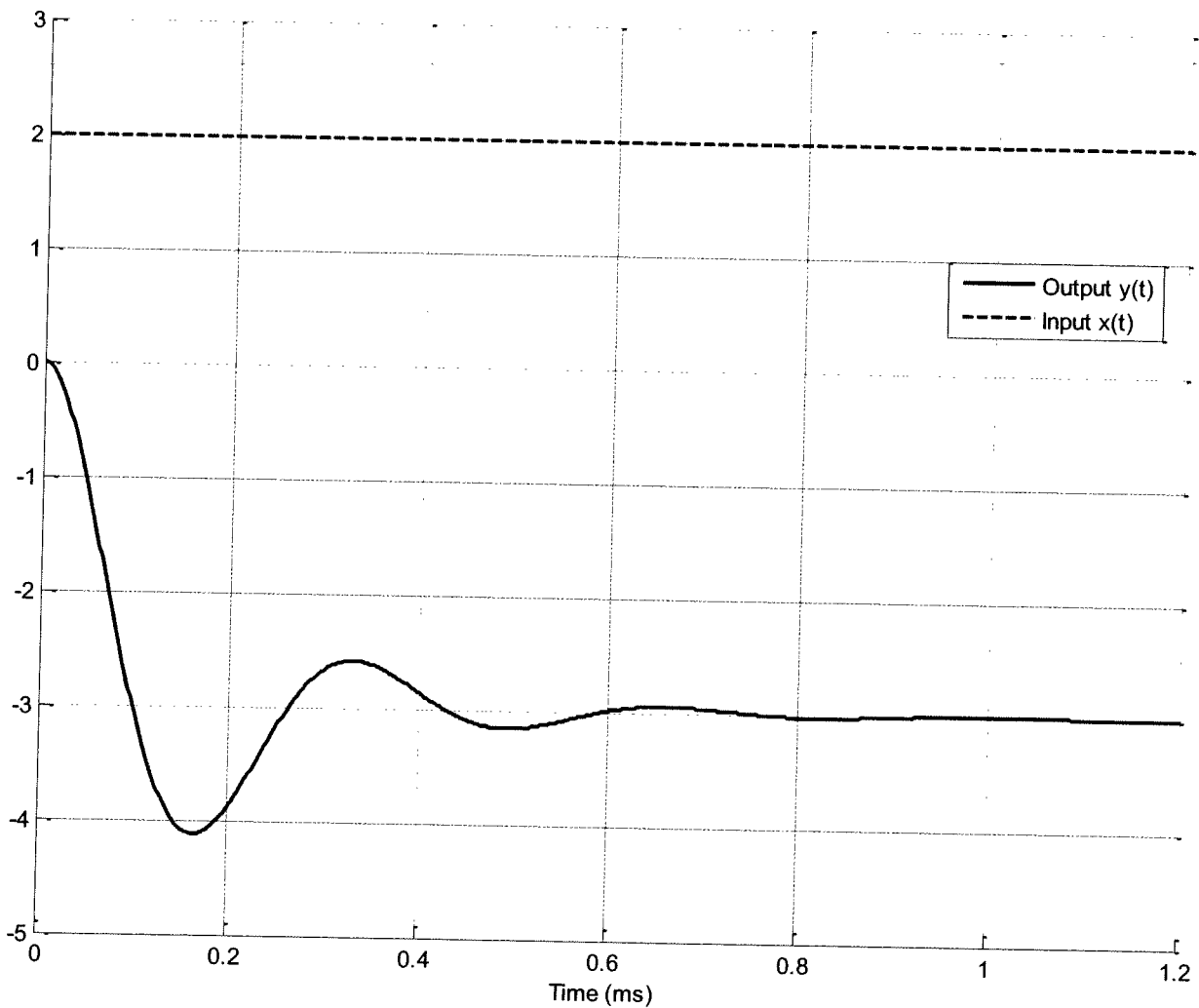
6) The Thevenin resistance seen from the ports of the inductor is

- a) $R_{th} = R_c \parallel (R_a + R_b)$ b) $R_{th} = R_c$ c) $R_{th} = R_a + R_b$ d) $R_{th} = R_a + R_b + R_c$ e) none of these

7) The static gain for the system is

- a) $K = 1$ b) $K = \frac{R_a + R_b}{R_a + R_b + R_c}$ c) $K = \frac{R_c}{R_a + R_b + R_c}$ d) $K = \frac{R_c}{R_a + R_b}$ e) none of these

Problems 8-10 refer the following graph showing the response of a second order system to a step input.



8) The percent overshoot for this system is best estimated as

- a) 400% b) -400% c) 300% d) -300% e) -33% **f) 33%**

$$\frac{-4 - (-3)}{-3} = \frac{-1}{-3} = 33\%$$

9) The (2%) settling time for this system is best estimated as

- a) 0.3 ms **b) 0.6 ms** c) 1.0 ms d) 1.2 ms

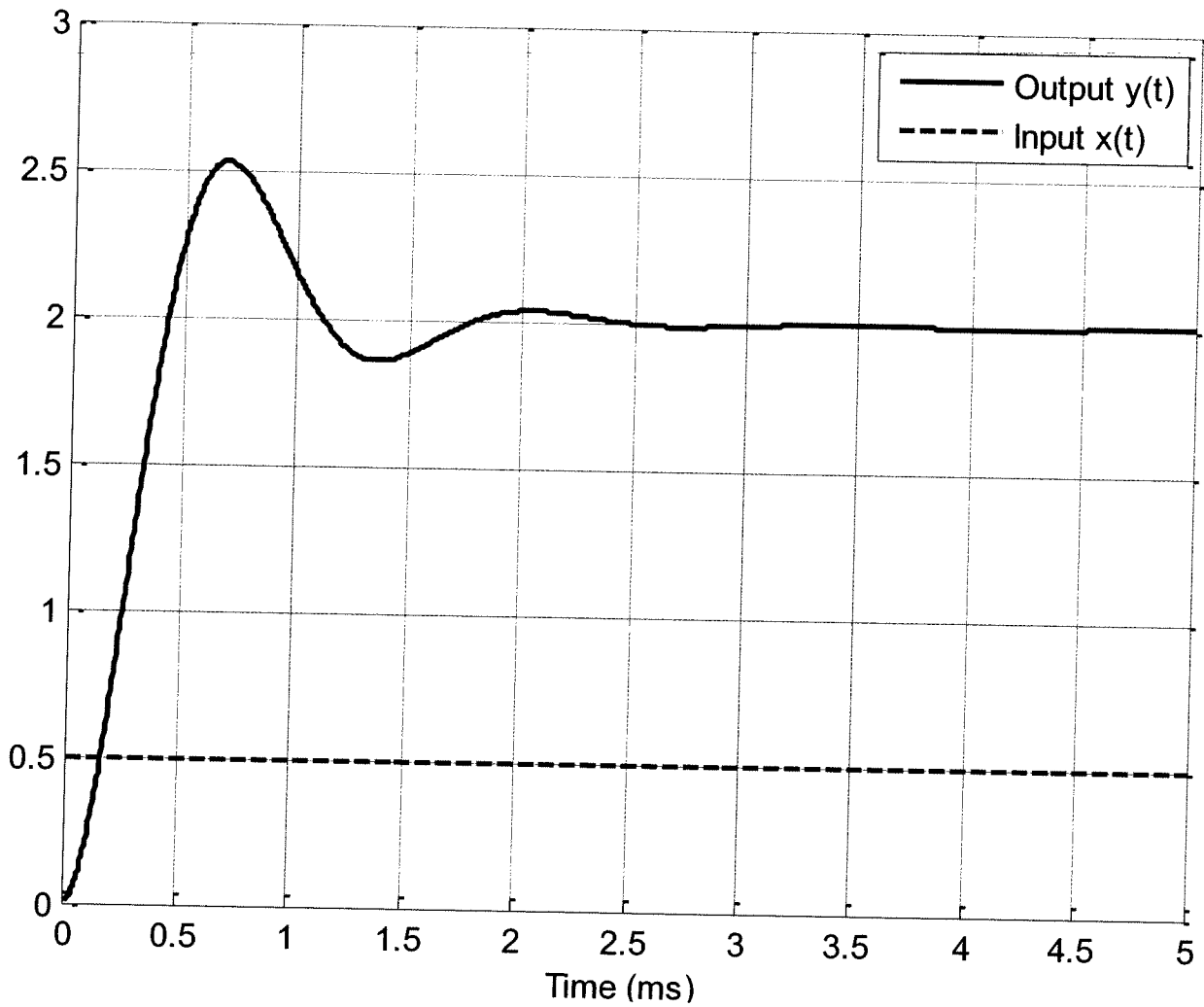
10) The static gain for this system is best estimated as

- a) 1.5 b) 3 **c) -1.5** d) -3

$$K_2 = -3$$

$$K = \frac{-3}{2}$$

Problems 11-13 refer the following graph showing the response of a second order system to a step input.



11) The percent overshoot for this system is best estimated as

- a) 400% b) 250% c) 200% d) 150% e) 100% **f) 25%** $\frac{2.5 - 2}{2} = \frac{0.5}{2} = 25\%$

12) The (2%) settling time for this system is best estimated as

- a) 1.5 ms **b) 2.5 ms** c) 4 ms d) 5 ms

13) The static gain for this system is best estimated as

- a) 1 b) 2 c) 3 **d) 4**

$$K(10s) = 2$$

$$K = \frac{2}{0.5} = 4$$