

# 7 Digital Modulation

## 7.1 Introduction

Once the system designer is faced with the transmission of digital data, the choice of modulation format becomes the primary consideration. This choice is not, however, merely an academic exercise. There are myriad implications for spectrum and spectral efficiency, implementation complexity, power efficiency, and flexibility that the designer must consider. In most cases, the system engineer works within the constraints of the link budgets, cost and complexity, spectrum regulations, and packaging concerns to select the proper modulation format.

This chapter presents the various forms of digital modulation in common use. Special emphasis is placed on visualized the time waveforms and PSDs for each of the formats so that performance can be understood. The chapter ends with a discussion of the various performance measures used to compare and select modulation formats.

## 7.2 Digital Modulation Principles

Digital modulation schemes differ significantly from analog schemes, primarily in the goal of the communication system. In analog systems, the message waveform is to be preserved through demodulation. In digital systems, only the information is to be preserved; preservation of the message waveform is not a design goal. So choosing a digital modulation format is not about choosing a waveform that will be preserved in transmission and reception, but rather a waveform which will optimally preserve the information in transmission and reception.

At the same time, the choice of a modulation format for digital transmission will be influenced by the ability to maximize data throughput in a limited transmission bandwidth. This ability is measured by a figure of merit called the spectral efficiency of the modulation format and will be discussed later in the chapter.

Digital modulation formats are classified as binary or multilevel signaling formats. The simplest formats are called binary signaling formats. Binary digital modulations formats not simply subsets of multilevel formats, but are rather formats used exclusively as binary formats. These are analog modulation formats (amplitude, phase, frequency or quadrature modulation) with baseband binary linecode messages having rectangular bit symbol pulses. These modulation formats can possess rather wide transmission bandwidths. One way to reduce the transmission bandwidth is to reduce the message bandwidth. Changing the bit symbol pulse shape can achieve this goal, and this process applied to digital signaling is known as pulse shaping.

The second class of digital modulation format is called multilevel signaling formats. In these formats, the message waveforms are linecodes with symbols representing multiple bits. The insertion of an algorithm assigning multiple bits to symbols before the

modulation stage is the distinguishing feature of this type of signaling. This type of format allows for increased throughput through a bandlimited channel. Pulse shaping is also applied frequently for multilevel digital modulation.

### 7.2.1 Digital Carrier Modulation Architecture

A typical digital transmitter and receiver design was shown in Chapter 6. In these discussions, we deal with coherent demodulation architectures only, although many of the conversation points apply directly to incoherent receiver structures as well.

The waveform consisting of a line code representation of data bits is the input to the modulator in the transmitter. In fact, this process is an analog modulation process. But since the information transmitted is representative of digital bits, we call it *digital modulation*. While the operation is identical to what has been discussed before, the formats and results are a bit different.

Whereas analog modulation schemes have been traditionally termed “modulation”, digital modulation schemes, otherwise identical in operation, are term “keying”, denoting the on-off nature of the modulation. (This term traces back to telegraphy.) Thus, DSB-SC with an analog message is called amplitude modulation, while the same DSB-SC transmission with a digital message is called “on-off keying”.

Frequency upconversion, amplification, and filtering follow the modulation step, and the signal is transmitted. From the signal design perspective, we are concerned mostly with data rate capacity and transmission bandwidth for the transmitted signal. Of course, in transmission, the digitally modulated carrier is just an analog signal, subject to the same constraints and ill effects as any other signal.

In the receiver, the signal is first amplified and downconverted in the RF front end. The received signal is characterized by typical signal parameters such as its SNR and distortion measures. However, reconstructing either the transmitted waveform or the line code is not the goal of the digital receiver. The carrier modulation format and original line code input to the modulator are typically used and discarded as the signal is processed through the IF stage and demodulator. The final stage of the receiver/demodulator includes a decision function which must output a line code representation of bits – where each bit estimate is made based upon the waveform received during the corresponding bit interval. Ultimately, a baseband detection problem remains at the end of the signal processing chain.

### 7.2.2 Binary Digital Modulation

Binary digital modulation schemes arise by applying a binary “digital” waveform as input to an analog modulator. These modulation formats have proven quite effective as a means of transmitting digitized information in noisy environments where analog formats would fail.

The following modulation formats are associated with binary modulation of a carrier. That is, during the symbol period, the carrier waveform takes on one of two possible

configurations, corresponding to a logical “1” or “0”. It will be important to define notation throughout the following discussion. The input bitstream of digital information is clocked at a data rate DR bits per second (bps). The bit interval, or the time duration corresponding to one bit, is denoted  $T_b$  seconds. In the transmitted waveform, the symbols are transmitted at a rate SR symbols per second (sps), and the symbol interval is  $T_s$  seconds. For binary modulation, the bit rate and symbol rate are identical. The transmission bandwidth is  $B_T$  Hertz.

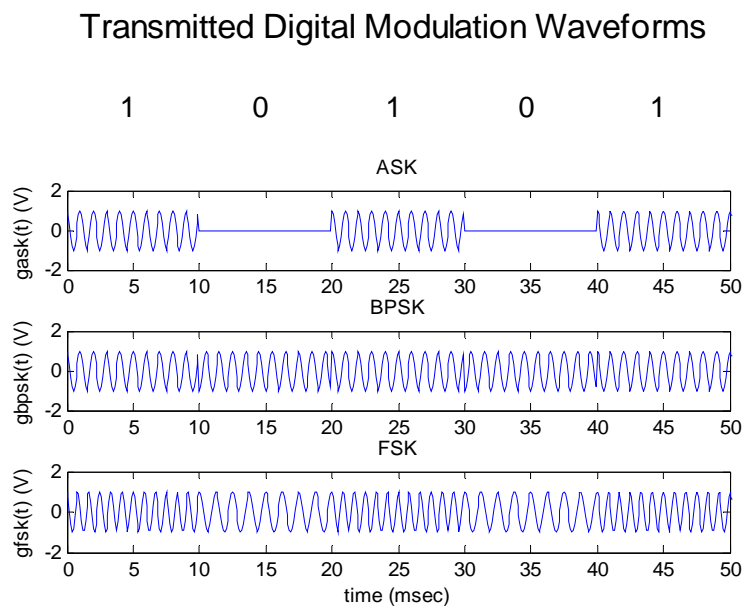
### 7.2.2.1 Binary Modulation Waveforms and Spectra

Just as was discussed for amplitude modulation, we can imagine a “digital” message waveform modifying (modulating) a carrier. The same possible carrier modifications are available:

$$g(t) = A(t) \cos \{ 2\pi [ f_c + \Delta f(t) ] t + \theta(t) \}. \quad (7-1)$$

The line code waveform could modify the carrier amplitude, frequency deviation, or phase. For binary digital message signals, the message waveforms have the characteristics of being nearly discrete-valued and discontinuous. This has great impact on the transmitted signal spectrum and receiver performance. Once these characteristics are understood, the system designer can choose the optimum signal waveform for a given application.

The various modulation formats are displayed as time domain waveforms in Figure 1. In each case, we assume a 100 bps random data input sequence modulating a 1 kHz cosine carrier. The analytic results follow the discussion in Couch [1].



**Figure 1 Examples of simple binary digital modulation formats.**

The simplest form of digital carrier modulation is *Amplitude-Shift-Keying* (ASK), the digital version of DSB-SC. When message is a unipolar line code, the message shifts the carrier amplitude between some positive value and zero (or on and off). In this case the signaling is called *On-Off Keying* (OOK). This was used first for Morse code transmission and thus precedes analog message transmission. The OOK waveform is shown as the first waveform in Figure 1. This waveform is particularly easy to detect by first passing the received signal through a bandpass filter centered at the carrier frequency and then passing that output through an envelope detector. The output thus produced is a linecode ready for baseband detection. The chief disadvantage of this format is that amplitude modulation produces a wide transmission bandwidth, as will be demonstrated shortly. The model for an ASK/OOK waveform is

$$g_{ASK}(t) = Am(t)\cos(\omega_c t), \quad (7-2)$$

where  $m(t)$  is the unipolar linecode message waveform.

Another binary modulation format is *Binary Phase-Shift Keying* (BPSK), which can be thought of as phase modulation with the input waveform being a unipolar linecode waveform. The carrier phase is typically shifted from  $0^\circ$  to  $180^\circ$ . This is demonstrated in the second waveform of Figure 1. In this waveform, there is a phase discontinuity at the linecode discontinuities (bit transitions). BPSK can also be modeled as ASK (DSB-SC) with a polar linecode message. Using this model, both OOK and BPSK may be viewed as holding the frequency and phase of the carrier constant while the amplitude is shifted.

In *Frequency Shift Keying* (FSK), the carrier amplitude is held constant, and the frequency is shifted between two frequencies according to the input message. Normally, the input message is a unipolar line code. The amount of frequency shift away from the unmodulated carrier frequency is called the frequency deviation. There are two types of FSK, discontinuous-phase FSK and continuous-phase FSK. In discontinuous-phase FSK, the carrier frequency is directly shifted from one frequency to another according to the binary data (via  $\Delta f$ ). This technique is normally not used, due to the amplitude fluctuations that accompany the modulation.

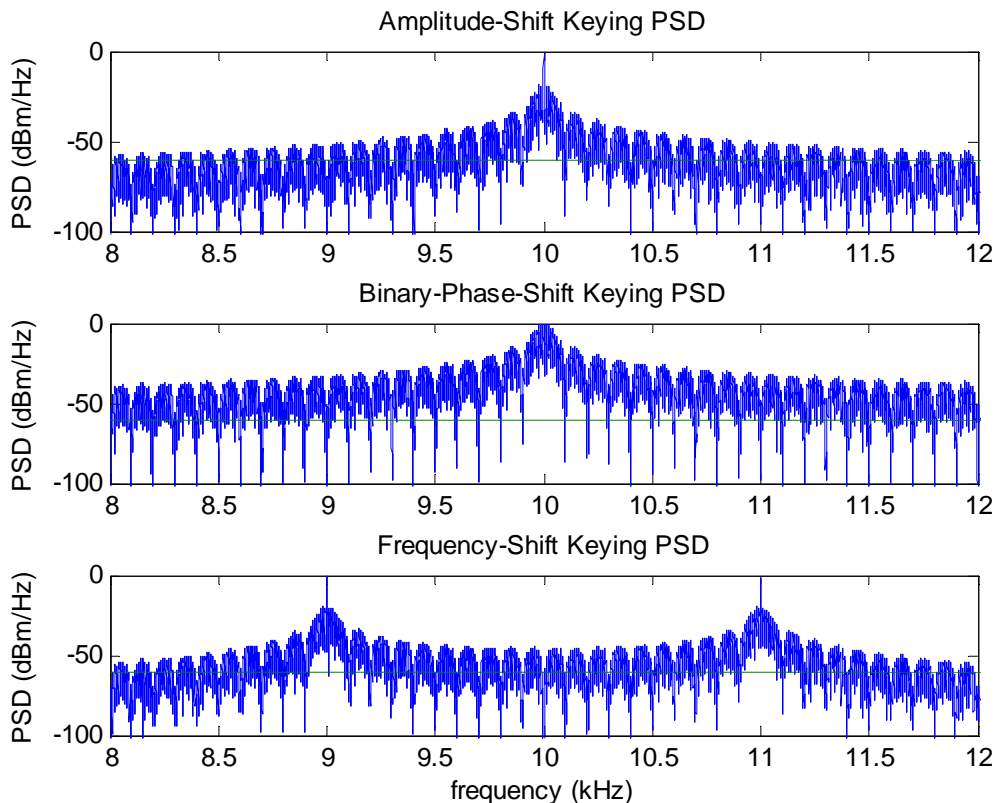
The continuous-phase FSK technique is shown in the third waveform of Figure 1. Note that the phase of the waveform is continuous as the name suggests. Also note the constant-envelope nature of the waveform. In this modulation format, the message is set equal to an instantaneous frequency deviation, which is integrated to produce the carrier instantaneous phase. The model for continuous-phase FSK is

$$g_{CP-FSK}(t) = A\cos\left[\omega_c t + 2\pi\int k_f m(\alpha) d\alpha\right]. \quad (7-3)$$

The term  $k_f$  is called the *peak frequency deviation* and determines the shift in frequency when keying. A term often used to describe the frequency deviation for digital modulation systems is the digital modulation index  $h$ , given by

$$h = \frac{2 \cdot k_f}{DR} . \quad (7-4)$$

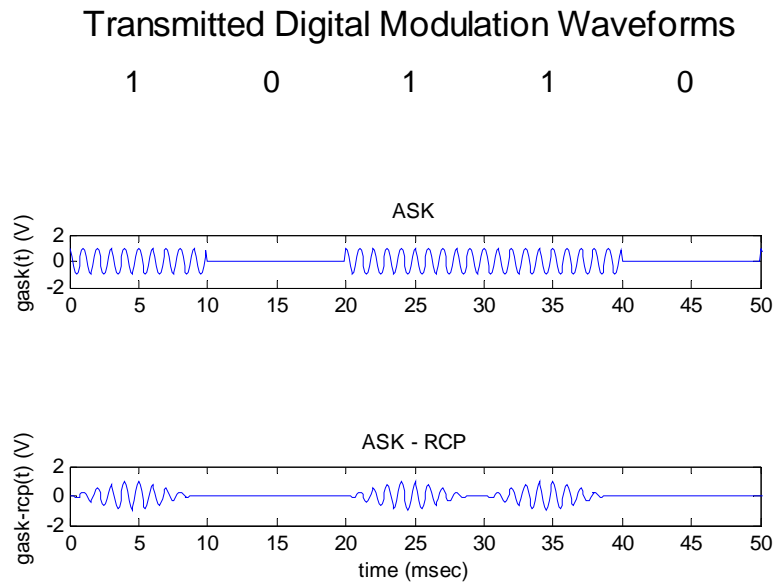
One of our interests in evaluating these modulation formats is to examine their spectra, and to determine the transmission bandwidth required to send data. The transmitted signal power spectral density (PSD) for each of these formats is shown in Figure 2. In each case, narrowband modulation is simulated with a bit/symbol period of 10 msec (DR=100 bps) and a carrier frequency of 10 kHz.



**Figure 2 Power Spectral Density of the three basic binary digital modulation formats: ASK, BPSK, and FSK.**

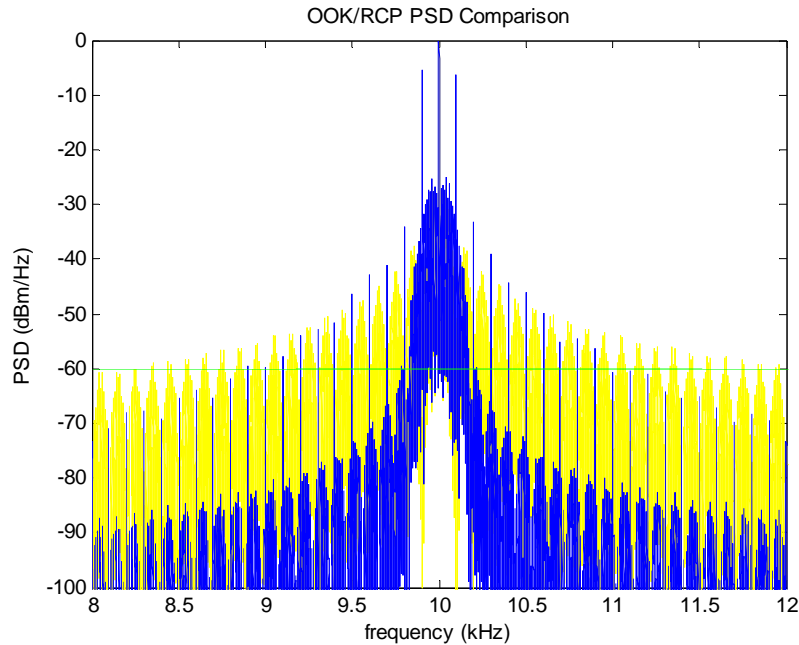
The PSD for OOK is the conventional DSB spectrum for a rectangular pulse-type random message. BPSK however, has much broader sidelobe content due to its nonlinear modulation mechanism (reminiscent of FM). While its mainlobe (90% power) bandwidth is similar to OOK, the sidelobe content is much more appreciable for BPSK. Of course, the form of the spectrum of FSK is dependent upon the value of frequency deviation selected. The example shown here is for a peak frequency deviation of 1 kHz. In this case, FSK can be viewed as ASK on two separate frequencies. Notice that the carrier frequency is not actually occupied with signal energy in FSK.

The pulse-shaping technique is often applied to the OOK format to reduce the signal bandwidth, specifically the sidelobe content. An example waveform is illustrated in Figure 3, where a raised-cosine pulse shape is applied to the baseband linecode data prior to modulation. The raised-cosine pulse shape provides advantage in both ISI management and bandwidth limitation. This produces a shaped-pulse symbol and the shaping is retained in the transmitted modulated carrier.



**Figure 3 Example of ASK modulation using Raised-Cosine-Pulse-shaped baseband pulses for ISI management and bandwidth reduction.**

The impact to transmission bandwidth is evident in the power spectral density comparison of Figure 4. While the pulse shaping did not greatly reduce the mainlobe bandwidth, the sidelobe content is greatly reduced, thus reducing the amount of interference to adjacent signals (an effect called adjacent channel interference).



**Figure 4** Transmission spectra for OOK and OOK with raised cosine pulse shaping. Note the dramatic reduction in sideband content resulting from the pulse shaping.

## 7.2.3 Multilevel Digital Modulation

More advanced digital modulation schemes are available when the designer wishes to greatly increase the data throughput of the system given a fixed bandwidth. This is especially appropriate for wireless systems, where the demand for throughput increases continuously, but the transmission bandwidth allocations increase only sporadically. In the following, a class of multilevel digital signaling is introduced. That is to say that each baseband symbol represents  $2^m$  bits of information, where  $m$  is an integer greater than 2. Often, these forms of signaling are called  $m$ -ary signaling to emphasize this fact. The representation of multiple bits per symbol is performed pre-modulation, and typically quadrature modulation is used to further increase the efficiency of the transmission.

### 7.2.3.1 QPSK and its Relatives

One important multilevel technique involves the use of binary signaling combined with quadrature multiplexing, which results in the class of digital modulation called Quadrature-Phase-Shift-Keying (QPSK). Each of these important modulation techniques are based on the same modulation architecture, but have important implementation and performance details.

The two message signals are polar NRZ linecode digital waveforms input to an IQ modulator. Typically, the two waveforms are derived from a single serial bit stream using a demultiplexer as shown in Figure 5. The demultiplexer clock frequency is set to the data rate of the message waveform, such that bits of the message are sent alternatively to the I and Q input ports.

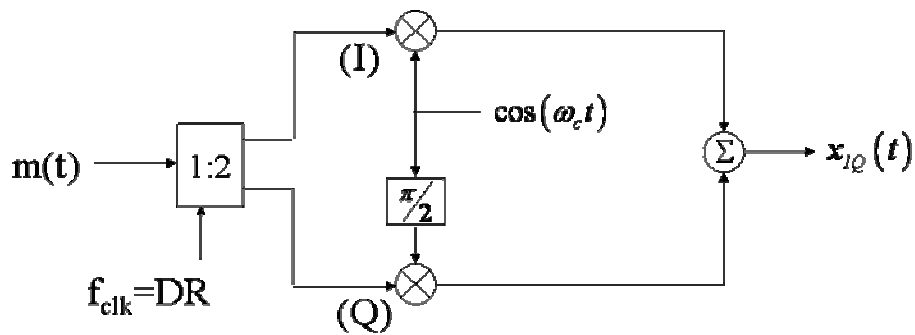


Figure 5 QPSK modulator showing single bitstream feed.

In standard QPSK, a symbol is formed when a symbol derived from the I channel modulates the amplitude of cosine component of the carrier, and simultaneously a symbol derived from the Q channel modulates the sine component. The baseband symbol waveform in this case is a standard polar NRZ rectangular pulse waveform. Note that the symbol rate for QPSK is one-half the input serial bitstream bit rate due to the action of the demux.

In Offset QPSK (OQPSK), a delay of  $\frac{1}{2}$  of a symbol period (or 1 bit period) is introduced on the Q input to the quadrature modulator. This format is also known as staggered QPSK. This provides an advantage in reducing the residual amplitude modulation on the transmitted signal. [1] (This results because the I and Q data cannot change simultaneously)

Further reduction of amplitude fluctuations is possible through the use of  $\pi/4$ -shifted QPSK modulation. In this technique, the signaling is performed by alternatively choosing symbols from the QPSK and OQPSK signal sets. While this seems complicated, it is actually implemented via an algorithm assigning the input bit stream to symbols according to a predefined pattern.

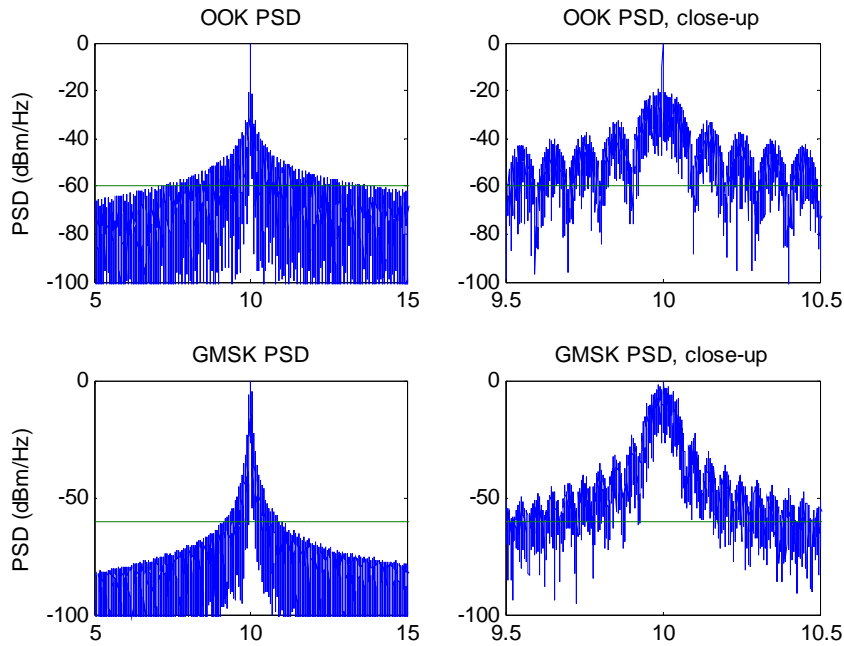
### 7.2.3.2 Minimum Shift Keying

Another modulation format for improved spectral performance is minimum shift keying (MSK), which modifies the concept of FSK in such a way to improve spectral efficiency and noise performance [2]. MSK can be an m-ary modulation format, but for this discussion, we will focus on binary MSK.

As indicated above, phase and frequency shift keying can result in rather wide bandwidth transmission signals. MSK offers reduced PSD sidelobe content, and thus reduced transmission bandwidth and interference with adjacent signal channels. One way to view MSK signaling is that it is binary continuous-phase FSK where the digital modulation index  $h$  is chosen to be the minimum required for the two symbols to remain orthogonal for optimum detection. This situation corresponds to a peak frequency deviation  $k_f$  equal to  $\frac{1}{4}$  of the input bit rate DR.



A comparison of the spectral performance of OOK and MSK is given in Figure 6. It is noted that sidelobe content is greatly reduced for the MSK format relative to OOK, which makes MSK so attractive.



**Figure 6 Comparison of ASK and MSK spectrum for 100 bps bit rate, 10 kHz carrier frequency. A closeup view of the PSDs is shown on the right.**

Of course, there is a price to pay, and that is in the receiver. The difficulty in distinguishing between the small difference in frequency between the two symbols makes the receiver design challenging. However, the engineering has been solved well enough that variations of this modulation method are now extremely popular.

MSK can be modeled as OQPSK where the rectangular symbol pulses have been replaced by half-cycle sinusoidal pulses during the bit interval [1]:

$$g_{msk}(t) = x(t)\cos(\omega_c t) - y(t)\sin(\omega_c t)$$

$$x(t) = A \cos\left(\pm 1 \frac{\pi t}{2T_b}\right), \quad y(t) = A \sin\left(\pm 1 \frac{\pi t}{2T_b}\right). \quad (7-5)$$

MSK is a constant-envelope format whose frequency-shifting process may also be conveniently expressed as a phase-shifting process [2]. The MSK signal can be modeled as a carrier whose phase term increases or decreases linearly each bit interval:

$$g_{MSK}(t) = A \cos(2\pi f_c t + \theta(t))$$

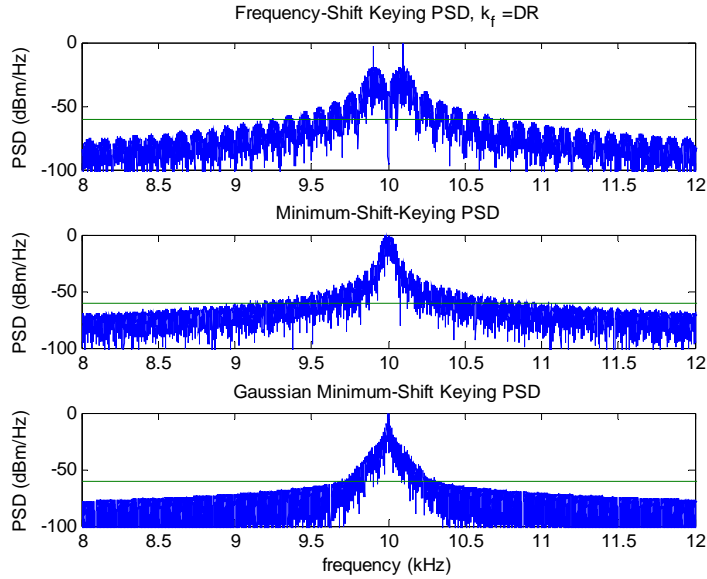
$$\theta(t) = \theta(0) + \frac{\pi h}{T_b} t \quad (7-6)$$

Here, the term  $h$  is called the deviation ratio. MSK corresponds to the case of  $h = 1/2$ . This model leads to the concept of monitoring the potential phase path vs time, which is called a *phase trellis*.

*Gaussian Minimum Shift Keying* (GMSK) prefilters the polar NRZ data with a Gaussian-shaped frequency response prior to MSK modulation. The interesting thing about the Gaussian filter is that both its impulse response and its frequency response are Gaussian-shaped. The objective is to further reduce the sidelobe energy content through narrow bandwidth frequency response and low overshoot impulse response filtering.

While the PSD for GMSK is complicated to analyze, this technique can further reduce PSD sidelobe content. However, since the pulse shape is Gaussian, which is infinite in extent in the time domain, there is a problem with intersymbol interference (ISI). Thus, there is a tradeoff in GMSK between spectral compactness and ISI-based BER performance. This tradeoff is normally expressed through the time-bandwidth product  $WT$ , where  $W$  denotes the bandwidth of the baseband Gaussian shaping filter and  $T$  denotes the bit duration. Small values of  $WT$  lead to large amounts of ISI. Large values of  $WT$  correspond to signaling which approaches conventional MSK. A good compromise value is  $WT=0.3$  which minimizes adjacent channel interference problems as well as managing ISI [2].

A comparison of the PSDs for FSK, MSK and GMSK is given in Figure 7. Note that MSK does indeed reduce the transmission bandwidth relative to FSK to a minimum. GMSK further reduces sidelobe content making it the preferred choice for ACI considerations.



**Figure 7 Comparison of several frequency-shift-keying modulation format spectra, showing decreased bandwidth.**

Actually, a modified form of signaling called Gaussian FSK is more often used, for which the receiver design is easier. GFSK is used widely for portable wireless, in applications ranging from GSM cellular telephones to the Bluetooth wireless standard. GSM signaling uses a value of  $WT = 0.3$  while Bluetooth signaling uses a value of  $WT=0.5$ .

## 7.2.4 Signal Constellation Modeling

It is sometimes difficult to visualize these waveforms, but an alternate means of visualizing the signaling is available. These signal constellations provide the information necessary to understand both how the signals are produced and how the modulation scheme will perform in terms of BER.

Consider the QPSK waveforms based on rectangular pulse linecodes. In each of these modulation formats, we can regard the transmitted signal as a narrowband signal as modeled previously:

$$\begin{aligned}
 g_{QPSK}(t) &= x_I(t) \cos(\omega_c t) - x_Q(t) \sin(\omega_c t) \\
 &= \text{Re} \left\{ A(t) e^{j\theta(t)} e^{j\omega_c t} \right\}
 \end{aligned} \tag{7-7}$$

The messages  $x_I$  and  $x_Q$  are the polar linecode waveforms representing the data. The last line of this definition recalls the definition of phasors in circuits. We can define a “signal phasor” for a narrowband transmitted signal, corresponding to a slowly varying function modulating the carrier. Then, suppressing the carrier frequency term, we work with just this slowly-varying function just as working with phasors in circuits. Recall that  $x_I$  is the

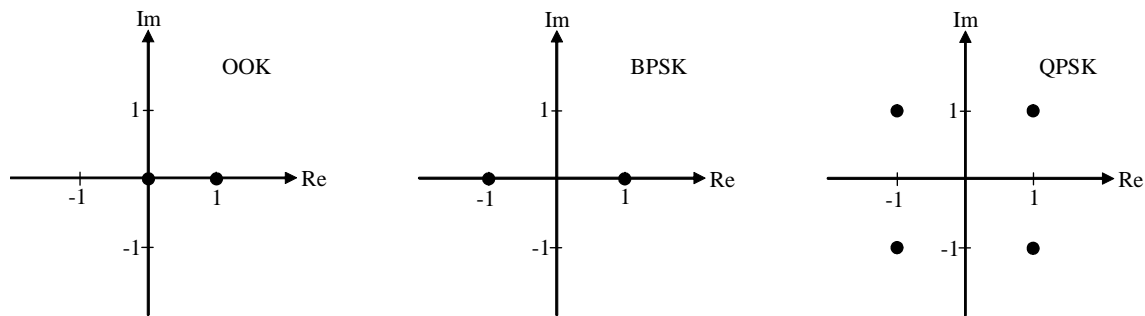
in-phase component, and  $x_Q$  is the quadrature component. Define the complex envelope of the signal  $g_{\text{QPSK}}(t)$  as

$$\tilde{g}(t) = g_I(t) + jg_Q(t) = A(t)e^{j\theta(t)}. \quad (7-8)$$

Thus, the complex envelope of the carrier has a real part  $g_I(t)$  and an imaginary part  $g_Q(t)$ . For the case of QPSK modulation,  $g_I$  and  $g_Q$  are both polar linecodes with rectangular pulses having some amplitude  $A$  during the symbol period.

A signal constellation displays all possible values of the complex envelope phasor. The signal constellations of OOK, BPSK, and QPSK are shown in Figure 8. For the case of OOK, only the cosine carrier component is used, and the  $g_I$  component takes on only the values 0 and 1. BPSK also involves the modulation only of the cosine component, but the message values are +1 and -1, which give the phase shift.

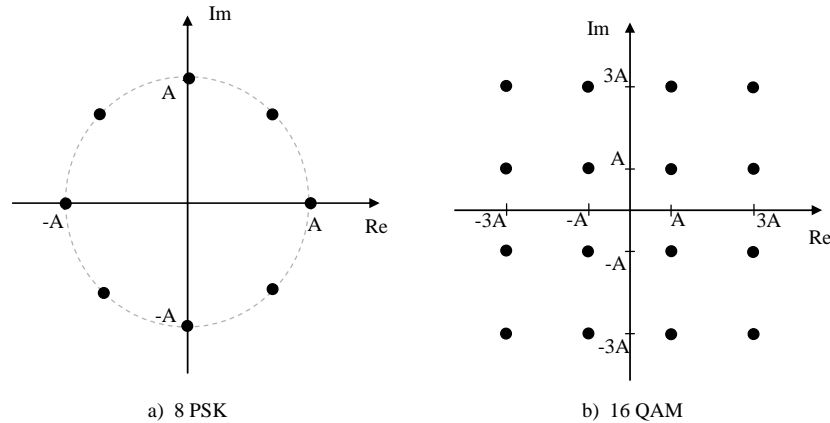
In QPSK, both the cosine and sine carrier components are modulated, and thus the entire complex plane of the signal constellation must be used to represent the carrier envelope. Both the  $g_I$  and  $g_Q$  components are polar linecodes, so the 4 possible values for the complex envelope are:  $(\text{Re}, \text{Im}) = \{ (1,1), (1,-1), (-1,1), (-1,-1) \}$ , as indicated in the constellation. Of course, an algorithm associating bit pairing  $(b_0, b_1)$  with points in the constellation must be specified, as this is not unique.



**Figure 8 Signal constellations for common digital modulation formats.**

In general, there are two major classes of multilevel digital signaling, grouped by properties of the complex envelope and the form of the signal constellation produced. In Phase-Shift-Keying (PSK), the key differentiator is that the complex envelope has a constant magnitude – the data is encoded in the phase of the carrier only. This results in the signal constellation consisting of points lying on a circle. Note that the BPSK and QPSK signal constellations of Figure 8 fit this description.

An example, 8-PSK, is shown in Figure 9a. The signal points are chosen to be equidistant in phase about the circle to optimize the detection problem.



**Figure 9** Example of signal constellations for a) MPSK for  $M=8$ , and b)  $M$ -symbol QAM for  $M=16$ .

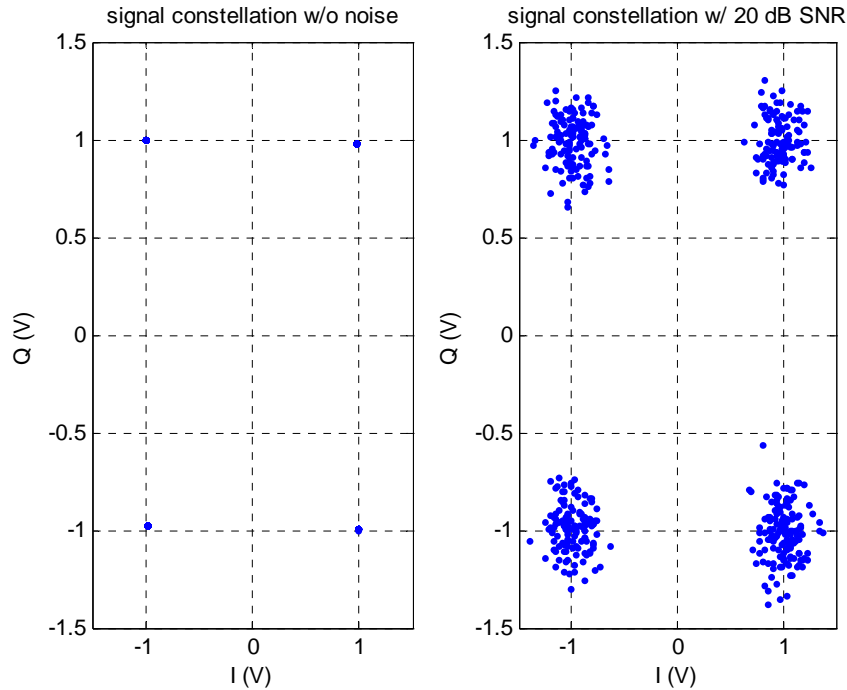
Ultimately, the detection capability is an SNR problem. In the PSK case, the problem is one of phase discrimination. In some cases, however, simple amplitude discrimination can be performed to achieve detection.

In Quadrature Amplitude Modulation (QAM), the data is encoded in both the amplitude and phase of the complex envelope of the carrier. An example, 16-QAM, is shown in Figure 9b. For 16-QAM, four bits are encoded into each symbol. Specifically, two bits are encoded into a symbol pulse modulating the cosine component, and two bits are encoded into a symbol pulse modulating the sine component of the carrier.

Note that these  $m$ -ary signals are transmitted at a single carrier frequency, and have a double-sided bandwidth equal to the twice the baseband message bandwidth entering the modulation operation (that is, the symbol waveform modulating the carrier components). By combining multilevel signaling, pulse shaping, and IQ modulation, very efficient use of transmission bandwidth is achieved relative to the simple DSB-SC format.

The power spectral density for PSK or QAM signaling follows a standard  $\text{sinc}^2$  shape for the case of rectangular symbol pulses. If the number of points in the signal constellation is  $M=2^q$ , then the null-to-null transmission bandwidth of PSK or QAM signal is  $2 \cdot DR/q$ , where  $DR$  is the input bit rate. Note that the use of multilevel signaling thus explicitly reduces the transmission bandwidth as expected.

Of course, noise impacts the performance of digital systems just as it does analog systems – through reducing the SNR. From the discussion of pulse detection, we learned that the SNR is reduced to the ratio of the signal distance squared to noise variance. In Figure 10 the impact of noise is displayed via the signal constellation. In this example, the noise is added at the input to the receiver filter, and the noise is at a 20 dB CNR (carrier to noise ratio, that is the modulated carrier power to noise power ratio is a factor of 100).



**Figure 10 Signal constellation showing QPSK result with 20 dB CNR noise added.**

The signal constellation allows the analyst to quickly gauge the severity of the noise and its impact to BER. The signal constellation gives a relative measure of signal distance and noise variance visually presented. Small signal distance would be demonstrated as having the points of the constellation being placed close to one another in the absence of noise. Large noise variance is demonstrated by a wide variance of the points splattered around the expected value of the constellation point. These two values together reveal both SNR and BER information. Communication test equipment often has the ability to derive signal constellation diagrams built in to its software for quick examination of performance.

### **7.3 Choice of signaling format in system implementation**

This chapter has presented many forms of digital modulation and several means of analyzing them. How does the system engineer go about choosing a modulation format, or understanding how a choice was made? First, it must be stressed that the decision is made based on inputs from the link design team based on requirements flowed down from the communication system engineers above. Second, only by considering many issues, most notably spectrum, data transmission quality, and throughput, can the choice be best understood. This section presents several of the major comparison categories by which the modulation formats are judged.

#### **7.3.1 Performance comparison of digital modulation formats**

There are even more digital modulation formats available beyond those discussed above. As new systems are designed, most often the signaling is inherited from some existed

predecessor. There are normally very good reasons why the incumbent format has been chosen, and this chapter has attempted to point out some of those reasons. A summary of some of the applications which have been associated with the various formats introduced in this chapter is given in Figure 11.

<b>Format</b>	<b>Sample Applications</b>
OOK	IR remote control devices
BPSK	Satellite telemetry, Dialup Computer Modems
FSK	Bluetooth (GFSK), Wireless networks (802.11, GFSK), cdmaOne cellular (BFSK), paging systems (BFSK, 4-FSK)
QPSK	cdmaOne cellular, Satellite television Digital Video Broadcast (DVB), Dialup Computer Modems
OQPSK	cdma2000 cellular
p/4 QPSK	ANSI/TIA/EIA-136 cellular
M-PSK	GPRS/GSM cellular 3G evolution (M=8)
M-QAM	Digital cable television (M=16/64/128/256)
M-FSK	Cordless telephones, DSL modem (OFDM)
GMSK	GSM cellular

Figure 11 Examples of applications using the various digital modulation formats discussed.

However, at times a new modulation choice is warranted, and at that point it is important to be able to compare the various modulation choices available and suggest alternatives. To do this, there needs to be objective means to compare the performance of the various formats.

The performance measures we will be most interested in concern spectrum, data transmission quality and throughput. The first measure will be BER performance as a function of SNR or received power, which will have direct impact to the link budget. The second performance measure will be transmission spectrum. The third performance measure of interest will be a measure of data throughput per unit transmission bandwidth called the spectral efficiency. A final performance measure has to do with a practical implementation issue of amplifier nonlinearity.

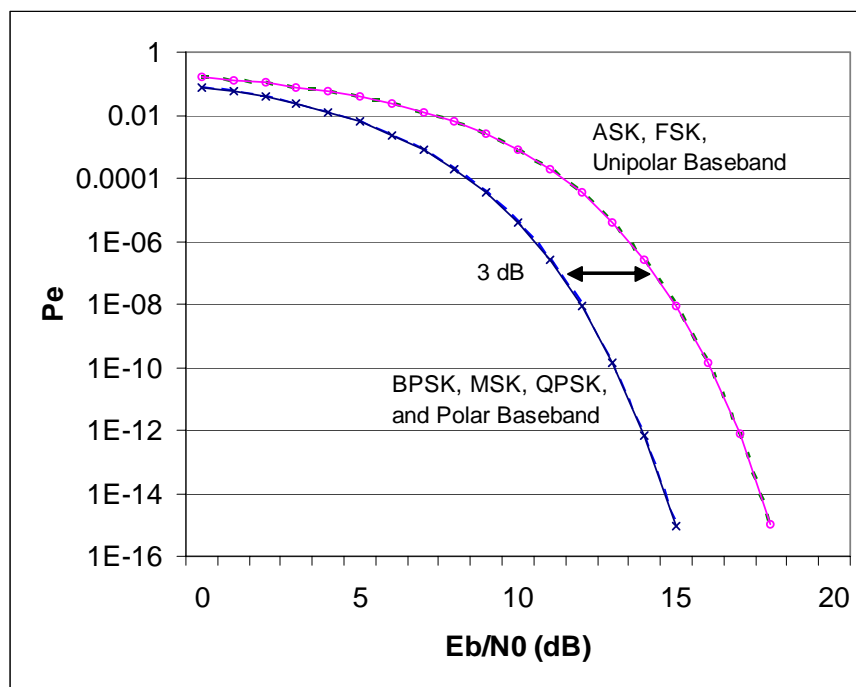
### 7.3.1.1 Bit Error Rate Performance

One of the metrics used to judge the quality of the link design is the bit error rate of transmission. Primarily, the BER is designed through choice of signaling and link budget power allocation by the link analyst under direction of the system engineer. Study of baseband pulse transmission and detection in the previous chapter led to several important conclusions regarding digital links. The error probability could be related to decision stage input SNR, or, more conveniently,  $E_b/N_0$ . The form of the  $P_e$  curve was

that of a “waterfall”, with error probability falling sharply with increasing SNR. Noise, intersymbol interference and implementation loss in the receiver all reduce performance from the ideal curve practical implementations.

Similar conclusions hold for bandpass, symbol-based digital communication links. For bandpass modulation formats, the analysis of BER performance is most easily understood by changing the matched filter followed by a decision and sampling circuit to a correlator followed by the same decision and sampling circuit. This circuit can then operate either at baseband or for bandpass signaling. In either the baseband or the bandpass case, there is to be a decision made as to whether the signal is greater or less than a threshold, which leads to the  $E_b/N_0$  factor.

Binary modulation formats are easily compared with baseband polar signaling, from which their signaling is normally derived. Figure 12 shows such a comparison between common baseband and coherent bandpass signaling formats. (Non-coherent receiver performances suffer a slight performance degradation versus coherent, but the receivers are easier and cheaper to implement.)



**Figure 12 BER performance curve for binary modulation formats relative to baseband polar signaling.**

Formats such as MSK and QPSK show advantage in that the receiver requires less power to achieve a given SNR. This required power to achieve a desired  $P_e$  (BER) is called the *receiver sensitivity*. For example, for a desired  $P_e$  of  $10^{-8}$ , QPSK requires a theoretical  $E_b/N_0$  of about 12 dB. (Of course, this value needs to be translated to a power at a given data rate to be useful to designers.)



**Example:** QPSK BER calculation

**Example:** Translate Eb/N0 to received power

### 7.3.1.2 Power Spectral Density and Bandwidth

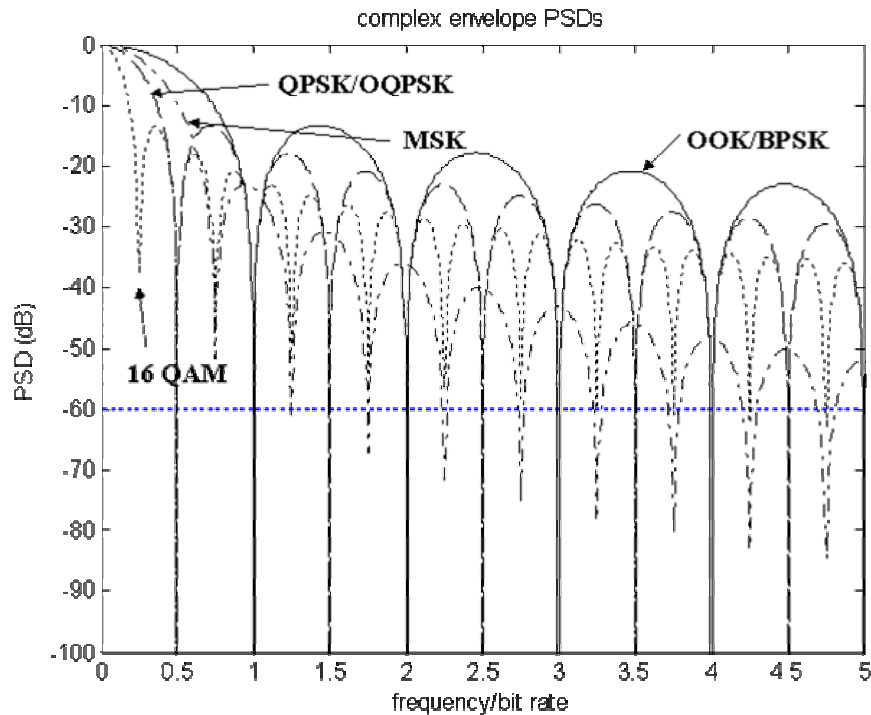
One of the primary concerns to the digital communication system designer is bandwidth, and bandwidth has a meaning with several nuances. First, by bandwidth is meant the allowed (allocated) bandwidth given for your system to transmit its information. Your task, as system engineer, is to transmit information through that limited frequency band. Second, bandwidth describes the range of frequencies necessary to transmit the information carrying modulated carrier. Different baseband linecodes, pulse shapes, and modulation formats all produce transmitted signals having different signal bandwidths. Finally, you must be a good citizen in the world of frequency allocation, and not interfere with your frequency (channel) neighbors. Therefore, there is a bandwidth beyond which your signal energy may not appreciably interfere with adjacent channels. In order to understand these definitions, and to design the systems, the system engineer must be comfortable with the power spectral densities of the various signaling formats described above.

Analytic expressions for the complex envelope PSDs for various forms of digital modulation are given in Figure 13 [1]. In each case, the input bit stream consists of a data rate of DR=1/T<sub>b</sub> bits per second (bps). For quadrature schemes, the serial data stream is demultiplexed into parallel I and Q bitstreams at half rate. The symbols are rectangular unless otherwise noted. Note that while the formats have comparable main-lobe bandwidths, the -60 dB bandwidths, which offer a description of ACI impact, are dramatically different.

Signaling Format	Complex Envelope PSD	Null-Null Transmission Bandwidth, B <sub>T</sub>	-60 dB Null-Null Bandwidth (approximate)
OOK/BPSK	$P_g(f) = K \text{sinc}^2(fT_b)$	2*DR	20*DR
QPSK/OQPSK	$P_g(f) = K \text{sinc}^2(2fT_b)$	DR	10*DR
MPSK/MQAM (M=2 <sup>q</sup> )	$P_g(f) = K \text{sinc}^2(qT_b f)$	2/q*DR	20/q*DR
MSK	$P_g(f) = K \frac{\cos^2(2\pi T_b f)}{(1 - (4T_b f)^2)^2}$	1.5*DR	3.0*DR

**Figure 13 Comparison of bandwidths of several modulation formats.**

For comparison, each of the corresponding PSDs are plotted in Figure 14 as a function of frequency scaled by data rate. For each of these PSDs, rectangular symbol pulses are used. Keep in mind that some formats are binary, others are m-ary, and so the transmission bandwidth may be reduced due to multiple-bit per symbol substitution.



**Figure 14 Comparison of complex envelope Power Spectral Densities of several modulation formats.**

There are a number of important features to note from these plots. First, note the  $\text{sinc}^2$  shape of the spectra, which results from the rectangular symbol pulse shape. Second, the “transmission bandwidth” is twice the complex baseband first null bandwidth in typical use. Minimizing bandwidth for a given data rate throughput is often an objective for system design. The only way to reduce this “main lobe” bandwidth is to change the pulse shape.

Finally, sidelobe content has much to do with adjacent channel interference, and so those formats which have greatly reduced sidelobe power content are preferred. A reference line drawn at a level 60 dB down from the peak power level is provided to emphasize this point. If adjacent channels require greater than 60 dB isolation, then the PSD must be at least this far down by the edge of the allocated frequency band for the adjacent channels. It is apparent why MSK and GMSK are so popular in terms of small ACI. Even though MSK has a larger null-null bandwidth than QPSK, its ACI performance is much better. It is noted that while GMSK can greatly reduce the bandwidth concerns, ISI-induced BER impact must be avoided.

Raised cosine filtering of the baseband input streams to the I and Q inputs to the quadrature multiplexer can reduce the bandwidth of the transmission while controlling ISI. The bandwidth of a M-ary (QAM or PSK) signal using RCP pulses with rolloff  $\alpha$  is found to be

$$B_T = (1 + \alpha) \frac{DR}{q}. \quad (7-9)$$

Actually, depending upon the severity of the bandwidth limitation and ACI constraints, QPSK and its variants prove to be quite capable in many circumstances. However, as data throughput requirements rise, the bandwidth control issue becomes dominant.

### 7.3.1.3 Spectral Efficiency

The prime reality of modern communication system design is fixed and limited channel bandwidth. Between legislated allocations, interference concerns, and practical implementation details, all communication links operate within a limited bandwidth. As demand for services increase, system engineers must solve the problem of sending more data through that fixed and limited bandwidth.

The spectral efficiency of a transmission format is defined as the link data rate divided by the transmission bandwidth.

$$\eta = \frac{DR}{B_T}. \quad (7-10)$$

By link data rate is meant the actual rate of bit transmission across the link, including link overhead, as opposed to the information data rate, which describes the rate of data passed through the link.

To correctly compare spectral efficiencies of different modulation formats, a definition of transmission bandwidth must be agreed upon. For example, the bandwidth could be defined as the 90% power bandwidth occupied by the signal. For rectangular pulse signals, this corresponds to the null-to-null bandwidth of the power spectral density.

**Example:** Compare the spectral efficiency of OOK with that of QPSK.

A throughput data rate of DR is assumed. The baseband signal is a polar NRZ line code representation of digital data. This message has a baseband bandwidth of DR, or, if using a DSB-SC carrier modulation scheme, a transmission bandwidth of 2DR, assuming the message signal bandwidth is equal to the first null of the PSD. Thus, for OOK, the throughput is DR, and the bandwidth is 2DR. The spectral efficiency for OOK is

$$\eta_{ASK} = \frac{DR}{B_T} = \frac{DR}{2 \cdot DR} = \frac{1}{2}.$$

Now, consider QPSK using the quadrature multiplexer of Figure 5. The action of the demux halves the rate actually transmitted into the I and Q channels. Thus, the symbol rate is DR/2.

This results in the transmission of a DSB-SC carrier modulated signal with bandwidth  $DR$ . Using the quadrature multiplexer, we have achieved a transmission bandwidth reduction factor of 2 while maintaining the same throughput! The bit rate being transmitted is  $DR$  bps. Using the QPSK scheme, the spectral efficiency is increased to

$$\eta_{QPSK} = \frac{DR}{B_T} = \frac{DR}{DR} = 1.$$

We would say that QPSK has twice the spectral efficiency of ASK. Of course, as the spectral efficiency increases, the difficulty in demodulating and detecting the signal increases, and not linearly!

In general, using  $M$ -ary signaling with rectangular pulse shaping, the spectral efficiency would be expected to scale as the  $\log_2 M$ . Specifically,

$$\eta_{M\text{-ary}} = \frac{DR}{2 \cdot DR/q} = \frac{q}{2}. \quad (7-11)$$

The spectral efficiency calculation should be examined carefully, and the same means of determining signal bandwidth applied to every situation evaluated. These efficiencies can be increased even further using pulse shaping techniques, such as implementing raised-cosine pulses.

#### 7.3.1.4 Power Amplifier Nonlinearity Impacts

All amplifiers are linear only within a range of input signal amplitudes. The range of input signal powers over which the amplifier is considered linear is described by the amplifier dynamic range. There are various types of amplifier designs, based in part upon their power efficiency and linearity. For example, Class C amplifiers, which offer good efficiency for portable wireless products, have issues with nonlinearity not found with other amplifier types.

The best signal design for use with Class C amplifiers is one which has a constant envelope (amplitude), which omits several of the basic modulation schemes discussed. We have found, for example, that the rectangular pulse QPSK family and MSK are constant envelope modulation formats, and so should operate well with power efficient Class C amplifiers in the handset transmitter. However, we also found that pulse shaping was desirable to reduce the sidelobe content for these signals. Pulse shaping introduces amplitude fluctuations in the envelope of the signal, although not as severe as rectangular pulse shaping.

This indicates an engineering tradeoff facing the system engineer. In practice, it is possible to simulate the effect of the amplifier nonlinearity on the transmitted spectrum. It is important to remember that the trade is at the system level, however, and system complexity/cost must also be considered. GMSK proves to be the superior signaling format, while OQPSK is slightly superior to the other QPSK formats [2].

**Example:** Simulate GMSK, OQPSK, OOK through simple nonlinearity

## 7.4 Summary

This chapter has presented many of the popular digital modulation formats available for modern link design. It turns out that many types of links today are built upon the versatile quadrature multiplexer/demultiplexer architecture, which supports the non-FSK digital modulation formats. The FSK formats are popular, especially teamed with Gaussian pulse shaping and incoherent receivers.

The system engineer is able to understand the behavior of the modulation formats in the time and frequency domains by studying their models and typical implementations. Often, these formats are simulated in model links to predict the actual performance according to the metrics described here and others that may be of interest.

## 7.5 References

1. Couch, L.W., Digital and Analog Communication Systems, 6<sup>th</sup> ed., 2001, Prentice-Hall.
2. Haykin, S. and Moher, M., Modern Wireless Communications, Pearson Prentice-Hall, 2005.