CSSE463: Image Recognition Day 9

- Lab 3 due Weds, 11:59pm
- Take home quiz will be assigned tomorrow and due Friday, 4:00 pm.
 - Mostly written problems too long for in-class quizzes

Today: region properties

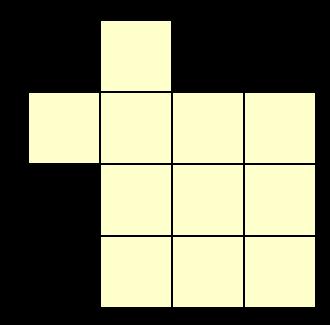
• Questions?

Representing a Region

- Review: Connected components labels groups of connected pixels.
 - 4-connectivity vs. 8-connectivity matters
 - Could you write a recursive algorithm for connected components?

Region properties

- Includes location, size, shape, and orientation
- Focus on binary images



Region Properties Area and Centroid

• Area: sum of pixels in region $A = \sum_{(r,c) \in R} 1$

• Centroid: (avg row, avg column) = (\bar{r}, \bar{c})

$$\bar{r} = \frac{1}{A} \sum_{(r,c) \in R} r \qquad \bar{c} = \frac{1}{A} \sum_{(r,c) \in R} c$$

- Recall that find returns row and column coordinates if you ask it to do so:
 - [r,c] = find(mask == 1)

Bounding box

- Can be used to describe a region's location
- For region to right, $(r_{min}, r_{max}, c_{min}, c_{max})$ = (1,4,4,7)

Matlab returns
 (x_{min}, y_{min}, width, height)

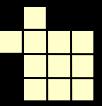
What types of shapes have maximal/minimal extent?

Perimeter

- Perimeter (assume no holes)
 - The set of interior border pixels

$$P_8(R) = \{(r,c) \in R \mid N_4(r,c) - R \neq \emptyset\}$$

- Interpretation, please?
- In Matlab P₈(region) is called bwperim(region, 4) because the border pixels are connected with the background using a 4-neighborhood.
 - The output is a mask
- The definition for P₄ is dual to P₈.



Perimeter length

- Assume we have an algorithm to list the perimeter pixels in a chain of neighboring pixels...
 - Matlab's bwtraceboundary
 - On an upcoming written assignment, you'll study the "Inner boundary tracing" algorithm (from text)
 - 1. Extremely efficient representation for large regions
- ...to find perimeter length, denoted PL or |P|:
 - Each pair of horizontal/vert. neighbors contributes 1
 - Each pair of diagonal neighbors contributes sqrt(2)
 - Which is typically longer, |P₈| or |P₄| ?

Circularity measures

$$C_1 = \frac{|P|^2}{A}$$

$$C_2 = \frac{\mu_R}{\sigma_R}$$
, where

$$\mu_{R} = \frac{1}{N} \sum_{i=1}^{N} \| (r_{i}, c_{i}) - (\bar{r}, \bar{c}) \|$$

$$\sigma_{R} = \left(\frac{1}{N} \sum_{i=1}^{N} \|(r_{i}, c_{i}) - (\bar{r}, \bar{c})\| - \mu_{R}\right)^{\frac{2}{2}}$$

N = # of pixels on perimeter

| Euclidean length of vector

 μ_R = mean distance of boundary pixel from center

 μ_R = standard deviation of distances from center

- Circles (theoretically) have minimum ratio
 - Why?
- Having a small standard deviation gives a larger circularity.
 - What's a circle's variation?
 - Sample radial representations of images